

GIT COMPACTIFICATIONS OF $M_{0,n}$ AND FLIPS

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ABSTRACT. We use geometric invariant theory (GIT) to construct a large class of compactifications of the moduli space $M_{0,n}$. These compactifications include many previously known examples, as well as many new ones. As a consequence of our GIT approach, we exhibit explicit flips and divisorial contractions between these spaces.

1. INTRODUCTION

The moduli spaces of curves $M_{g,n}$ and their Deligne-Mumford compactifications $\overline{M}_{g,n}$ are among the most ubiquitous and important objects in algebraic geometry. However, many questions about them remain wide open, including ones that Mumford asked several decades ago concerning various cones of divisors [Mum77, Har87]. While exploring this topic for $\overline{M}_{0,n}$, Hu and Keel showed that for a sufficiently nice space—a so-called Mori dream space—understanding these cones and their role in birational geometry is intimately related to variations of geometric invariant theory (GIT) quotients [Tha96, DH98, HK00]. Although it remains unsettled whether $\overline{M}_{0,n}$ is a Mori dream space for $n \geq 7$, the underlying philosophy is applicable nonetheless. In this paper we explore the birational geometry of $\overline{M}_{0,n}$ and illustrate that VGIT plays a significant role.

Theorem 1.1. *For each $d \geq 1$, there is a family of birational models of $\overline{M}_{0,n}$ obtained as GIT quotients parameterizing n -pointed rational normal curves in \mathbb{P}^d and their degenerations. These models include $\overline{M}_{0,n}$, all the Hassett spaces $\overline{M}_{0,\vec{\epsilon}}$, all the previously constructed GIT models, and many new compactifications as well.*

1.1. The setup. The Chow variety of degree d curves in \mathbb{P}^d has an irreducible component parameterizing rational normal curves and their limit cycles. Denote this by $\text{Chow}(1, d, \mathbb{P}^d)$ and consider the locus

$$U_{d,n} := \{(X, p_1, \dots, p_n) \in \text{Chow}(1, d, \mathbb{P}^d) \times (\mathbb{P}^d)^n \mid p_i \in X \forall i\}.$$

There is a natural action of $\text{SL}(d+1)$ on $U_{d,n}$, and the main objects of study in this paper are the GIT quotients $U_{d,n} // \text{SL}(d+1)$. These depend on a linearization $L \in \mathbb{Q}_{>0}^{n+1}$ which can be thought of as assigning a rational weight to the curve and each of its marked points.

A preliminary stability analysis reveals that every singular semistable curve is a union of rational normal curves of smaller degree meeting at singularities that are locally a union of coordinate axes (Corollary 2.4). By considering a certain class of one-parameter subgroups, we derive bounds on the weight of marked points allowed to lie at these singularities and in various linear subspaces (see §2.3). Moreover, we show in Proposition 2.10 that a rational normal curve with distinct marked points is stable for an appropriate range of linearizations, so there is a convex cone with cross-section $\Delta^\circ \subset \mathbb{Q}^{n+1}$ parameterizing GIT quotients that are compactifications of $M_{0,n}$ (cf. §2.5). These are related to the Deligne-Mumford-Knudsen compactification as follows:

Theorem 1.2. *For any $d \geq 1$ and any linearization $L \in \Delta^\circ$, there is a regular birational morphism $\phi : \overline{M}_{0,n} \rightarrow U_{d,n} //_L \mathrm{SL}(d+1)$.*

Our technique for proving this is to take an appropriate $\mathrm{SL}(d+1)$ -quotient of the Kontsevich space $\overline{M}_{0,n}(\mathbb{P}^d, d)$ so that every DM-stable curve maps, in a functorial manner, to a GIT-stable curve in \mathbb{P}^d .

1.2. Chambers, walls, and flips. For each fixed d , the space of linearizations Δ° admits a finite wall and chamber decomposition by the general results of VGIT [DH98, Tha96]. This imparts the birational models we obtain with a rich set of interrelations. For instance, the quotients corresponding to open chambers map to the quotients corresponding to adjacent walls, and whenever a wall is crossed there is an induced rational map which is frequently a flip. We undertake a careful analysis of this framework in the context of $U_{d,n}$ and provide a modular description of the maps that arise.

There are two types of walls in the closure of Δ° : interior walls corresponding to changes in stability conditions between open chambers, and exterior walls corresponding to semi-ample linearizations or linearizations with empty stable locus.

Our main results concerning the VGIT of $U_{d,n}$ are the following:

- *we list all of the GIT walls;*
- *we classify the strictly semistable curves corresponding to a wall between two chambers and determine the ones with closed orbit;*
- *we provide necessary and sufficient conditions for the map induced by crossing an interior wall to be i) a divisorial contraction, ii) a flip, or iii) to contract a curve;*
- *we describe the morphism corresponding to each exterior wall.*

Precise statements are provided in §5 and §6. The flips we obtain between various models of $\overline{M}_{0,n}$ are quite novel; in fact, it appears that

no genus zero flips have appeared previously in the literature¹. We hope that these can be used to illuminate some previously unexplored Mori-theoretic aspects of the birational geometry of $\overline{M}_{0,n}$. In particular, we note that the existence of a modular interpretation of these flips, and of the other VGIT maps, is reminiscent of the Hassett-Keel program which aims to construct log canonical models of \overline{M}_g through a sequence of modular flips and contractions.

1.3. Hassett’s weighted spaces. To illustrate the significance of our unified GIT construction of birational models, consider the Hassett moduli spaces $\overline{M}_{0,\vec{c}}$ of weighted pointed rational curves [Has03]. For a weight vector $\vec{c} = (c_1, \dots, c_n) \in \mathbb{Q}_{>0}^n$ with $\sum c_i > 2$, this space parameterizes nodal rational curves with smooth marked points that are allowed to collide if their weights add up to at most 1. Hassett showed that whenever the weights are decreased, e.g. $\vec{c}' = (c'_1, \dots, c'_n)$ with $c'_i \leq c_i$, there is a corresponding morphism $\overline{M}_{0,\vec{c}} \rightarrow \overline{M}_{0,\vec{c}'}$. It has since been discovered that these morphisms are all steps in the log minimal model program for $\overline{M}_{0,n}$. Specifically, the third author shows in [Moo11] that each Hassett space $\overline{M}_{0,\vec{c}}$ is the log canonical model of $\overline{M}_{0,n}$ with respect to the sum of tautological classes ψ_i weighted by \vec{c} .

If $\overline{M}_{0,n}$ is indeed a Mori dream space, then by the results of [HK00] it would be possible to obtain all log canonical models through VGIT. Although proving this seems a lofty goal, we are able to deduce the following from our present GIT construction:

Theorem 1.3. *For each fixed $n \geq 4$, there exists $d \geq 1$ such that every Hassett space $\overline{M}_{0,\vec{c}}$ arises as a quotient $U_{d,n} // \mathrm{SL}(d+1)$. Consequently, the log minimal model program for $\overline{M}_{0,n}$ with respect to the ψ -classes can be performed entirely through VGIT.*

1.4. Modular compactifications. In the absence of strictly semistable points, each birational model $U_{d,n} // \mathrm{SL}(d+1)$ is itself a moduli space of pointed rational curves. Moreover, this modular interpretation extends that of the interior, $M_{0,n}$. A formalism for such compactifications, in any genus, has been introduced by Smyth in [Smy09]. The basic idea is to define a modular compactification to be an open substack of the stack of all smoothable curves that is proper over $\mathrm{Spec} \mathbb{Z}$. Smyth shows that there are combinatorial gadgets, called extremal assignments, that produce modular compactifications—and that in genus zero, they produce all of them. This result can be thought of as a powerful step toward understanding the modular aspects of the birational geometry

¹That is, a flip in the Mori-theoretic sense of a relatively anti-ample divisor becoming relatively ample; see [AGS10, Theorem 7.7] for an example of a generalized flip between compactifications.

of $\overline{M}_{0,n}$. What remains is to determine the maps between these modular compactifications, and for this we can apply our GIT machinery.

In Proposition 5.5, we identify the extremal assignment corresponding to each GIT linearization without strictly semistable points. Although this does not yield all modular compactifications (cf. §7.5), it does yield an extensive class of them. For linearizations that admit strictly semistable points, the corresponding stack-theoretic quotients $[U_{d,n}^{ss}/\mathrm{SL}(d+1)]$ typically are non-separated Artin stacks—so they are not modular in the strict sense of Smyth. However, they are close to being modular in that they are weakly proper stacks (as in [ASW10]) parameterizing certain equivalence classes of pointed rational curves. One might call these “weakly modular” compactifications.

Recasting the results of §1.2 in this light, we begin to see an elegant structure emerge: *Every open GIT chamber in Δ° corresponds to a modular compactification of $M_{0,n}$, whereas the walls correspond to weakly modular compactifications. The wall-crossing maps yield relations between the various Smyth spaces that arise in our GIT construction.* In other words, the GIT chamber decomposition determines which modular compactifications should be thought of as “adjacent” in the space of all such compactifications.

1.5. Previous constructions. In the early 90s, Kapranov introduced two constructions of $\overline{M}_{0,n}$ that have since played an important role in many situations. He showed that $\overline{M}_{0,n}$ is the closure in $\mathrm{Chow}(1, n-2, \mathbb{P}^{n-2})$ of the locus of rational normal curves passing through n fixed points in general position [Kap93b]. There exist linearizations such that $U_{n-2,n} // \mathrm{SL}(n-1) \cong \overline{M}_{0,n}$, so setting $d = n-2$ in our construction yields a similar construction to Kapranov’s—except that instead of fixing the points, we let them vary and then quotient by the group of projectivities. Kapranov showed that $\overline{M}_{0,n}$ is also the Chow quotient $(\mathbb{P}^1)^n // \mathrm{SL}(2)$, or equivalently, the inverse limit of these GIT quotients [Kap93a]. But these GIT quotients are precisely the $d = 1$ case of our construction. So in a sense, our construction is inspired by, and yields a common generalization of, both of Kapranov’s constructions.

Remark 1.4. Kapranov showed that for both of his constructions, one could replace the relevant Chow variety with a Hilbert scheme and the construction remains. Similarly, we could have used a Hilbert scheme to define a variant of the incidence locus $U_{d,n}$. By Corollary 2.4, however, the irreducible components of any GIT-semistable curves coming from $U_{d,n}$ are reduced, so the Hilbert-Chow morphism restricts to an isomorphism over the semistable locus. Therefore, using an asymptotic linearization on the Hilbert scheme would yield GIT quotients isomorphic to those we consider here with the Chow variety.

The GIT quotients $(\mathbb{P}^1)^n // \mathrm{SL}(2)$ have made numerous appearances in the literature beyond Kapranov’s use in the Chow quotient—they are even included in Mumford’s book [MFK94] as “an elementary example” of GIT. The papers [Sim08, GS10] introduce and investigate the $d = 2$ case of the GIT quotients in this paper. In [Gia10], the first author introduces and studies GIT quotients parameterizing the configurations of points in projective space that arise in $U_{d,n}$, for $1 \leq d \leq n - 3$. These can be viewed as a special case of the current quotients obtained by setting the linearization on the Chow factor to be trivial. In fact, the GIT quotients studied here appear to include as special cases all GIT quotients of pointed rational curves that have previously been studied.

1.6. Outline. We briefly summarize the contents of this paper:

- In Section 2, we explain the GIT setup and prove some preliminary results. Among these is the fact that all of the GIT quotients $U_{d,n} // \mathrm{SL}(d + 1)$ are compactifications of $M_{0,n}$ (Prop 2.10).
- In Section 3, we develop the main tool for studying semistability in these quotients, a weight function that controls the degrees of components of GIT-stable curves. Using this function we explicitly determine the GIT walls and chambers (Prop 3.9).
- In Section 4, we show that the GIT quotients $U_{d,n} // \mathrm{SL}(d + 1)$ always receive a morphism from $\overline{M}_{0,n}$. This map factors through a Hassett space $\overline{M}_{0,\vec{c}}$ for a fixed weight datum \vec{c} determined by the linearization (Prop 4.7).
- In Section 5, we provide a modular description of all the GIT quotients $U_{d,n} // \mathrm{SL}(d + 1)$ (Thm 5.6).
- In Section 6, we describe the rational maps between these spaces arising from variation of GIT. We provide conditions for such a map to be a divisorial contraction (Cor 6.10), a flip (Cor 6.11), or to contract a curve (Prop 6.12).
- In Section 7, we construct several explicit examples of moduli spaces that arise from our GIT construction. We show that every Hassett space $\overline{M}_{0,\vec{c}}$, including $\overline{M}_{0,n}$, can be constructed in this way (Thm 7.1) and demonstrate an example of variation of GIT for $\overline{M}_{0,9}$ (Sec 7.3). We further demonstrate an example of a flip between two compactifications of $M_{0,n}$.

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2.1. The cone of linearizations. We are interested in the natural action of $\mathrm{SL}(d+1)$ on $U_{d,n} \subseteq \mathrm{Chow}(1, d, \mathbb{P}^d) \times (\mathbb{P}^d)^n$. Since $\mathrm{SL}(d+1)$ has no characters, the choice of a linearization is equivalent to the choice of an ample line bundle. Each projective space \mathbb{P}^d has the hyperplane class $\mathcal{O}_{\mathbb{P}^d}(1)$ as an ample generator of its Picard group. The Chow variety has a distinguished ample line bundle $\mathcal{O}_{\mathrm{Chow}}(1)$ coming from the embedding in projective space given by Chow forms. Therefore, by taking external tensor products we obtain an \mathbb{N}^{n+1} of ample line bundles on $\mathrm{Chow}(1, d, \mathbb{P}^d) \times (\mathbb{P}^d)^n$, which we then restrict to $U_{d,n}$.

It is convenient to use fractional linearizations by tensoring with \mathbb{Q} . Moreover, since stability is unaffected when a linearized line bundle is replaced by a tensor power, we can work with a transverse cross-section of the cone of linearizations:

$$\Delta := \left\{ (\gamma, c_1, c_2, \dots, c_n) \in \mathbb{Q}_{\geq 0}^{n+1} \mid (d-1)\gamma + \sum_{i=1}^n c_i = d+1 \right\}$$

As we will see (Corollary 2.6), this ensures that for a pointed curve to be semistable, all the points must have weight at most 1. This allows us to relate our construction to previous GIT constructions as well as Hassett's spaces, where the point weights are similarly bounded by 1.

2.2. The Hilbert-Mumford numerical criterion. Let $\lambda : \mathbb{C}^* \rightarrow \mathrm{SL}(d+1)$ be a one-parameter subgroup. As in [Mum77, 2.8], we renormalize the weights for this 1-PS to satisfy $r_0 \geq r_1 \geq \dots \geq r_d = 0$. Let x_i be homogeneous coordinates on \mathbb{P}^d for which λ is diagonalized. Given a variety $X \subseteq \mathbb{P}^d$, let R be its homogeneous coordinate ring and $I \subseteq R[t]$ the ideal generated by $\{t^{r_i} x_i\}_{0 \leq i \leq d}$. Following [Sch91, Lemma 1.3], we denote by $e_\lambda(X)$ the normalized leading coefficient of $\dim(R[t]/I^m)_m$, where $R[t] = \bigoplus_{i=1}^\infty R_i[t]$ is the grading on $R[t]$.

The following result is a crucial first step toward the GIT stability analysis conducted subsequently:

Proposition 2.1. *A pointed curve $(X, p_1, \dots, p_n) \in U_{d,n}$ is semistable with respect to the linearization $(\gamma, c_1, \dots, c_n) \in \Delta$ if, and only if, for every non-trivial 1-PS λ with weights r_i as above,*

$$\gamma e_\lambda(X) + \sum c_i e_\lambda(p_i) \leq (1 + \gamma) \sum r_i.$$

It is stable if and only if these inequalities are strict.

Proof. A pointed curve (X, p_1, \dots, p_n) is stable (resp. semistable) if and only if, for every 1-PS λ , the Hilbert-Mumford index $\mu_\lambda(X, p_1, \dots, p_n)$ is negative (resp. nonpositive). By [Mum77, Theorem 2.9] and its proof, we see that for the linearization $(\gamma, \vec{0})$ we have

$$\mu_\lambda(X) = \gamma(e_\lambda(X) - \frac{2d}{d+1} \sum r_i).$$

Similarly, for the linearization $(0, \vec{c})$, we have

$$\mu_\lambda(p_1, \dots, p_n) = \sum c_i e_\lambda(p_i) - \frac{\sum c_i}{d+1} \sum r_i.$$

By the linearity of the Hilbert-Mumford index, we therefore have

$$\begin{aligned} \mu_\lambda(X, p_1, \dots, p_n) &= \gamma e_\lambda(X) + \sum c_i e_\lambda(p_i) - \left(\frac{2d}{d+1}\gamma + \frac{\sum c_i}{d+1}\right) \sum r_i \\ &= \gamma e_\lambda(X) + \sum c_i e_\lambda(p_i) - (1 + \gamma) \sum r_i, \end{aligned}$$

where the last equality follows from the assumption that the linearization vector lies in the cross-section Δ (cf. §2.1). \square

2.3. Destabilizing one-parameter subgroups. There is one particularly simple type of 1-PS that is sufficient for most of our results.

Proposition 2.2. *Consider the k -dimensional linear subspace $V := V(x_{k+1}, x_{k+2}, \dots, x_d) \subset \mathbb{P}^d$, and let λ_V be the 1-PS with weight vector $(1, 1, \dots, 1, 0, \dots, 0)$, where the first $k+1$ weights are all one. For $X \in \text{Chow}(1, d, \mathbb{P}^d)$, write $X = X(V) \cup Y$, where $X(V)$ is the union of irreducible components of X contained in V . Then X is semistable with respect to λ_V if and only if*

$$\gamma(2 \deg X(V) + \deg(Y \cap V)) + \sum_{p_i \in V} c_i \leq (k+1)(1 + \gamma).$$

Proof. This follows from Proposition 2.1 and [Sch91, Lemma 1.2]. \square

We first consider the extreme cases $k = d-1$ and $k = 0$. The former leads to instability of degenerate curves, whereas the latter leads to upper bounds on the weight of marked points at smooth and singular points of semistable curves.

Proposition 2.3. *A pointed curve $(X, p_1, \dots, p_n) \in U_{d,n}$ is unstable if X is contained in a hyperplane $\mathbb{P}^{d-1} \subset \mathbb{P}^d$.*

Proof. We may assume that $\mathbb{P}^{d-1} = V(x_d)$. Consider the 1-PS in Proposition 2.2 with $V := \mathbb{P}^{d-1}$. Clearly $X(V) = X$, $Y = \emptyset$, and $\sum_{p_i \in V} c_i = \sum_{i=1}^n c_i = d+1 - (d-1)\gamma$, so

$$\begin{aligned} \gamma(2 \deg X(V) + \deg(Y \cap V)) + \sum_{p_i \in V} c_i &= 2d\gamma + (d+1) - (d-1)\gamma \\ &= (d+1)(1 + \gamma) > d(1 + \gamma), \end{aligned}$$

hence λ_V destabilizes (X, p_1, \dots, p_n) . \square

Consequently, GIT-semistable curves are geometrically quite nice:

Corollary 2.4. *A semistable pointed curve (X, p_1, \dots, p_n) has the following properties:*

- (1) *Each irreducible component is a rational normal curve in the projective space that it spans.*
- (2) *The singularities are at worst multinodal (analytically locally the union of coordinate axes in \mathbb{C}^k).*
- (3) *Every connected subcurve of degree e spans a \mathbb{P}^e .*

Proof. See [Art76, Lemma 13.1]. □

By setting $k = 0$ in Proposition 2.2, we obtain the following:

Proposition 2.5. *The total weight of the marked points at a singularity of multiplicity m on a GIT-stable curve cannot exceed $1 - (m - 1)\gamma$.*

Proof. Suppose the singularity occurs at the point $p = (1, 0, \dots, 0)$ and set $k = 0$. Then $X(p) = \emptyset$ and $\deg(Y \cap p) = \mu_p X = m$. If X is stable, then by Proposition 2.2 we have

$$\gamma m + \sum_{p_i=p} c_i < 1 + \gamma,$$

from which the result follows. □

Corollary 2.6. *The total weight of the marked points at a smooth point, and hence at any point, of a GIT-stable curve cannot exceed 1.*

Corollary 2.7. *A GIT-stable curve cannot have a singularity of multiplicity m unless $\gamma < \frac{1}{m-1}$.*

Proof. This follows from the fact that the minimum total weight at a point is zero. □

Corollary 2.8. *If $\gamma \geq 1$, then every GIT-semistable curve is smooth.*

2.4. Existence of a stable point. To ensure that GIT quotients of $U_{d,n}$ are compactifications of $M_{0,n}$, it is necessary and sufficient to prove that rational normal curves with configurations of distinct points are stable for each linearization. We prove this in several steps. By Corollary 2.8, the quotients with $\gamma \geq 1$ are rather uninteresting, so we focus henceforth on the case $\gamma < 1$. We begin with the simple case where all of the weights c_i are relatively small.

Lemma 2.9. *Let $(\gamma, \vec{c}) \in \Delta$ satisfy $\gamma < 1$ and $0 < c_i < 1 - \gamma \forall i$. Then $U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d+1)$ is a compactification of $M_{0,n}$.*

Proof. Let $X \subset \mathbb{P}^d$ be a rational normal curve and p_1, \dots, p_n distinct points of X . Since all rational normal curves in \mathbb{P}^d are projectively equivalent, it suffices to show that $(X, p_1, \dots, p_n) \in U_{d,n}$ is stable for the given linearization. We will show that (X, p_1, \dots, p_n) is stable with respect to the linearization $(0, \vec{c})$ and semistable with respect to the linearization $(\gamma, \vec{0})$. It then follows from general GIT results that (X, p_1, \dots, p_n) is stable with respect to the linearization (γ, \vec{c}) .

A rational normal curve has reduced degree 1, which is the minimum possible amongst all non-degenerate curves. It follows that X is linearly semistable, hence by [Mum77, Theorem 4.12] it is semistable with respect to the linearization $(\gamma, \vec{0})$. Now, let $V \subset \mathbb{P}^d$ be a k -dimensional linear space. Since any collection of n distinct points on a rational normal curve are in general linear position, we see that

$$\sum_{p_i \in V} c_i \leq \sum_{p_i \in V} (1 - \gamma) \leq (k + 1)(1 - \gamma) < (k + 1) \frac{\sum_{i=1}^n c_i}{d + 1}.$$

Hence (p_1, \dots, p_n) is stable for the linearization $(0, \vec{c})$, by [DH98, Example 3.3.24]. \square

We now tackle the more general case.

Proposition 2.10. *Let $(\gamma, \vec{c}) \in \Delta$ satisfy $\gamma < 1$ and $0 < c_i < 1$, $i = 1, \dots, n$. Then $U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d + 1)$ is a compactification of $M_{0,n}$.*

Proof. If $c_i < 1 - \gamma$ for all i , then the result holds by Lemma 2.9 above. We prove the remaining cases by induction on d , the case $d = 2$ having been done in [GS10]. Let (X, p_1, \dots, p_n) be smooth with distinct points, and assume without loss of generality that $c_1 \geq c_i$ for all i and that $c_1 > 1 - \gamma$. Let $\lambda : \mathbb{C}^* \rightarrow \mathrm{SL}(d + 1)$ be a 1-PS acting with weights $r_0 \geq r_1 \geq \dots \geq r_d = 0$, and write x_i for homogeneous coordinates on \mathbb{P}^d on which λ acts diagonally. We show in Lemma 2.11 below that it is sufficient to consider the situation $p_1 = (1, 0, 0, \dots, 0)$, so let us consider this case now.

Let f_i be the restriction of x_i to X , which is a homogeneous polynomial of degree d on $X \cong \mathbb{P}^1$. Write $\pi(X) \subset \mathbb{P}^{d-1}$ for the image of X under linear projection from p_1 and $\lambda^{(d)} : \mathbb{C}^* \rightarrow \mathrm{SL}(d)$ for the 1-PS with weights r_i , $i > 0$, diagonalized with respect to the homogeneous coordinates x_i , $i > 0$. Without loss of generality we assume that p_1 is the image of the point $[0 : 1] \in \mathbb{P}^1$ under the map $\mathbb{P}^1 \rightarrow \mathbb{P}^d$ given by the f_i 's. Notice that

$$e_{\lambda^{(d)}}(\pi(p_i)) = \min\{r_j | j > 0, f_j(p_i) \neq 0\} \geq \min\{r_j | f_j(p_i) \neq 0\} = e_{\lambda}(p_i)$$

$$e_{\lambda^{(d)}}(\pi(p_1)) = r_a := \min\{r_j | j > 0, \frac{f_j}{x}(p_1) \neq 0\} \leq r_0.$$

We now show that

$$e_{\lambda}(X) \leq e_{\lambda^{(d)}}(\pi(X)) + r_0 + r_a.$$

To see this, note that the polynomials $g_i := \frac{f_i}{x}$ for $i > 0$ form a basis for homogeneous polynomials of degree $d - 1$. Let J denote the ideal in $\mathbb{C}[x, y]$ generated by the f_i 's for all $i > 0$ and J' the ideal in $\mathbb{C}[x, y, t]$ generated by the $t^{r_i} f_i$'s for all $i > 0$. Then J^m consists of all polynomials that vanish at p_1 to order at least m , so $\dim \mathbb{C}[x, y]_{md} / J^m = m$. Since the polynomials $f_0^k f_a^{m-k}$, $1 \leq k \leq m$ each have different order of

vanishing at p_1 , they are linearly independent and hence form a basis for this vector space. Thus:

$$\begin{aligned} \dim(\mathbb{C}[x, y, t]/I^m)_{md} &\leq \dim(\mathbb{C}[x, y, t]/(t^{r_0k+r_a(m-k)} f_0^k f_a^{m-k}, J^m))_{md} \\ &\leq \binom{m+1}{2} (r_0 + r_a) + \dim(\mathbb{C}[x, y, t]/(t^{r_i} g_i)^m)_{m(d-1)}. \end{aligned}$$

Taking normalized leading coefficients, we obtain the formula above.

It follows that

$$\gamma e_\lambda(X) + \sum_{i=1}^n c_i e_\lambda(p_i) \leq \gamma(e_{\lambda^{(d)}}(\pi(X)) + r_0 + r_a) + c_1 r_0 + \sum_{i=2}^n c_i e_{\lambda^{(d)}}(\pi(p_i)).$$

By induction, however, we know that

$$\gamma e_{\lambda^{(d)}}(\pi(X)) + (c_1 - (1 - \gamma))r_a + \sum_{i=2}^n c_i e_{\lambda^{(d)}}(\pi(p_i)) < (1 + \gamma) \sum_{j=1}^d r_j.$$

It follows that the expression above is smaller than

$$(1 + \gamma) \sum_{j=1}^d r_j - (c_1 - (1 - \gamma))r_a + \gamma r_0 + c_1 r_0 + \gamma r_a \leq (1 + \gamma) \sum_{j=0}^d r_j$$

as desired. The result then follows from Lemma 2.11 below. \square

Lemma 2.11. *Let (X, p_1, \dots, p_n) and λ be as above. Then there is a curve (X, p'_1, \dots, p'_n) and a 1-PS λ' such that $p'_1 = (1, 0, \dots, 0)$ and*

$$\gamma e_\lambda(X) + \sum c_i e_\lambda(p_i) \leq \gamma e_{\lambda'}(X) + \sum c_i e_{\lambda'}(p'_i).$$

Proof. Let $V_k \subset \mathbb{P}^d$ be the k -dimensional linear space cut out by $x_{k+1} = x_{k+2} = \dots = x_d = 0$. We let k be the smallest integer such that $X \cap V_k$ is non-empty, and write λ' for the 1-PS acting with weights $(r_k, r_k, \dots, r_k, r_{k+1}, \dots, r_d)$. Note that $\sum_{i=1}^n c_i e_\lambda(p_i) = \sum_{i=1}^n c_i e_{\lambda'}(p_i)$. We claim that $e_\lambda(X) = e_{\lambda'}(X)$ as well. Indeed, let W denote the linear series on $X \cong \mathbb{P}^1$ generated by x_k, \dots, x_d . By assumption, W is basepoint-free, so it contains a basepoint-free pencil. Using the basepoint-free pencil trick, we see that the map

$$W \otimes H^0(X, \mathcal{O}((m-1)d)) \rightarrow H^0(X, \mathcal{O}(md))$$

is surjective for all $m \geq 2$. By induction on m , the map

$$\text{Sym}^{m-1} W \otimes H^0(X, \mathcal{O}(d)) \rightarrow H^0(X, \mathcal{O}(md))$$

is surjective as well. It follows that $\dim(R[t]/I^m)_m$ depends only linearly on r_i for all $i < k$. In other words, these r_i 's do not contribute to the normalized leading coefficient, so $e_\lambda(X) = e_{\lambda'}(X)$. Because of this, we may assume that X passes through the point $(1, 0, 0, \dots, 0)$.

Next, relabel the points as follows:

$$p'_i = \begin{cases} (1, 0, 0, \dots, 0) & \text{if } i = 1 \\ p_1 & \text{if } p_i = (1, 0, 0, \dots, 0) \\ p_i & \text{otherwise} \end{cases}$$

Note that $\sum_{i=1}^n c_i e_\lambda(p_i) \leq \sum_{i=1}^n c_i e_\lambda(p'_i)$. This concludes the proof. \square

Note that if $c_i > 1$ for any i , then no element of $U_{d,n}$ is semistable by Corollary 2.6. The only remaining case, therefore, is when $c_i = 1$ for some i . In this case we will see that every semistable point is strictly semistable, and the resulting quotient is a compactification of $M_{0,n}$ if and only if d is larger than the number of i 's for which equality holds. We delay the proof of this until §6.4.

2.5. The space of effective linearizations. Recall (cf. §2.1) that we have been working with the cross-section Δ of the cone of linearizations defined by $(d-1)\gamma + \sum_{i=1}^n c_i = d+1$. As we remarked earlier, the quotients we are interested in satisfy $\gamma < 1$, since otherwise all semistable curves are isomorphic to \mathbb{P}^1 . Moreover, by Corollary 2.6 we can assume that $c_i \leq 1$ for all i . In fact, by Proposition 2.10 we know that if $c_i < 1$ for all i then the linearization (γ, \vec{c}) is effective, i.e., the semistable locus is nonempty. To avoid boundary issues such as non-ample linearizations, it is convenient to assume also that $c_i > 0$ for all i . Therefore, we are led to the following space of effective linearizations:

$$\Delta^\circ := \{(\gamma, c_1, \dots, c_n) \in \mathbb{Q}^{n+1} \mid 0 < \gamma, c_i < 1, (d-1)\gamma + \sum_{i=1}^n c_i = d+1\}.$$

This is the space of linearizations of most interest to us. By Proposition 2.10, for any $L \in \Delta^\circ$, the quotient $U_{d,n} //_L \mathrm{SL}(d+1)$ is birational to $\bar{M}_{0,n}$.

3. DEGREES OF COMPONENTS IN STABLE CURVES

In this section we apply the stability results of the previous section to get a fairly explicit description of the pointed curves (X, p_1, \dots, p_n) corresponding to stable points of $U_{d,n}$. Specifically, we show that for a generic linearization, GIT stability completely determines the degrees of subcurves of X . This is then used to describe the walls in the GIT chamber decomposition of Δ° .

We begin by defining a numerical function that will be useful for describing the degrees of subcurves. First, some notation: given a linearization (γ, \vec{c}) and a subset $I \subset [n]$, we set

$$c_I := \sum_{i \in I} c_i \text{ and } c := \sum_{i=1}^n c_i.$$

3.1. Weight functions. Consider the function

$$\varphi : 2^{[n]} \times \Delta^\circ \rightarrow \mathbb{Q} \qquad \varphi(I, \gamma, \vec{c}) = \frac{c_I - 1}{1 - \gamma}.$$

For a fixed linearization $(\gamma, \vec{c}) \in \Delta^\circ$, we define

$$\sigma(I) = \begin{cases} \lceil \varphi(I, \gamma, \vec{c}) \rceil & \text{if } 1 \leq c_I \leq c - 1 \\ 0 & \text{if } c_I < 1 \\ d & \text{if } c_I > c - 1 \end{cases}$$

Before relating this to the degrees of subcurves in GIT stable curves, let us make a few elementary observations:

Lemma 3.1. *For any $I \subset [n]$, we have $\sigma(I) \in \{0, 1, \dots, d\}$. If $\sigma(I) = d$, then $c_I > c - 1$.*

Proof. It is enough to show that $\varphi(I, \gamma, \vec{c}) \leq d - 1$ whenever $1 \leq c_I \leq c - 1$. But in this case we have

$$\varphi(I, \gamma, \vec{c}) = \frac{c_I - 1}{1 - \gamma} \leq \frac{c - 2}{1 - \gamma} = \frac{(d + 1 - (d - 1)\gamma) - 2}{1 - \gamma} = d - 1,$$

so this indeed holds. \square

Lemma 3.2. *For any collection of disjoint subsets $I_1, \dots, I_m \subset [n]$,*

$$\sigma\left(\bigcup_{j=1}^m I_j\right) \geq \sum_{j=1}^m \sigma(I_j).$$

Proof. The statement is trivial for $m = 1$, so assume $m \geq 2$. Note that if $\sigma(I_j) = 0$ for any j , then it does not contribute to the sum, so we may ignore it. If there is a j with $c_{I_j} > c - 1$, then by the disjointness hypothesis we have $c_{I_k} < 1$, and hence $\sigma(I_k) = 0$, for all $k \neq j$. Therefore, we are reduced to the case that $\sigma(I_j) = \lceil \varphi(I_j, \gamma, \vec{c}) \rceil$ for every j . In this case, since $\frac{1}{1-\gamma} \geq 1$, we have

$$\begin{aligned} \sum_{j=1}^m \sigma(I_j) &= \sum_{j=1}^m \left\lceil \frac{c_{I_j} - 1}{1 - \gamma} \right\rceil < \sum_{j=1}^m \left(\frac{c_{I_j} - 1}{1 - \gamma} + 1 \right) \\ &= \frac{\sum_{j=1}^m c_{I_j} - 1}{1 - \gamma} - \frac{m - 1}{1 - \gamma} + 1 \leq \frac{\sum_{j=1}^m c_{I_j} - 1}{1 - \gamma} \\ &\leq \left\lceil \frac{\sum_{j=1}^m c_{I_j} - 1}{1 - \gamma} \right\rceil = \left\lceil \frac{c_{I_1 \cup \dots \cup I_m} - 1}{1 - \gamma} \right\rceil, \end{aligned}$$

which by definition is $\sigma(\bigcup_{j=1}^m I_j)$. \square

Perhaps most significantly, σ satisfies a convenient additivity property for most linearizations:

Lemma 3.3. *If $\varphi(I, \gamma, \vec{c}) \notin \mathbb{Z}$ for each nonempty $I \subset [n]$, then*

$$\sigma(I) + \sigma(I^c) = d$$

for each I .

Proof. If $c_I < 1$ then $c_{I^c} = c - c_I > c - 1$, so $\sigma(I) + \sigma(I^c) = d + 0 = d$. The case $c_I > c - 1$ is analogous, so without loss of generality assume that c_I and c_{I^c} are between 1 and $c - 1$. Then

$$\begin{aligned} \sigma(I^c) = \lceil \frac{c_{I^c} - 1}{1 - \gamma} \rceil &= \lceil \frac{(d+1) - (d-1)\gamma - c_I - 1}{1 - \gamma} \rceil \\ &= \lceil d - 1 - \frac{c_I - 1}{1 - \gamma} \rceil = d - \sigma(I), \end{aligned}$$

where the last equality uses the non-integrality assumption. \square

3.2. Degrees of tails. As we show below, the function σ computes the degree of a certain type of subcurve. For notational convenience, given a marked curve (X, p_1, \dots, p_n) and a subcurve $Y \subset X$, let us set

$$\varphi(Y, \gamma, \vec{c}) = \varphi(\{i \mid p_i \in Y\}, \gamma, \vec{c})$$

and similarly for $\sigma(Y)$.

Definition 3.4. *Let $X \in \text{Chow}(1, d, \mathbb{P}^d)$. A subcurve $Y \subset X$ is called a **tail** if it is connected and $|Y \cap X \setminus Y| = 1$.*

We do not require tails to be irreducible. Moreover, this intersection is set-theoretic; the ‘‘attaching point’’ of a tail need not be a node.

Proposition 3.5. *For a fixed $(\gamma, \vec{c}) \in \Delta^\circ$, suppose that $\varphi(I, \gamma, \vec{c}) \notin \mathbb{Z}$ for any nonempty $I \subset [n]$. If X is a GIT-semistable curve and $E \subset X$ a tail, then $\deg(E) = \sigma(E)$.*

Proof. Write $r := \deg(E)$. The dimension of the linear span of E is r by Corollary 2.4, so we may assume that $E \subset V := V(x_{r+1}, \dots, x_d) \subset \mathbb{P}^d$. Now

$$\gamma(2 \deg X(V) + \deg(Y \cap V)) + \sum_{p_i \in V} c_i \geq \gamma(2r + 1) + \sum_{p_i \in E} c_i,$$

so by Proposition 2.2 we have

$$\sum_{p_i \in E} c_i \leq (r + 1)(1 + \gamma) - \gamma(2r + 1) = r + 1 - \gamma r,$$

or equivalently,

$$r \geq \frac{(\sum_{p_i \in E} c_i) - 1}{1 - \gamma}.$$

Since r is a positive integer, it follows that $r \geq \sigma(E)$.

Now, if E is a tail then so is $\overline{X \setminus E}$, hence

$$\deg(\overline{X \setminus E}) \geq \sigma(\overline{X \setminus E}) \geq \sigma(\{i \mid p_i \notin E\}).$$

Thus, by Lemma 3.3, $\deg(\overline{X \setminus E}) \geq d - \sigma(E)$. But we know that $r + \deg(\overline{X \setminus E}) = d$, so the inequality $r \leq \sigma(E)$ also holds. \square

3.3. Arbitrary subcurves. Removing an irreducible component from a curve yields a finite collection of tails. This holds more generally for any connected subcurve. We can combine this fact with the above result on tails to deduce the following:

Corollary 3.6. *Suppose that $\varphi(I, \gamma, \vec{c}) \notin \mathbb{Z}$ for any $\emptyset \neq I \subset [n]$, and let $E \subseteq X$ be a connected subcurve of $(X, p_1, \dots, p_n) \in U_{d,n}^{ss}$. Then*

$$\deg(E) = d - \sum \sigma(Y)$$

where the sum is over all connected components Y of $\overline{X \setminus E}$.

Proof. If Y is a connected component of $\overline{X \setminus E}$, then it is a tail. It follows from Proposition 3.5 that $\deg(Y) = \sigma(Y)$. Since the total degree of X is d , we see that $\deg(E) = d - \sum \sigma(Y)$. \square

3.4. GIT Walls. These results are sufficient to determine the wall-and-chamber decomposition of Δ° . Specifically, for any integer k with $0 \leq k \leq d - 1$, the set $\varphi(I, \cdot)^{-1}(k)$ defines a hyperplane in Δ° . Note that, by additivity,

$$\varphi(I, \cdot)^{-1}(k) = \varphi(I^c, \cdot)^{-1}(d - 1 - k),$$

but otherwise these hyperplanes are distinct.

Proposition 3.7. *If (γ, \vec{c}) is not contained in any hyperplane of the form $\varphi(I, \cdot)^{-1}(k)$, then every semistable pointed curve has trivial automorphism group.*

Proof. By Corollary 2.4, every semistable curve is a union of rational normal curves meeting in multinodal singularities. It follows that such a curve (X, p_1, \dots, p_n) has a non-trivial automorphism if and only if it contains either:

- (1) a tail E with all marked points of its smooth locus E^{sm} supported on at most one point, or
- (2) a component E with $|E \cap \overline{X \setminus E}| = 2$ such that E^{sm} contains no marked points.

We show that neither of these cases is possible. Let $E \subset X$ be a tail. Since E has positive degree, by Proposition 3.5 we have $\sigma(E) \geq 1$, so by additivity $\sigma(\overline{X \setminus E}) \leq d - 1$, and hence by Lemma 3.1 we see that $\sum_{p_i \in \overline{X \setminus E}} c_i \leq c - 1$. By the non-integrality assumption this inequality must be strict, and consequently $\sum_{p_i \in E^{sm}} c_i > 1$. On the other hand, by Corollary 2.6, the sum of the weights at a smooth point of E cannot exceed 1. It follows that the marked points on E must be supported at 2 or more points of E other than the singular point.

Similarly, let $E \subset X$ be a bridge—a component such that $|E \cap \overline{X \setminus E}| = 2$. Let Y_1, Y_2 denote the connected components of $\overline{X \setminus E}$. If the smooth part of E contains no marked points, then by Lemma 3.3 we see that $\sigma(Y_1) + \sigma(Y_2) = d$. Again, since E has positive degree, by Corollary 3.6 this is impossible. \square

Corollary 3.8. *If (γ, \vec{c}) is not contained in any hyperplane of the form $\varphi(I, \cdot)^{-1}(k)$, then the corresponding GIT quotient admits no strictly semistable points.*

Proof. If $U_{d,n}^{ss}$ contains strictly semistable points, then some of these points must have positive-dimensional stabilizer. If (X, p_1, \dots, p_n) is such a curve, then since X spans \mathbb{P}^d , by Proposition 2.3, such a stabilizer cannot fix X pointwise. It follows that (X, p_1, \dots, p_n) admits a non-trivial automorphism, which contradicts Proposition 3.7. \square

Proposition 3.9. *The hyperplanes $\varphi(I, \cdot)^{-1}(k)$ are the walls in the GIT chamber decomposition of Δ° .*

Proof. By Corollary 3.8, if a linearization does not lie on any of these hyperplanes, then it admits no strictly semistable points. Hence the GIT walls must be contained in these hyperplanes. To see that each hyperplane $\varphi(I, \cdot)^{-1}(k)$ yields a wall in Δ° , we must show that the stable locus changes when each such hyperplane is crossed. But it is clear from the definition that the function σ in §3.1 changes along these hyperplanes, so by Proposition 3.5, GIT stability changes as well. \square

4. FROM DELIGNE-MUMFORD TO GIT

In this section we prove Theorem 1.2, i.e., that the GIT quotients $U_{d,n} // \mathrm{SL}(d+1)$ always receive a regular morphism from the moduli space of stable curves $\overline{M}_{0,n}$. The main tool we use is the Kontsevich space of stable maps $\overline{M}_{0,n}(\mathbb{P}^d, d)$ [FP95]. The basic idea is as follows. The product of evaluation maps yields a morphism $\overline{M}_{0,n}(\mathbb{P}^d, d) \rightarrow (\mathbb{P}^d)^n$. By pushing-forward the fundamental cycle of each curve under each stable map, there is also a morphism $\overline{M}_{0,n}(\mathbb{P}^d, d) \rightarrow \mathrm{Chow}(1, d, \mathbb{P}^d)$. By functoriality, one sees that together these yield a morphism

$$\phi : \overline{M}_{0,n}(\mathbb{P}^d, d) \rightarrow U_{d,n} \subset \mathrm{Chow}(1, d, \mathbb{P}^d) \times (\mathbb{P}^d)^n.$$

This map is clearly $\mathrm{SL}(d+1)$ -equivariant. We prove below that for a general linearization L on $U_{d,n}$, there is a corresponding linearization L' on $\overline{M}_{0,n}(\mathbb{P}^d, d)$ such that:

- (1) there is an induced map $\overline{M}_{0,n}(\mathbb{P}^d, d) //_{L'} \mathrm{SL}(d+1) \rightarrow U_{d,n} //_L \mathrm{SL}(d+1)$, and
- (2) there is an isomorphism $\overline{M}_{0,n}(\mathbb{P}^d, d) //_{L'} \mathrm{SL}(d+1) \cong \overline{M}_{0,n}$

This is enough to draw the desired conclusion:

Lemma 4.1. *If (1) and (2) above hold for all $L \in \Delta^\circ$ that do not lie on a GIT wall, then for any $L \in \Delta^\circ$ there is a regular birational morphism $\overline{M}_{0,n} \rightarrow U_{d,n} //_L \mathrm{SL}(d+1)$.*

Proof. Given $L \in \Delta^\circ$, we can perturb it slightly to obtain a linearization L_ϵ such that stability and semistability coincide. By general variation of GIT, there is a birational morphism from the L_ϵ -quotient to the L -quotient. Using (1) and (2) we then have

$$\overline{M}_{0,n} \cong \overline{M}_{0,n}(\mathbb{P}^d, d) //_{L_\epsilon} \mathrm{SL}(d+1) \rightarrow U_{d,n} //_{L_\epsilon} \mathrm{SL}(d+1) \rightarrow U_{d,n} //_L \mathrm{SL}(d+1).$$

Birationality of this morphism follows from Proposition 2.10. \square

4.1. Equivariant maps and GIT. Here we prove a generalized form of the result needed for item (1) above.

Lemma 4.2. *Let $f : X \rightarrow Y$ be a G -equivariant birational morphism between two projective varieties. Suppose X is normal, and let L be a linearization on Y . Then there exists a linearization L' on X such that*

$$f^{-1}(Y^s(L)) \subset X^s(L') \subset X^{ss}(L') \subset f^{-1}(Y^{ss}(L)).$$

Proof. Take an f -ample divisor M , the existence of which is guaranteed by [Gro61, 5.3, 5.5]. Since X is normal, some integral multiple of M is G -linearized [MFK94, Corollary 1.6], so we may assume that M is G -linearized. Let $L' = f^*(L^m) \otimes M$ for sufficiently large m . Then L' is ample and the above inclusions hold by [Hu96, Theorem 3.11]. \square

Corollary 4.3. *With the same assumptions as the previous lemma, there is a quotient morphism*

$$\overline{f} : X //_{L'} G \rightarrow Y //_L G.$$

Proof. By Lemma 4.2, we have $f(X^{ss}(L')) \subset Y^{ss}(L)$, so there is a morphism $X^{ss}(L') \rightarrow Y //_L G$. This is G -invariant, so it must factor through the categorical quotient of $X^{ss}(L')$ by G , which is precisely the GIT quotient $X //_{L'} G$. \square

4.2. Invariant maps and unstable divisors. In this subsection we address item (2) above. To begin, recall that there is a forgetting-stabilizing map $\pi : \overline{M}_{0,n}(\mathbb{P}^d, d) \rightarrow \overline{M}_{0,n}$. Since this is $\mathrm{SL}(d+1)$ -invariant, the universal property of categorical quotients implies that there is an induced map

$$\overline{\pi} : \overline{M}_{0,n}(\mathbb{P}^d, d) //_{L'} \mathrm{SL}(d+1) \rightarrow \overline{M}_{0,n}.$$

for any linearization L' . The main result here is that if $L \in \Delta^\circ$ does not lie on a GIT wall and L' is as in Lemma 4.2, then this induced quotient morphism is in fact an isomorphism. In what follows, we always consider a linearization L' on $\overline{M}_{0,n}(\mathbb{P}^d, d) //_{L'} \mathrm{SL}(d+1)$ that is of this form, so that stability and semistability coincide. To show that

$\bar{\pi}$ is an isomorphism, we show that it has relative Picard number zero. First, a couple preliminary results:

Lemma 4.4. *For $0 \leq i \leq d$ and $I \subset [n]$, let $D_{i,I}$ be a boundary divisor of $\bar{M}_{0,n}(\mathbb{P}^d, d)$. Only one of $D_{i,I}$ for $i = 0, 1, \dots, d$ can be stable.*

Proof. By Lemma 4.2 and the stability assumption, to compute stability of $x \in \bar{M}_{0,n}(\mathbb{P}^d, d)$, it suffices to consider the stability of $\phi(x) \in U_{d,n}$.

Choose a general point $(f : (C_1 \cup C_2, p_1, \dots, p_n) \rightarrow \mathbb{P}^d)$ in $D_{i,I}$. Then $f(C_1) \subset \mathbb{P}^d$ is a degree i rational normal curve and $f(C_2) \subset \mathbb{P}^d$ is a degree $d-i$ rational normal curve. (If $i = 0$, then $f(C_1)$ is a point.) By dimension considerations, the linear spans of $f(C_1)$ and $f(C_2)$ meet at a unique point, namely $f(C_1 \cap C_2)$. By Proposition 3.5, $f(C_1 \cup C_2)$ is stable only if $\deg(f|_{C_1}) = \sigma(I)$ and $\deg(f|_{C_2}) = \sigma(I^c)$, so at most one $D_{i,I}, i \in \{0, \dots, d\}$, is stable. \square

Lemma 4.5. *Let X be a normal \mathbb{Q} -factorial projective variety with a linearized $\mathrm{SL}(n)$ -action, and suppose that $X^{ss} = X^s$. Then*

$$\mathrm{Pic}(X // \mathrm{SL}(n))_{\mathbb{Q}} \cong \mathrm{Pic}(X^{ss})_{\mathbb{Q}}.$$

Proof. For the quotient morphism $q : X^{ss} \rightarrow X // \mathrm{SL}(n)$, the pull-back morphism $q^* : \mathrm{Pic}(X // \mathrm{SL}(n)) \rightarrow \mathrm{Pic}(X^{ss})$ is injective because q is dominant. Conversely, pick $L \in \mathrm{Pic}(X^{ss})$. By Kempf's descent lemma [DN89, Theorem 2.3], L is a pull-back of some line bundle on $X // \mathrm{SL}(n)$ if and only if for every point with closed orbit, the stabilizer acts on the fiber trivially. Because $X^{ss} = X^s$, the stabilizer group of each point is finite. Thus on some integral multiple of L , the stabilizer group of each point acts trivially. Hence L^m is the pull-back of some line bundle on $X // \mathrm{SL}(n)$, so q^* is surjective after tensoring with \mathbb{Q} . \square

We now prove the main result.

Proposition 4.6. *The map $\bar{\pi} : \bar{M}_{0,n}(\mathbb{P}^d, d) //_{L'} \mathrm{SL}(d+1) \rightarrow \bar{M}_{0,n}$ is an isomorphism.*

Proof. The space $\bar{M}_{0,n}(\mathbb{P}^d, d)$ is a normal variety with finite quotient singularities only [FP95, Theorem 2]. Since there are no strictly semistable points with respect to L' , the GIT quotient $\bar{M}_{0,n}(\mathbb{P}^d, d) //_{L'} \mathrm{SL}(d+1)$ is also normal and with finite quotient singularities only. Since $\bar{\pi}$ is a birational morphism between two normal \mathbb{Q} -factorial projective varieties, to show that $\bar{\pi}$ is an isomorphism it suffices to show that the Picard number of both varieties is the same [KM98, Lemma 2.62]. By [Kee92], the Picard number of $\bar{M}_{0,n}$ is $2^{n-1} - \binom{n}{2} - 1$. By [Pan99, Theorem 2]), the Picard number of $\bar{M}_{0,n}(\mathbb{P}^d, d)$, for $d \geq 2$, is $(d+1)2^{n-1} - \binom{n}{2}$. Therefore, it suffices to show that there are $d \cdot 2^{n-1} + 1$ numerically independent unstable divisors.

Take a partition $I \sqcup I^c$ of $[n]$ with $2 \leq |I| \leq n - 2$. Among $D_{0,I}, D_{1,I}, \dots, D_{d,I}$, there are at least d unstable divisors by Lemma 4.4. It follows from [Pan99, Lemma 1.2.3] that these are all numerically independent. Since degenerate curves in $U_{d,n}$ are unstable by Proposition 2.3, their inverse image

$$D_{deg} = \{f : (C, x_1, \dots, x_n) \rightarrow \mathbb{P}^d \mid \text{span of } f(C) \text{ is not } \mathbb{P}^d\}$$

is unstable, too. One checks that this divisor is independent of the preceding divisors either by explicitly constructing a curve in $\overline{M}_{0,n}(\mathbb{P}^d, d)$ or by using the formula for D_{deg} in the $n = 0$ case in [CHS08, Lemma 2.1] and pulling back to $\overline{M}_{0,n}(\mathbb{P}^d, d)$.

Combining this with Lemma 4.5, we obtain

$$\begin{aligned} \rho(\overline{M}_{0,n}(\mathbb{P}^d, d) //_{L'} \text{SL}(d+1)) &= \rho(\overline{M}_{0,n}(\mathbb{P}^d, d)^s) \\ &\leq (d+1)2^{n-1} - \binom{n}{2} - d2^{n-1} - 1 \\ &= 2^{n-1} - \binom{n}{2} - 1 = \rho(\overline{M}_{0,n}) \end{aligned}$$

The opposite inequality holds due to the existence of the birational morphism $\overline{\pi}$. This completes the proof. \square

4.3. Relation to Hassett’s spaces. We prove here that the morphism constructed above factors through a Hassett moduli space of weighted pointed curves. First observe that for any linearization $(\gamma, \vec{c}) \in \Delta^\circ$, the vector \vec{c} defines a Hassett space $\overline{M}_{0,\vec{c}}$.

Proposition 4.7. *For any $(\gamma, \vec{c}) \in \Delta^\circ$, there is a commutative triangle:*

$$\begin{array}{ccc} \overline{M}_{0,n} & \xrightarrow{\phi} & U_{d,n} //_{(\gamma, \vec{c})} \text{SL}(d+1) \\ & \searrow & \nearrow \\ & \overline{M}_{0,\vec{c}} & \end{array}$$

Proof. By a result of Alexeev (cf. [Fak09, Lemma 4.6]), it is enough to show that every F-curve contracted by the map $\overline{M}_{0,n} \rightarrow \overline{M}_{0,\vec{c}}$ is also contracted by ϕ . The F-curves contracted by this Hassett morphism are precisely those for which one of the tails carries $\geq c - 1$ weight of marked points. By Proposition 3.5, for a generic linearization these F-curves are also contracted by ϕ because their heavy leg must have degree d , leaving degree zero for the component with the four attaching points. If the linearization is not generic, then we can obtain the result by perturbing the linearization slightly:

$$\overline{M}_{0,n} \rightarrow \overline{M}_{0,\vec{c}} \rightarrow \overline{M}_{0,\vec{c}-\epsilon} \rightarrow U_{d,n} //_{\gamma', \vec{c}-\epsilon} \text{SL}(d+1) \rightarrow U_{d,n} //_{\gamma, \vec{c}} \text{SL}(d+1).$$

Everything is separated and the interior $M_{0,n}$ is preserved, so this composition coincides with ϕ . \square

5. MODULAR INTERPRETATION OF CHAMBERS

In the absence of strictly semistable points, i.e., for linearizations in open GIT chambers, the GIT quotients $U_{d,n} // \mathrm{SL}(d+1)$ are fine moduli spaces of pointed rational curves. In this section we describe explicitly the functors they represent. A useful framework for accomplishing this is provided by Smyth's notion of a *modular compactification* [Smy09].

5.1. Modular Compactifications. We briefly recall here the relevant results from [Smy09]. A modular compactification is defined to be an open substack of the stack of all curves that is proper over $\mathrm{Spec} \mathbb{Z}$ [Smy09, Definition 1.1]. A main result of Smyth is that in genus zero these are classified by certain combinatorial gadgets.

Definition 5.1. [Smy09, Definition 1.5] *Let \mathcal{G} be the set of isomorphism classes of dual graphs of strata in $\overline{M}_{0,n}$. An **extremal assignment** \mathcal{Z} is a proper (though possibly empty) subset of vertices $\mathcal{Z}(G) \subsetneq G$ for each $G \in \mathcal{G}$ such that if $G \rightsquigarrow G'$ is a specialization inducing $v \rightsquigarrow v'_1 \cup \dots \cup v'_k$, then $v \in \mathcal{Z}(G) \Leftrightarrow v'_1, \dots, v'_k \in \mathcal{Z}(G')$.*

Smyth states an additional axiom that for any $G \in \mathcal{G}$, the set $\mathcal{Z}(G)$ is invariant under $\mathrm{Aut}(G)$, but in genus zero there are no nontrivial automorphisms since G is a tree with marked points on all the leaves.

Definition 5.2. [Smy09, Definition 1.8] *Let \mathcal{Z} be an extremal assignment. A reduced marked curve (X, p_1, \dots, p_n) is **\mathcal{Z} -stable** if there exists $(X^s, p_1^s, \dots, p_n^s) \in \overline{M}_{0,n}$ and a surjective morphism $\pi : X^s \rightarrow X$, $\pi(p_i^s) = p_i$, with connected fibers such that:*

- (1) π maps $X^s \setminus \mathcal{Z}(X^s)$ isomorphically onto its image, and
- (2) if X_1, \dots, X_k are the irreducible components of $\mathcal{Z}(X^s)$, then $\pi(X_i)$ is a multinodal singularity of multiplicity $|X_i \cap X_i^c|$.

The beautiful culmination of Smyth's story, in genus zero, is the following result:

Theorem 5.3 ([Smy09]). *For any extremal assignment \mathcal{Z} , the stack $\overline{M}_{0,n}(\mathcal{Z})$ of \mathcal{Z} -stable curves is an algebraic space and a modular compactification of $M_{0,n}$. There is a morphism $\overline{M}_{0,n} \rightarrow \overline{M}_{0,n}(\mathcal{Z})$ contracting the assigned components of each DM-stable curve. Every modular compactification is of the form $\overline{M}_{0,n}(\mathcal{Z})$ for an extremal assignment \mathcal{Z} .*

5.2. Extremal assignments from GIT. For GIT situations such that there are no strictly semistable points, the corresponding quotient is not only a categorical quotient of the semistable locus but in fact a geometric quotient [MFK94]. In the present situation, it is not hard

to see that in such cases the quotient $U_{d,n} // \mathrm{SL}(d+1)$ is a modular compactification of $M_{0,n}$ in the sense of [Smy09]. In particular, for each linearization (γ, \vec{c}) in an open GIT chamber, there is a corresponding extremal assignment. We define here an extremal assignment $\mathcal{Z}_{\gamma, \vec{c}}$ and then show below that it is in fact the extremal assignment associated to the corresponding GIT quotient.

Definition 5.4. *Let $E \subset X$ be an irreducible component of a DM-stable curve. Set $E \in \mathcal{Z}_{\gamma, \vec{c}}(X)$ if and only if $\sum \sigma(Y) = d$, where the sum is over all connected components Y of $\overline{X} \setminus \overline{E}$.*

Proposition 5.5. *Let $(\gamma, \vec{c}) \in \Delta^\circ$ be a linearization admitting no strictly semistable points. Then $\mathcal{Z}_{\gamma, \vec{c}}$ is an extremal assignment.*

Proof. It suffices to show that $\mathcal{Z} := \mathcal{Z}_{\gamma, \vec{c}}$ satisfies the axioms of Definition 5.1. We first show that \mathcal{Z} is invariant under specialization. Let $v \in \mathcal{Z}(G)$, and suppose that $G \rightsquigarrow G'$ is a specialization with $v \rightsquigarrow v'_1 \cup v'_2 \cup \cdots \cup v'_k$. To see that $v'_i \in \mathcal{Z}$ for all i as well, notice that the marked points on the connected components of $G \setminus \{v'_i\}$ contain unions of the marked points of the connected components of $G \setminus \{v\}$. Thus, the result follows from Lemma 3.2.

Next, suppose that $v'_i \in \mathcal{Z}(G)$ for $i = 1, \dots, k$. We must show that $v \in \mathcal{Z}(G)$ as well. We prove this by induction on k , the case $k = 1$ being trivial. To prove the inductive step, let T be the subtree spanned by all of the v'_i and let v' be a leaf of T . Let A_1, \dots, A_s denote the connected components of $G' \setminus \{v'\}$, and let B_1, \dots, B_t denote the connected components of $(G' \setminus T) \cup \{v'\}$. By assumption, $\sum_{i=1}^s \sigma(A_i) = d$, and by induction we may assume that $\sum_{i=1}^t \sigma(B_i) = d$. Note that exactly one of the B_i 's contains v' . Without loss of generality, we assume that this is B_t . Similarly, since v' is a leaf of T , exactly one of the A_i 's contains $T \setminus \{v'\}$, and we will assume that this is A_s . Note that $A_s \cup B_t = G'$, hence by additivity $\sigma(A_s) + \sigma(B_t) = d$. It follows that $\sum_{i=1}^{s-1} \sigma(A_i) + \sum_{i=1}^{t-1} \sigma(B_i) = d$. But the components appearing in this sum are precisely the connected components of $G' \setminus T$, and the marked points on these connected components are the same as those on the components of $G \setminus \{v\}$. Thus $v \in \mathcal{Z}$.

Finally, we note that $\mathcal{Z}(G) \neq G$ for each G , since otherwise the specialization property proved above would imply that the graph with one vertex corresponding to a smooth curve is in \mathcal{Z} , which is clearly not the case. \square

Consequently, by Theorem 5.3, there is a moduli space $\overline{M}_{0,n}(\mathcal{Z}_{\gamma, \vec{c}})$ of $\mathcal{Z}_{\gamma, \vec{c}}$ -stable curves and a morphism $\overline{M}_{0,n} \rightarrow \overline{M}_{0,n}(\mathcal{Z}_{\gamma, \vec{c}})$ contracting all the assigned components.

Theorem 5.6. *Let $(\gamma, \vec{c}) \in \Delta^\circ$ be a linearization admitting no strictly semistable points. Then*

$$U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d+1) \cong \overline{M}_{0,n}(\mathcal{Z}_{\gamma, \vec{c}}).$$

Moreover, a curve is GIT-stable if and only if it is $\mathcal{Z}_{\gamma, \vec{c}}$ -stable.

Proof. Because of the assumption that there are no strictly semistable points, $U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d+1)$ is a stable modular compactification of $M_{0,n}$. It therefore suffices to show that the map $\overline{M}_{0,n} \rightarrow U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d+1)$ from Theorem 1.2 contracts precisely the components in $\mathcal{Z}_{\gamma, \vec{c}}$. This morphism factors through the GIT quotient $\overline{M}_{0,n}(\mathbb{P}^d, d) // \mathrm{SL}(d+1)$, so we may think of it as assigning to each curve $(X, p_1, \dots, p_n) \in \overline{M}_{0,n}$ an equivalence class of a map $\varphi : X \rightarrow \mathbb{P}^d$. For any subcurve $E \subset X$, $\deg \varphi|_E$ is independent of the choice of representative φ . Now, let $\pi : X \rightarrow \hat{X}$ be the $\mathcal{Z}_{\gamma, \vec{c}}$ -stable contraction. If $Y \subset X$ is a tail, then $\pi(Y)$ is either a tail or $\sigma(Y) = 0$. Hence, for any component $E \subset X$, if $\sum_{Y \subset \overline{X \setminus E}} \sigma(Y) = d$, then $\sum_{Y \subset \overline{\hat{X} \setminus \pi(E)}} \sigma(Y) = d$ as well. It follows from Corollary 3.6 that $\varphi|_E$ must have degree 0 and hence E is contracted. Conversely, if $\sum_{Y \subset \overline{X \setminus E}} \sigma(Y) \neq d$, then since $\deg \varphi(X) = d$, $\varphi|_E \neq 0$ and hence E is not contracted. We therefore see that the extremal assignment corresponding to $U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d+1)$ is precisely $\mathcal{Z}_{\gamma, \vec{c}}$. By [Smy09], the corresponding coarse moduli spaces must be isomorphic.

Moreover, by the above any representative map φ factors through π :

$$\begin{array}{ccc} X & & \\ \downarrow \pi & \searrow \varphi & \\ \hat{X} & \longrightarrow & \mathbb{P}^d. \end{array}$$

It follows that every $\mathcal{Z}_{\gamma, \vec{c}}$ -stable curve can be embedded in \mathbb{P}^d as an element of $U_{d,n}^{ss}$. Since there are no strictly semistable points, all of the orbits are closed in the semistable locus. Hence, for a curve $Y \in U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d+1)$, every lift of Y to $U_{d,n}^{ss}$ is isomorphic to every other lift. By the properness of $\overline{M}_{0,n}(\mathcal{Z}_{\gamma, \vec{c}})$, one of these lifts is $\mathcal{Z}_{\gamma, \vec{c}}$ -stable, hence they all must be. \square

6. MAPS BETWEEN MODULI SPACES

In this section we describe maps between the various different quotients of $U_{d,n}$. The gluing maps are related to known maps defined on $\overline{M}_{0,n}$. The projection and VGIT maps, on the other hand, form a large set of explicit maps that do not appear previously in the literature.

6.1. Gluing Maps. The first maps we consider are helpful for understanding the boundary of these moduli spaces. Recall that each of

the boundary divisors in $\overline{M}_{0,n}$ corresponds to a subset $I \subset [n]$ with $|I| = i, 2 \leq i \leq \frac{n}{2}$. Each such divisor D_I is the image of a gluing map:

$$\overline{M}_{0,i+1} \times \overline{M}_{0,n-i+1} \rightarrow \overline{M}_{0,n}.$$

In this section we describe a natural analogue of these gluing maps for the GIT quotients $U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d+1) \cong \overline{M}_{0,n}(\mathcal{Z}_{\gamma, \vec{c}})$.

Proposition 6.1. *Let $(\gamma, \vec{c}) \in \Delta^\circ$ be such that there are no strictly semistable points, and let $I \subset [n]$ be a subset such that $\sigma(I) \neq 0, d$ and write $i = |I|$. We write \vec{c}_I for the vector consisting of the weights c_i for all $i \in I$. Then there is a commutative “gluing” diagram:*

$$\begin{array}{ccc} \overline{M}_{0,i+1} \times \overline{M}_{0,n-i+1} & \longrightarrow & \overline{M}_{0,n} \\ \downarrow & & \downarrow \\ \overline{M}_{0,i+1}(\mathcal{Z}_{\gamma, \vec{c}_I, b_I}) \times \overline{M}_{0,n-i+1}(\mathcal{Z}_{\gamma, \vec{c}_{I^c}, b_{I^c}}) & \xrightarrow{\Gamma_i} & \overline{M}_{0,n}(\mathcal{Z}_{\gamma, \vec{c}}) \end{array}$$

where $b_I = (1 - \gamma)\sigma(I) - (c_I - 1) + \gamma$. Similarly, if $\sigma(I) = d$, then there is a commutative diagram:

$$\begin{array}{ccc} \overline{M}_{0,i+1} \times \overline{M}_{0,n-i+1} & \longrightarrow & \overline{M}_{0,n} \\ \downarrow & & \downarrow \\ \overline{M}_{0,i+1}(\mathcal{Z}_{\gamma, \vec{c}_I, b_I}) & \xrightarrow{\Gamma_i} & \overline{M}_{0,n}(\mathcal{Z}_{\gamma, \vec{c}}). \end{array}$$

Moreover, the horizontal maps are all injective.

Proof. Let

$$\begin{aligned} (X_I, p_1, \dots, p_i, q) &\in \overline{M}_{0,i+1} \\ (X_{I^c}, p_{i+1}, \dots, p_n, q') &\in \overline{M}_{0,n-i+1} \end{aligned}$$

be two Deligne-Mumford stable curves. By Theorem 5.6, there is a map $f : X_I \cup_{q=q'} X_{I^c} \rightarrow \mathbb{P}^d$ whose image is a $\mathcal{Z}_{\gamma, \vec{c}}$ -stable curve. By Proposition 3.5, $f(X_I)$ spans a projective space of dimension $\sigma(I)$. It therefore suffices to show that $f(X_I)$ is a $\mathcal{Z}_{\gamma, \vec{c}_I, b_I}$ -stable curve. If X_I has only one component, this is clear, so suppose that X_I has at least two components and let $Y \subset X_I$ be a tail. We will write σ_I for the σ function with respect to the linearization (γ, \vec{c}_I, b_I) . Note that if $q \notin Y$, then Y is also a tail of X and $\sigma(Y) = \sigma_I(Y)$. If $q \in Y$, then $\overline{X_I \setminus Y}$ is also a tail, so by Lemma 3.3 we have

$$\begin{aligned} \deg(f(Y)) &= d - \sigma(I^c) - \sigma(\overline{X_I \setminus Y}) \\ &= \sigma(I) - \sigma(\overline{X_I \setminus Y}) = \sigma(I) - \sigma_I(\overline{X_I \setminus Y}) = \sigma_I(Y). \end{aligned}$$

We therefore see that all of the tails of $f(X_I)$ have the correct degree, so $f(X_I)$ is a $\mathcal{Z}_{\gamma, \vec{c}_I, b_I}$ -stable curve. \square

Remark 6.2. We would like to conclude more strongly that the gluing maps are all embeddings, which would follow if the varieties in question were all normal. Several of the results below about maps between these GIT quotients could be similarly strengthened using normality. We note here that, since the map $\overline{M}_{0,n} \rightarrow \overline{M}_{0,n}(Z_{\gamma,\vec{c}})$ has connected fibers, the normalization map $\overline{M}_{0,n}(Z_{\gamma,\vec{c}})^\nu \rightarrow \overline{M}_{0,n}(Z_{\gamma,\vec{c}})$ is bijective. Although we strongly suspect that it is indeed an isomorphism, at present we have no proof.

6.2. Projection Maps. Another natural set of maps between these moduli spaces is given by projection from the marked points.

Proposition 6.3. *Let $(\gamma, \vec{c}) \in \Delta^\circ$ be such that there are no strictly semistable points, and suppose that $d \geq 2$ and $c_1 > 1 - \gamma$. Then projection from p_1 defines a birational morphism*

$$\pi_i : U_{d,n} //_{(\gamma,\vec{c})} \mathrm{SL}(d+1) \rightarrow U_{d-1,n} //_{(\gamma,c_1-(1-\gamma),c_2,\dots,c_n)} \mathrm{SL}(d).$$

Proof. First, note that since $c_1 > 1 - \gamma$, every GIT-stable curve is smooth at p_1 by Corollary 2.6. It follows that, if (X, p_1, \dots, p_n) is a GIT-stable curve, then its projection $\pi_{p_1}(X, p_1, \dots, p_n)$ is a connected rational curve of degree $d - 1$ in \mathbb{P}^{d-1} . We show that this projected curve is stable for the linearization $(\gamma, c_1 - (1 - \gamma), c_2, \dots, c_n)$ if and only if the original curve is stable for the linearization $(\gamma, c_1, \dots, c_n)$. Indeed, every component of $\pi_{p_1}(X)$ has the same degree as its preimage, unless its preimage contains p_1 , in which case the degree drops by one. It follows that, for any tail $Y \subset \pi_{p_1}(X)$, we have

$$\deg(Y) = \begin{cases} \left\lceil \frac{(\sum_{p_i \in Y} c_i) - 1}{1 - \gamma} \right\rceil & \text{if } p_1 \notin Y \\ \left\lceil \frac{(\sum_{p_i \in Y} c_i) - (1 - \gamma) - 1}{1 - \gamma} \right\rceil & \text{if } p_1 \in Y \end{cases}$$

But this is exactly the condition for stability of points in $U_{d-1,n}$ for the linearization $(\gamma, c_1 - (1 - \gamma), c_2, \dots, c_n)$. \square

Proposition 6.4. *The projection map π_1 is a bijective morphism if and only if, for every partition $\{2, \dots, n\} = I_1 \sqcup \dots \sqcup I_k$ into at least 3 disjoint sets, we have $\sum_{i=1}^k \sigma(I_i) \neq d - 1$.*

Proof. Let $E \subset X$ be a component of a GIT-stable curve with respect to the linearization (γ, \vec{c}) . E is contracted by the projection map if and only if $p_1 \in E$ and $\deg E = 1$. It follows that the map is bijective if and only if every such component has no moduli, which is equivalent to every such component having exactly three special points, where here a “special point” is either a singular point (regardless of the singularity type) or a marked point (regardless of how many of the p_i ’s collide at that point). By Corollary 3.6, we therefore see that π_1 is a bijective morphism if and only if the hypothesis holds. \square

6.3. Wall-Crossing Maps. One of the benefits of our GIT approach is that, by varying the choice of linearization, we obtain explicit maps between our moduli spaces. The nature of these maps can be understood using the general theory of variation of GIT.

Recall that, by Proposition 3.9, the GIT walls in Δ° are of the form $\varphi(I, \cdot)^{-1}(k)$ for any given subset $I \subset [n]$ and integer k . For a fixed such I and k , we let $(\gamma, \vec{c}) \in \varphi(I, \cdot)^{-1}(k) = \varphi(I^c, \cdot)^{-1}(d - 1 - k)$ be such that (γ, \vec{c}) does not lie on any other walls, and we write

$$U_{d,n} //_{I,k,0} \mathrm{SL}(d + 1) := U_{d,n} //_{\gamma, \vec{c}} \mathrm{SL}(d + 1).$$

Similarly, we will write $U_{d,n} //_{I,k,+} \mathrm{SL}(d + 1)$ and $U_{d,n} //_{I,k,-} \mathrm{SL}(d + 1)$ for the GIT quotients corresponding to the neighboring chambers, which are contained in $\varphi(I, \cdot)^{-1}(\{x > k\})$ and $\varphi(I, \cdot)^{-1}(\{x < k\})$, respectively. We will write σ_+, σ_- for the σ functions on either side of the wall. Note that, for any subset $A \subset [n]$, $\sigma_+(A) = \sigma_-(A)$ if and only if $A \neq I, I^c$. By general VGIT, there is a commutative diagram:

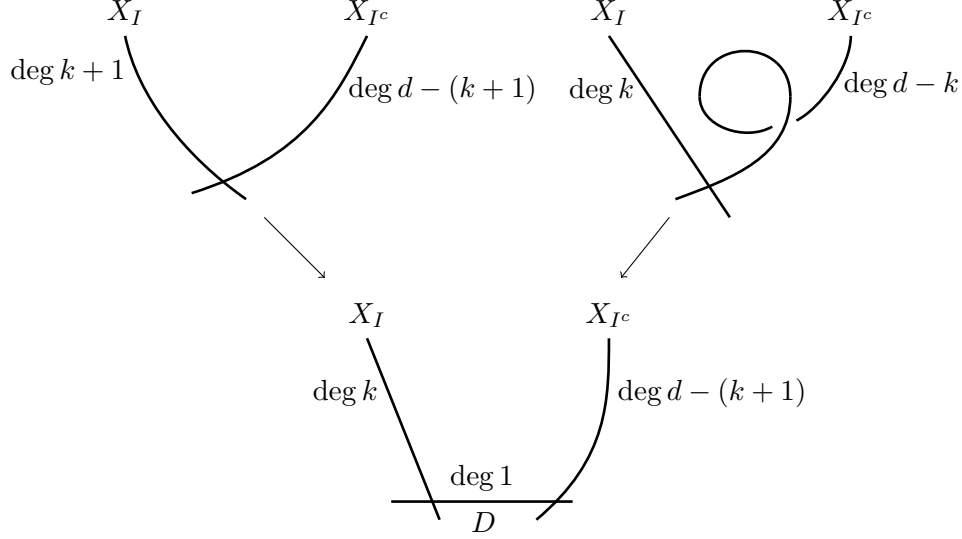
$$\begin{array}{ccc} U_{d,n} //_{I,k,+} \mathrm{SL}(d + 1) & \dashrightarrow & U_{d,n} //_{I,k,-} \mathrm{SL}(d + 1) \\ & \searrow & \swarrow \\ & U_{d,n} //_{I,k,0} \mathrm{SL}(d + 1) & \end{array} .$$

We now consider stability conditions at a wall. For these linearizations, a new type of semistable curve appears:

Definition 6.5. A pointed curve $(X, p_1, \dots, p_n) \in U_{d,n}$ is an (I, k) -**bridge** if:

- (1) X has a degree 1 component D such that $|D \cap \overline{X \setminus D}| = 2$;
- (2) If we write X_I, X_{I^c} for the connected components of $\overline{X \setminus D}$, then X_I is marked by the points in I and X_{I^c} is marked by the points in I^c ;
- (3) If $E \subset X_I$ (resp. X_{I^c}) is a connected subcurve, then the degree of E is equal to $d - \sum_Y \sigma_-(Y)$ (resp. $d - \sum_Y \sigma_+(Y)$), where the sum is over all connected components of $X \setminus E$.

Note that, by definition, $\deg(X_I) = k$ and $\deg(X_{I^c}) = d - (k + 1)$, as in the following picture:



Proposition 6.6. *Every (I, k) -bridge is GIT-semistable at the wall $\varphi(I, \cdot)^{-1}(k)$.*

Proof. Let (X, p_1, \dots, p_n) be an (I, k) -bridge. It suffices to construct an $(I, k, +)$ -stable curve (Y, q_1, \dots, q_n) and a 1-PS λ such that

$$\mu_\lambda(Y, q_1, \dots, q_n) = 0 \text{ and}$$

$$\lim_{t \rightarrow 0} \lambda(t) \cdot (Y, q_1, \dots, q_n) = (X, p_1, \dots, p_n).$$

Let $(X_I, p_1, \dots, p_m, p)$ denote the tail of X labeled by points in I , where p is the “attaching point”. Note that, by Proposition 6.1 and the fact that (γ, \vec{c}) does not lie on any walls other than $\varphi(I, \cdot)^{-1}(k)$, X_I is stable for the linearization $(\gamma, c_1, \dots, c_m, \gamma - \epsilon)$. Because the projection map is proper and birational, there is a curve $(Y_I, q_1, \dots, q_m, q)$, stable for the linearization $(\gamma, c_1, \dots, c_m, 1 - \epsilon)$, such that $\pi_q(Y_I) = X_I$.

Choose coordinates so that the span of Y_I is $V(x_{k+2}, \dots, x_d)$ and $q = V(x_0, \dots, x_k, \widehat{x_{k+1}}, x_{k+2}, \dots, x_d)$. Now, let λ be the 1-PS that acts with weights $(0, \dots, 0, 1, \dots, 1)$, where the first $k + 1$ weights are all zero. Let $i : Y_I \hookrightarrow \mathbb{P}^d$ be the inclusion and consider the rational map

$$U := \mathbb{C} \times Y_I \dashrightarrow \mathbb{P}^d$$

given by $(t, r) \mapsto \lambda(t) \cdot i(r)$. Note that this map is regular everywhere except the point $(0, q)$. If we blow-up U at this point, we obtain a regular map $\tilde{U} \rightarrow \mathbb{P}^d$ whose special fiber is the union of $\pi_q(Y_I) = X_I$ and a line. Since the image of the point q is constant in this family, we may glue on X_{I^c} to obtain a family of connected degree d curves. By Proposition 6.1, $Y = Y_I \cup X_{I^c}$ is an $(I, k, +)$ -stable curve. It follows that (X, p_1, \dots, p_n) is semistable. \square

We will see that the (I, k) -bridges are the only “new” curves that appear at the wall.

Proposition 6.7. *A pointed curve $(X, p_1, \dots, p_n) \in U_{d,n}$ is stable for the linearization $(I, k, 0)$ if and only if it is stable for the linearization $(I, k, +)$ (equivalently, $(I, k, -)$) and does not contain a tail labeled by the points in I or I^c . It is strictly semistable if and only if it contains a tail labeled by the points in I or I^c , and is either $(I, k, +)$ -stable, $(I, k, -)$ -stable, or an (I, k) -bridge. Moreover, the (I, k) -bridges are exactly the strictly semistable curves with closed orbits.*

Proof. We first show that each of the curves above is (semi)stable. It is a standard fact from variation of GIT that, if a curve is stable for both linearizations $(I, k, +)$ and $(I, k, -)$, then it is stable for the linearization $(I, k, 0)$ as well. By assumption, the only wall that (γ, \vec{c}) lies on is $\varphi(I, \cdot)^{-1}(k) = \varphi(I^c, \cdot)^{-1}(d - 1 - k)$, so any curve that does not contain a tail labeled by the points in I will be stable for one of these linearizations if and only if it is stable for the other. Similarly, if a curve is stable for either linearization $(I, k, +)$ or $(I, k, -)$, then it is semistable for the linearization $(I, k, 0)$. It therefore suffices to show that (I, k) -bridges are GIT-semistable, but this was shown in Proposition 6.6.

To see the converse, let $(X, p_1, \dots, p_n) \in U_{d,n}$ be semistable for the linearization $(I, k, 0)$. Notice that the degree of each tail $Y \subset X$ is completely determined by σ unless Y is labeled by points in I or I^c . We therefore see that, if X contains no tails labeled by points in I or I^c , then for any connected subcurve $E \subset X$ we have

$$\deg(E) = d - \sum \sigma(Y)$$

and (X, p_1, \dots, p_n) is an $(I, k, +)$ -stable curve. Similarly, suppose that X contains a subcurve E such that $\overline{X \setminus E}$ contains a connected component X_I labeled by I but no connected component labeled by I^c . Then the degree of X_I is either k or $k + 1$, and thus either

$$\deg(E) = d - k - \sum \sigma(Y)$$

or

$$\deg(E) = d - (k + 1) - \sum \sigma(Y)$$

where the sum is over all connected components $Y \subset \overline{X \setminus E}$ other than X_I . Notice that, if X also contains a tail labeled by the points in I^c , but there is no subcurve separating these two tails, then the degree of the latter tail is precisely $d - \deg(X_I)$. It follows that (X, p_1, \dots, p_n) is either $(I, k, +)$ -stable or $(I, k, -)$ -stable.

The remaining case is where X contains a component E such that $\overline{X \setminus E}$ contains a connected component X_I labeled by the points in I

and a connected component X_{I^c} labeled by the points in I^c . Since $\deg X_I \geq k + 1$, $\deg X_{I^c} \geq d - (k + 1)$, and $\deg E \geq 1$, we see that the only possibility is if all three inequalities hold. Thus, E is a degree 1 subcurve of X such that $|E \cap \overline{X \setminus E}| = 2$, and (X, p_1, \dots, p_n) is an (I, k) -bridge.

Finally, note that if a semistable curve does not have a closed orbit, then it degenerates to a semistable curve with higher-dimensional stabilizer. Furthermore, a strictly semistable curve with closed orbit cannot have a 0-dimensional stabilizer. Since (I, k) -bridges have 1-dimensional stabilizers and all other semistable curves have 0-dimensional stabilizers, we see that the (I, k) -bridges must be precisely the strictly semistable curves with closed orbits. \square

We can restate the results of Proposition 6.7 in the following way. Each of the maps in the diagram

$$\begin{array}{ccc} U_{d,n} //_{I,k,+} \mathrm{SL}(d+1) & \xleftarrow{\hspace{10em}} & U_{d,n} //_{I,k,-} \mathrm{SL}(d+1) \\ & \searrow & \swarrow \\ & U_{d,n} //_{I,k,0} \mathrm{SL}(d+1) & \end{array}$$

restricts to an isomorphism away from the image of $D_I \subset \overline{M}_{0,n}$. If $k \neq 0, d - 1$, then along the image of this divisor, the maps restrict to the following:

$$\begin{array}{ccc} \overline{M}_{0,i+1}(\mathcal{Z}_\gamma, \vec{c}_I, 1-\epsilon) \times \overline{M}_{0,n-i+1}(\mathcal{Z}_\gamma, \vec{c}_{I^c}, \gamma+\epsilon) & \xrightarrow{\Gamma_i} & U_{d,n} //_{I,k,+} \mathrm{SL}(d+1) \\ \downarrow (\pi_{i+1}, id) & & \downarrow \\ \overline{M}_{0,i+1}(\mathcal{Z}_\gamma, \vec{c}_I, \gamma+\epsilon) \times \overline{M}_{0,n-i+1}(\mathcal{Z}_\gamma, \vec{c}_{I^c}, \gamma+\epsilon) & \longrightarrow & U_{d,n} //_{I,k,0} \mathrm{SL}(d+1) \\ \uparrow (id, \pi_{n-i+1}) & & \uparrow \\ \overline{M}_{0,i+1}(\mathcal{Z}_\gamma, \vec{c}_I, \gamma+\epsilon) \times \overline{M}_{0,n-i+1}(\mathcal{Z}_\gamma, \vec{c}_{I^c}, 1-\epsilon) & \xrightarrow{\Gamma_i} & U_{d,n} //_{I,k,-} \mathrm{SL}(d+1) \end{array}$$

where the central map is obtained by gluing a line between the attaching points.

Similarly, if $k = d - 1$, the maps restrict to:

$$\begin{array}{ccc} \overline{M}_{0,i+1}(\mathcal{Z}_\gamma, \vec{c}_I, 1-\epsilon) & \xrightarrow{\Gamma_i} & U_{d,n} //_{I,k,+} \mathrm{SL}(d+1) \\ \downarrow \pi_{i+1} & & \downarrow \\ \overline{M}_{0,i+1}(\mathcal{Z}_\gamma, \vec{c}_I, \gamma+\epsilon) & \longrightarrow & U_{d,n} //_{I,k,0} \mathrm{SL}(d+1) \\ \uparrow (id, \cdot) & & \uparrow \\ \overline{M}_{0,i+1}(\mathcal{Z}_\gamma, \vec{c}_I, \gamma+\epsilon) \times \overline{M}_{0,n-i+1}(\mathcal{Z}_\gamma, \vec{c}_{I^c}, 1-\epsilon) & \xrightarrow{\Gamma_i} & U_{d,n} //_{I,k,-} \mathrm{SL}(d+1). \end{array}$$

6.4. Quotients at the Boundary of Δ° .

Corollary 6.8. *Suppose that $c_1 = 1 - \epsilon$ for $\epsilon \ll 1$. Then the GIT wall-crossing map is equal to the projection map:*

$$\begin{array}{ccc}
 U_{d,n} //_{\gamma, c_1, \dots, c_n} \mathrm{SL}(d+1) & & \\
 \downarrow & \searrow^{\pi_1} & \\
 U_{d,n} //_{\gamma-\epsilon, 1, c_2, \dots, c_n} \mathrm{SL}(d+1) & \xrightarrow{\cong} & U_{d-1,n} //_{\gamma, 1-\gamma, c_2, \dots, c_n} \mathrm{SL}(d)
 \end{array}$$

Proof. Note that the boundary wall $c_1 = 1$ is equal to the hyperplane $\varphi(\{1\}, \cdot)^{-1}(0)$. Let X be a $(\{1\}, 0, -)$ -stable curve. By Proposition 6.6, we see that there is a $(\{1\}, 0)$ -semistable curve with closed orbit consisting of the projected curve $\pi_1(X)$ together with a degree 1 tail L containing p_1 and attached at $\pi(p_1)$. Since the points of the GIT quotient are in bijection with the closed orbits of semistable points, we see that this map is exactly the projection map. \square

Proposition 6.9. *When $\gamma = 1$, we have the following isomorphism:*

$$U_{d,n} //_{1, \vec{c}} \mathrm{SL}(d+1) \cong (\mathbb{P}^1)^n //_{\vec{c}} \mathrm{SL}(2).$$

Proof. By Corollary 2.8, every GIT-stable curve is smooth, and by Corollary 2.6, at most half of the total weight may collide at a marked point. We therefore have a map

$$U_{d,n} //_{1, \vec{c}} \mathrm{SL}(d+1) \rightarrow (\mathbb{P}^1)^n //_{\vec{c}} \mathrm{SL}(2).$$

On the other hand, by Proposition 4.7 there is a map $f : \overline{M}_{0,n} \rightarrow U_{d,n} //_{1, \vec{c}} \mathrm{SL}(d+1)$ that factors through each of the maps

$$\overline{M}_{0,n} \rightarrow \overline{M}_{0, \vec{c}'} \rightarrow U_{d,n} //_{1, \vec{c}} \mathrm{SL}(d+1)$$

for every weight vector $\vec{c}' > \vec{c}$. It follows that f factors through the direct limit, which is $(\mathbb{P}^1)^n //_{\vec{c}} \mathrm{SL}(2)$. \square

With Corollary 6.8 and Proposition 6.9, we now have a complete description of all of the boundary walls of the GIT cone Δ° . If $c_i = 1$ for some i , then the wall-crossing map corresponds to a projection map. If $\gamma = 1$, then the quotient is isomorphic to $(\mathbb{P}^1)^n //_{\vec{c}} \mathrm{SL}(2)$. On the other hand, if $c_i = 0$ for some i , then the wall-crossing map corresponds to a forgetful map, whereas if $\gamma = 0$, the quotient is isomorphic to the spaces $V_{d,n} //_{\vec{c}} \mathrm{SL}(d+1)$ studied in [Gia10].²

²In the latter two statements, the line bundles in question are only semi-ample rather than ample, and hence by Mumford’s definition the corresponding GIT quotients are quasi-projective rather than projective. If, however, one defines the GIT quotient to be Proj of the invariant section ring, then these statements are fine.

6.5. Behavior of Wall-Crossing Maps. By the above diagram, we also have a nice description of wall-crossing behavior along the interior walls.

Corollary 6.10. *The rational map*

$$U_{d,n} //_{I,k,+} \mathrm{SL}(d+1) \dashrightarrow U_{d,n} //_{I,k,-} \mathrm{SL}(d+1)$$

contracts a divisor if and only if $3 \leq |I| \leq n-2$ and $k=0$. Its inverse contracts a divisor if and only if $2 \leq |I| \leq n-3$ and $k=d-1$.

Proof. This follows directly from the diagram above. Because the map restricts to an isomorphism away from the image of $D_{I,I^c} \subset \overline{M}_{0,n}$, the only divisor that could be contracted by the map is the image of this divisor. In the diagram above, however, which details the restriction of this map to this divisor, all of the maps are birational unless $k=0$ and $3 \leq |I| \leq n-2$ or $k=d-1$ and $2 \leq |I| \leq n-3$. \square

Corollary 6.11. *If $k \neq 0, d-1$, then the rational map*

$$U_{d,n} //_{I,k,+} \mathrm{SL}(d+1) \dashrightarrow U_{d,n} //_{I,k,-} \mathrm{SL}(d+1)$$

is either regular, its inverse is regular, or it is a flip.

Proof. Consider the diagram:

$$\begin{array}{ccc} U_{d,n} //_{I,k,+} \mathrm{SL}(d+1) & \dashrightarrow & U_{d,n} //_{I,k,-} \mathrm{SL}(d+1) \\ & \searrow f^+ & \swarrow f^- \\ & U_{d,n} //_{I,k,0} \mathrm{SL}(d+1) & \end{array} .$$

If f^+ (resp. f^-) is an isomorphism, then the composition $(f^+)^{-1} \circ f^-$ (resp. $(f^-)^{-1} \circ f^+$) is regular. Otherwise by Theorem 3.3 in [Tha96], it suffices to show that f^+ and f^- are both small contractions. But again, this is clear from the gluing diagram above. \square

Because of Corollary 6.11, it is interesting to ask when the wall-crossing map is regular. Although we are unable to answer this question at present, we can provide a condition for the map to contract no curves. If the GIT quotients were normal, this would be sufficient to conclude that the inverse map is regular in precisely this case (see Remark 6.2).

Proposition 6.12. *The rational map*

$$U_{d,n} //_{I,k,+} \mathrm{SL}(d+1) \dashrightarrow U_{d,n} //_{I,k,-} \mathrm{SL}(d+1)$$

contracts no curves if and only if, for every partition $I = I_1 \sqcup \cdots \sqcup I_m$ into at least 3 disjoint sets, we have $\sum_{i=1}^m \sigma(I_i) \neq k$.

Proof. By the diagrams above, the map f^+ is bijective if and only if the projection map

$$\overline{M}_{0,n-i+1}(\mathcal{Z}_{\gamma,\vec{c}_I,1-\epsilon}) \rightarrow \overline{M}_{0,n-i+1}(\mathcal{Z}_{\gamma,\vec{c}_I,\gamma+\epsilon})$$

is bijective. By Proposition 6.4, this is the case if and only if, for every partition $I = I_1 \sqcup \cdots \sqcup I_m$ into at least 3 disjoint sets, we have $\sum_{i=1}^m \sigma(I_i) \neq k$. It follows that the composite rational map $(f^-)^{-1} \circ f^+$ contracts no curves in precisely this case. \square

7. EXAMPLES

In this section we consider examples of the quotients $U_{d,n} //_{\gamma,\vec{c}} \mathrm{SL}(d+1)$ for specific choices of $(\gamma, \vec{c}) \in \Delta$. We will see that many previously constructed compactifications of $M_{0,n}$ arise as such quotients.

7.1. Hassett's Spaces. In [Has03], Hassett constructs the moduli spaces of weighted pointed stable curves $\overline{M}_{0,\vec{c}}$. A genus 0 marked curve (X, p_1, \dots, p_n) is Hassett stable if:

- (1) The singularities are at worst nodal;
- (2) There are no marked points at nodes;
- (3) The weight at any smooth point is at most 1, and
- (4) $\omega_X(\sum_{i=1}^n c_i p_i)$ is ample.

Here we show that each of Hassett's spaces arises as a quotient of $U_{d,n}$.

Theorem 7.1. *Let (γ, \vec{c}) be a linearization such that there are no strictly semistable points and $1 > \gamma > \max\{\frac{1}{2}, 1 - c_1, \dots, 1 - c_n\}$. Then there is an isomorphism $\overline{M}_{0,\vec{c}} \cong U_{d,n} //_{(\gamma,\vec{c})} \mathrm{SL}(d+1)$.*

Proof. It is enough to prove the existence of a morphism $U_{d,n} //_{(\gamma,\vec{c})} \mathrm{SL}(d+1) \rightarrow \overline{M}_{0,\vec{c}}$ preserving the interior. Indeed, both sides are separated, so such a morphism is automatically inverse to the morphism in Proposition 4.7.

We claim that the hypotheses imply that the universal family over the semistable locus $(U_{d,n})^{\mathrm{ss}}$ is a family of Hassett-stable curves for the weight vector \vec{c} . Indeed,

- The singularities are at worst nodal, by Corollary 2.7 and the assumption $\gamma > \frac{1}{2}$;
- There are no marked points at nodes, by Proposition 2.5 and the fact that $\gamma > 1 - c_i$ for $i = 1, \dots, n$;
- The weight at any smooth point is at most 1, by Corollary 2.6; and
- The ampleness condition of Hassett-stability is satisfied.

The only item here that needs explanation is the last one. Hassett-stability, in genus zero, requires that the weight of marked points on

any component, plus the number of nodes on that component, is strictly great than 2. This follows by the same argument as Proposition 3.7.

Having shown that we have a family of Hassett-stable curves over the semistable locus, the representability of this moduli space implies that we have a morphism $(U_{d,n})^{ss} \rightarrow \overline{M}_{0,\vec{c}}$. This is clearly $\mathrm{SL}(d+1)$ -invariant, so it descends to a morphism from the categorical quotient, which is precisely the GIT quotient: $U_{d,n} //_{(\gamma,\vec{c})} \mathrm{SL}(d+1) \rightarrow \overline{M}_{0,\vec{c}}$. The interior $M_{0,n}$ is clearly preserved, so this concludes the proof. \square

Corollary 7.2. *Every Hassett space, including $\overline{M}_{0,n}$, is a quotient of $U_{d,n}$ for a fixed value of d .*

Proof. Note that there is a chamber structure on the space of weight data ([Has03, Section 5]). Chambers are separated by hyperplanes

$$\{(c_1, \dots, c_n) \mid \sum_{i \in I} c_i = 1\}$$

for some $I \subset \{1, 2, \dots, n\}$. Therefore we can find $\epsilon > 0$ satisfying the following property: For any weight data \vec{c} , there is a weight data \vec{c}' in the same chamber and $c'_i > \epsilon$ for all i . Now we can take d satisfying $\frac{d+1-n}{d-1} > 1 - \epsilon$. Then this d satisfies

$$1 > \frac{d+1-c}{d-1} \geq \frac{d+1-n}{d-1} > 1 - \epsilon \geq \max\left\{\frac{1}{2}, 1 - c'_1, \dots, 1 - c'_n\right\},$$

for every weight datum \vec{c}' . \square

We note the following fact, which was remarked in the introduction:

Corollary 7.3. *There exists $L \in \Delta^\circ$ with $U_{n-2,n} //_L \mathrm{SL}(n-1) \cong \overline{M}_{0,n}$.*

Proof. The Hassett space $\overline{M}_{0,\vec{c}}$ with $\vec{c} = (\frac{1}{2} + \epsilon, \dots, \frac{1}{2} + \epsilon)$ is isomorphic to $\overline{M}_{0,n}$ (in fact they have the same universal curves) since no points are allowed to collide. Thus, it suffices to take a linearization $(\gamma, \vec{c}) \in \Delta^\circ$ with $\gamma > \frac{1}{2}$. Now, $\gamma = \frac{d+1-(\frac{n}{2}+n\epsilon)}{d-1}$, so $\gamma > \frac{1}{2}$ is equivalent to $d > n - 2n\epsilon - 3$, so indeed for ϵ small enough we can take $d = n - 2$. \square

7.2. Kontsevich-Boggi compactification. In [Kon92], Kontsevich described certain topological modifications of the moduli spaces $\overline{M}_{g,n}$ which for $g = 0$ were given an algebraic description by Boggi as an alternate compactification of $\overline{M}_{0,n}$ [Bog99]. This compactification was later independently constructed by Smyth in [Smy09]. A genus 0 marked curve (X, p_1, \dots, p_n) is *Boggi-stable* if:

- (1) The singularities are multinodal;
- (2) There are no marked points at the singular points;
- (3) There are at least two points on any tail, and
- (4) There are no unmarked components.

The Boggi space corresponds to the extremal assignment in which all components without marked points are assigned. We will see that the Boggi space also arises as a quotient of $U_{d,n}$, in the case $d = n$, $c_i = 1 - \epsilon \forall i$. Note that in this case $\gamma = \frac{1+d\epsilon}{d-1}$.

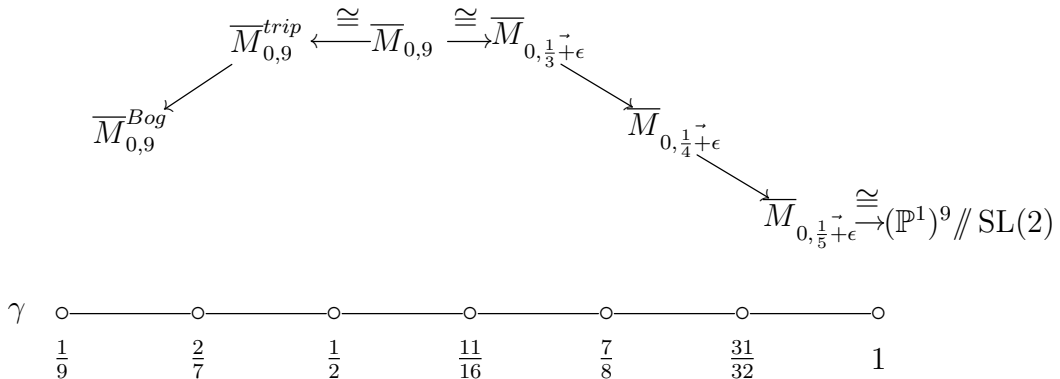
Proposition 7.4. *The GIT quotient $U_{d,n} //_{\frac{1+d\epsilon}{d-1}, 1-\epsilon} \mathrm{SL}(d+1)$ is isomorphic to the Boggi space $\overline{M}_{0,n}^{Bog}$.*

Proof. Let $(X, p_1, \dots, p_n) \in \overline{M}_{0,n}$ be a Deligne-Mumford stable curve. It suffices to show that a component of X is $\mathcal{Z}_{\frac{1+d\epsilon}{d-1}, 1-\epsilon}$ -assigned if and only if it is unmarked. Let $Y \subset X$ be a tail containing k marked points. Then

$$\sigma(Y) = \lceil \frac{k(1-\epsilon) - 1}{1-\gamma} \rceil = k.$$

Hence, for any component $E \subset X$, E is assigned if and only if the total number of points on the connected components of $\overline{X} \setminus E$ is equal to $d = n$. In other words, E is assigned if and only if it is unmarked. \square

7.3. Variation of GIT. In addition to previously constructed moduli spaces, our GIT approach also recovers known maps between these moduli spaces. As an example we consider the case where $n = d = 9$ and the weights are symmetric – that is, $c_i = c_j \forall i, j$. By the results above, we see that $U_{9,9} //_{\gamma, \vec{c}} \mathrm{SL}(10)$ is isomorphic to a Hassett space for all $\gamma > \frac{1}{2}$, and isomorphic to the Boggi space for $\frac{1}{9} < \gamma < \frac{2}{7}$. In the range $\frac{2}{7} < \gamma < \frac{1}{2}$, the space $\overline{M}_{0,9}^{trip} = U_{9,9} //_{\gamma, \vec{c}} \mathrm{SL}(10)$ is isomorphic to $\overline{M}_{0,9}$, but the corresponding moduli functor is different. Specifically, a curve consisting of three components meeting in a triple point, each containing three marked points, is GIT-stable, while the corresponding Deligne-Mumford stable curve obtained by replacing the triple point with a rational triborough is not GIT-stable. We note furthermore that since all of the moduli spaces just described are normal, the corresponding wall-crossing maps are all regular by Proposition 6.12. As we increase γ from $\frac{1}{9}$ to 1, we therefore obtain the following picture:



7.4. An Example of a Flip. While the previous example includes several previously constructed spaces, it does not include any flips. To see an example of a flip, we consider the case where $d = 5, n = 19$, and the weights are symmetric. Let I_k denote any set of k marked points. When $\gamma = \frac{4}{9} + \epsilon$, we see that

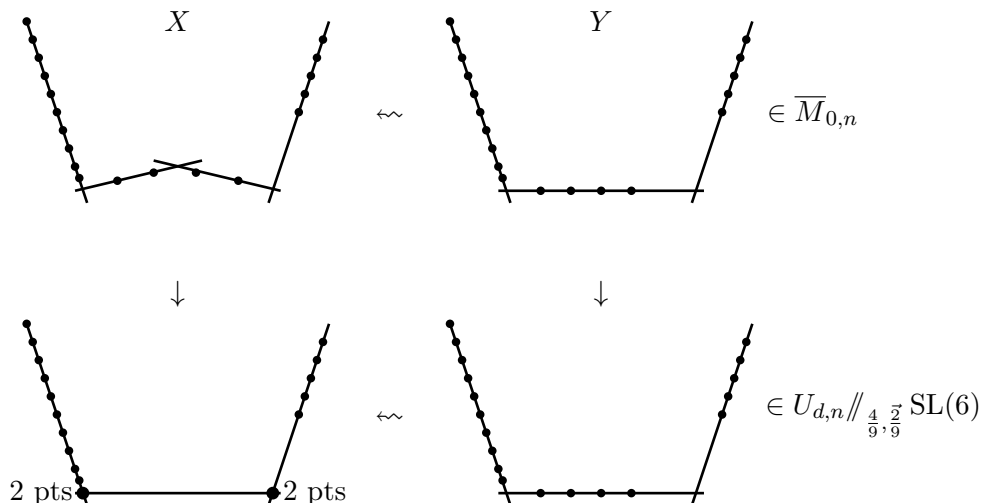
$$\sigma(I_k) = \begin{cases} 0 & \text{if } k \leq 4 \\ 1 & \text{if } 5 \leq k \leq 7 \\ 2 & \text{if } 8 \leq k \leq 9 \\ 3 & \text{if } 10 \leq k \leq 11 \\ 4 & \text{if } 12 \leq k \leq 14 \\ 5 & \text{if } 15 \leq k \end{cases}$$

On the other hand, when $\gamma = \frac{4}{9} - \epsilon$, then each of these remains the same, except for $\sigma(I_7)$ which becomes 2, and $\sigma(I_{12})$, which becomes 3. Now, consider the diagram

$$\begin{array}{ccc} U_{5,19} //_{\frac{4}{9} + \epsilon, \frac{2}{9} - \epsilon} \text{SL}(6) & \overset{\dots\dots\dots}{\longleftrightarrow} & U_{5,19} //_{\frac{4}{9} - \epsilon, \frac{2}{9} + \epsilon} \text{SL}(6) \\ & \searrow f^+ \quad \swarrow f^- & \\ & U_{5,19} //_{\frac{4}{9}, \frac{2}{9}} \text{SL}(6) & \end{array} .$$

By Corollary 6.10, neither f^+ nor f^- contracts a divisor. On the other hand, the map f^+ contracts the F-curve $(10, 7, 1, 1)$, whereas the map f^- contracts the F-curve $(12, 5, 1, 1)$, so neither f^+ nor f^- is trivial. It follows from Corollary 6.11 that the diagram is a flip.

Finally we note that the moduli space $U_{5,19} //_{\frac{4}{9}, \frac{2}{9}} \text{SL}(6)$ is not isomorphic to a modular compactification as in [Smy09]. In this sense it is truly a “new” compactification of $M_{0,19}$. To see this, consider the Deligne-Mumford stable curve X which is a chain of 4 rational curves, each component containing 10, 2, 2, and 5 marked points, respectively. The image of X in the GIT quotient has three components. These components have 10, 0, and 5 marked points on their interiors, and there are 2 marked points at each of the nodes – the two interior components of X are contracted. On the other hand, the original curve is a specialization of a Deligne-Mumford stable curve Y consisting of 3 components, containing 10, 4, and 5 marked points, respectively. Hence, if this space were modular, then by [Smy09] the interior component of Y would have to be contracted as well. But we see that this is not the case.



7.5. Modular compactifications not from GIT. In the above subsection we saw an example of a GIT compactification of $M_{0,n}$ which is not modular in the sense of [Smy09]. On the other hand, there are also examples of modular compactifications which do not arise from our GIT construction. For instance, consider a partition $[n] = I \sqcup J \sqcup K$ into three nonempty subsets. It is easy to see that assigning a tail if and only if the marked points on it are indexed entirely by I or entirely by J yields an extremal assignment. Suppose this assignment is given by a geometric quotient of $U_{d,n}$. If a tail has only two marked points, p_{i_1}, p_{i_2} , both indexed by I , then by Proposition 3.5 we have $\sigma(\{i_1, i_2\}) = 0$ and so $c_{i_1} + c_{i_2} < 1$. Similarly, considering a tail with two points p_{j_1}, p_{j_2} both indexed by J forces $c_{i_1} + c_{i_2} < 1$. Without loss of generality write $c_{i_1} \leq c_{i_2}$ and $c_{j_1} \leq c_{j_2}$. Then $c_{i_1} + c_{j_1} < 1$, so $\sigma(\{i_1, j_1\}) = 0$, and hence a tail with only p_{i_1} and p_{j_1} would be contracted, contradicting the definition of the extremal assignment.

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