

## CHIP FIRING

### 13. DIVISOR THEORY OF METRIC GRAPHS

We now turn from discrete graphs to metric graphs.

**Definition 13.1.** A metric graph is a compact, connected metric space  $\Gamma$  obtained by identifying the edges of a graph  $G$  with line segments of fixed positive real length. The graph  $G$  is called a model for  $\Gamma$ .

**Example 13.2.** If we assign lengths to the edges of a cycle, we obtain a circle. Thus, the circle is a metric graph.

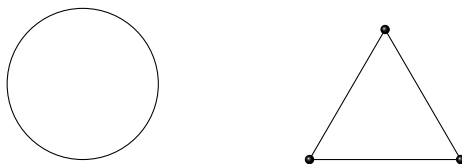


FIGURE 1. A metric graph and one of its models

**Remark 13.3.** A metric graph  $\Gamma$  does not have a unique model. Two graphs are models for the same metric graph if and only if they admit a common refinement.

**Definition 13.4.** The divisor group  $\text{Div}(\Gamma)$  of a metric graph  $\Gamma$  is the free abelian group on points of the metric space  $\Gamma$ .

Many properties of divisors can be defined in a way that is completely analogous to the discrete graph case.

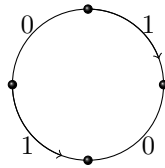
**Definition 13.5.** A divisor  $D = \sum a_i v_i$  on a metric graph is effective if  $a_i \geq 0$  for all  $i$ . Its degree is defined to be

$$\deg(D) := \sum a_i.$$

As in the case of discrete graphs, we want to talk about equivalence of divisors. For this, we need a notion of rational functions on metric graphs.

**Definition 13.6.** A rational function on a metric graph  $\Gamma$  is a continuous, piecewise linear function  $\varphi : \Gamma \rightarrow \mathbb{R}$  with integer slopes. We write  $\text{PL}(\Gamma)$  for the group of rational functions on  $\Gamma$ .

**Example 13.7.** Figure 2 indicates the domains of linearity and slopes of a rational function  $\varphi$  on a circle. It therefore determines the rational function up to translation.

FIGURE 2. The domains of linearity and slopes of  $\varphi$ 

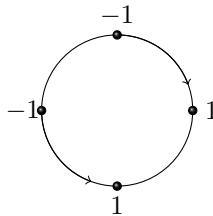
Note that, in order for the function to be continuous, the two regions on which the function has slope 1 must be of equal length.

**Definition 13.8.** Given  $\varphi \in \text{PL}(\Gamma)$  and  $v \in \Gamma$ , we define the order of vanishing of  $\varphi$  at  $v$ ,  $\text{ord}_v(\varphi)$ , to be the sum of the incoming slopes of  $\varphi$  at  $v$ . Note that  $\text{ord}_v(\varphi)$  is nonzero for only finitely many points  $v \in \Gamma$ . We define the divisor associated to  $\varphi$  to be

$$\text{div}(\varphi) = \sum_{v \in \Gamma} \text{ord}_v(\varphi) \cdot v.$$

Divisors of the form  $\text{div}(\varphi)$  are called principal.

**Example 13.9.** The divisor associated to the rational function of Example 13.7 is pictured in Figure 3. Note that  $\text{div}(\varphi)$  is equal to  $\text{div}(\varphi + c)$  for any real number  $c$ . This is analogous to the fact that, on an algebraic curve, the divisor associated to a rational function is invariant under scaling the function by a non-zero constant. Indeed, we have the following.

FIGURE 3. The principal divisor  $\text{div} \varphi$ 

**Lemma 13.10.** Let  $\Gamma$  be a metric graph and let  $\varphi, \psi \in \text{PL}(\Gamma)$ . We have  $\text{div}(\varphi) = \text{div}(\psi)$  if and only if there exists a constant  $c$  such that  $\varphi = \psi + c$ .

*Proof.* First, if  $\varphi = \psi + c$ , then  $\varphi$  and  $\psi$  have the same slope along every tangent vector of  $\Gamma$ . It follows that  $\text{ord}_v(\varphi) = \text{ord}_v(\psi)$  for all  $v \in \Gamma$ , hence  $\text{div}(\varphi) = \text{div}(\psi)$ .

Conversely, if  $\text{div}(\varphi) = \text{div}(\psi)$ , then

$$\text{div}(\varphi - \psi) = \text{div}(\varphi) - \text{div}(\psi) = 0.$$

It therefore suffices to show that, if  $\phi \in \text{PL}(\Gamma)$  satisfies  $\text{div}(\phi) = 0$ , then  $\phi$  is constant. To see this, consider the set  $A \subseteq \Gamma$  where  $\phi$  obtains its minimum. Since  $\Gamma$  is compact,

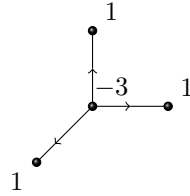


FIGURE 4. A rational function that is constant outside a local neighborhood, and its associated divisor  
bottom

the set  $A$  is nonempty. For any point  $v$  in the boundary of  $A$ , we have  $\text{ord}_v(\phi) < 0$ . Thus, if  $\text{div}(\phi) = 0$ , the boundary of  $A$  must be empty. Since  $\Gamma$  is connected, this implies that  $A = \Gamma$ , so  $\phi$  is constant.  $\square$

**Example 13.11.** On any metric graph  $\Gamma$ , given a point  $v \in \Gamma$ , let  $\epsilon \in \mathbb{R}$  be sufficiently small so that the open ball  $B_\epsilon(v)$  contains no points of valence greater than 2 other than possibly  $v$ . Let  $\chi$  be the rational function that takes the value  $\epsilon$  on  $\Gamma \setminus B_\epsilon(v)$ , the value 0 at  $v$ , and has slope 1 on the edges in  $B_\epsilon(v)$  emanating from  $v$ . Then  $\chi$  has order of vanishing  $-\text{val}(v)$  at  $v$  and 1 at each of the boundary points of  $B_\epsilon(v)$ . In this way, we can view addition of  $\text{div}(\chi)$  as a continuous version of chip firing, where we specify not only the vertex  $v$  that we fire from, but also the distance  $\epsilon$  that we fire the chips.

We note the following.

**Lemma 13.12.** *The degree of a principal divisor is zero.*

*Proof.* Let  $\varphi \in \text{PL}(\Gamma)$ , and let  $G$  be a model for  $\Gamma$  such that  $\varphi$  is linear on every edge of  $G$ . In other words,  $V(G)$  contains the support of  $\text{div}(\varphi)$ . For every edge  $e$  of  $G$ , let  $s_e$  denote the slope of  $\varphi$  along  $e$ . We see that the incoming slope of  $\varphi$  at one endpoint of  $e$  is  $s_e$ , and the incoming slope of  $\varphi$  at the other endpoint is  $-s_e$ . It follows that

$$\deg(\text{div}(\varphi)) = \sum_{v \in V(G)} \text{ord}_v(\varphi) = \sum_{e \in E(G)} [s_e - s_e] = 0.$$

$\square$

Now that we have a notion of principal divisors on metric graphs, we can use it to define equivalence of divisors.

**Definition 13.13.** *We say that two divisors  $D$  and  $D'$  on a metric graph  $\Gamma$  are equivalent if  $D - D'$  is principal. We define the Picard group of  $\Gamma$  to be the group of equivalence classes of divisors on  $\Gamma$ . That is,*

$$\text{Pic}(\Gamma) = \text{Div}(\Gamma) / \text{div}(\text{PL}(\Gamma)).$$

*The Jacobian  $\text{Jac}(\Gamma)$  of  $\Gamma$  is the group of equivalence classes of divisors of degree zero.*

The rank of a divisor on a metric graph is defined in exactly the same way as on a discrete graph. Since this definition is crucial to our interests, we record it here.

**Definition 13.14.** *Given  $D \in \text{Div}(\Gamma)$ , the complete linear series of  $D$  is*

$$|D| := \{D' \sim D \mid D' \geq 0\}.$$

*The rank of  $D$  is the largest integer  $r$  such that  $|D - E| \neq \emptyset$  for all effective divisors  $E$  of degree  $r$ .*

See the paper of Haase–Musiker–Yu for details on the structure of  $|D|$ .