EXPECTATION MAXIMIZATION

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The Expectation Maximization (EM) algorithm [1, 2] is one of the most widely used algorithms in statistics. Suppose we are given some observed data X and a model family parametrized by θ , and would like to find the θ which maximizes $p(X|\theta)$, i.e. the maximum likelihood estimator. The basic idea of EM is actually quite simple: when direct maximization of $p(X|\theta)$ is complicated we can augment the data X by introducing some "hidden variable" Z such that

$p(X, Z|\theta)$

can be computed easily (for example when you observe both X and Z it can be easily maximized with respect to θ).

GENERAL DERIVATION

Suppose we have a guess of the parameter value θ^t and want to find θ such that $p(X|\theta) \ge p(X|\theta^t)$. This can be done by considering the difference between *observed-data* log-likelihood

$$\Delta L = L(\theta) - L(\theta^t) = \log \frac{p(X|\theta)}{p(X|\theta^t)}$$

Now we introduce the hidden variable Z such that $p(X, Z|\theta)$ is easy to compute (usually in a product form so that $\log p(X, Z|\theta)$ can be factorized). We have

$$\begin{split} L(\theta) - L(\theta^{t}) &= \log \frac{\int p(X, Z|\theta) dZ}{p(X|\theta^{t})} \\ &= \log \left[\int \frac{p(Z|\theta^{t}, X)}{p(Z|\theta^{t}, X)} \frac{p(X, Z|\theta)}{p(X|\theta^{t})} dZ \right] \\ &\geq \int \left[p(Z|\theta^{t}, X) \log \frac{p(X, Z|\theta)}{p(Z|\theta^{t}, X)p(X|\theta^{t})} \right] dZ \\ &\stackrel{\triangle}{=} \underline{\Delta} L(\theta; \theta^{t}). \end{split}$$

where the last inequality is due to Jensen's inequality and the fact that log(.) is concave. Note that equivalently we have $L(\theta) \ge L(\theta^t) + \underline{\Delta}L(\theta; \theta^t)$, which says that $L(\theta^t) + \underline{\Delta}L(\theta; \theta^t)$ is a global lower bound of $L(\theta)$ for any θ . Consequently we can maximize $\underline{\Delta}L(\theta; \theta^t)$ wrt θ to obtain θ^{t+1} , and as long as $\underline{\Delta}L(\theta^{t+1}; \theta^t) \ge 0$ we have $L(\theta^{t+1}) \ge L(\theta^t)$ (and verify that $\underline{\Delta}L(\theta^t; \theta^t) = 0$).

Now back to the problem of maximizing $\underline{\Delta}L(\theta; \theta^t)$ wrt θ :

$$\begin{aligned} \theta^{t+1} &= \arg \max_{\theta} \underline{\Delta} L(\theta; \theta^t) \\ &= \arg \max_{\theta} \int \left[p(Z|\theta^t, X) \log \frac{p(X, Z|\theta)}{p(Z|\theta^t, X) p(X|\theta^t)} \right] dZ \\ &= \arg \max_{\theta} \int p(Z|\theta^t, X) \log p(X, Z|\theta) dZ. \end{aligned}$$

Define

$$Q(\theta; \theta^t) \stackrel{\triangle}{=} \int p(Z|\theta^t, X) \log p(X, Z|\theta) dZ = \mathbb{E}_{Z|\theta^t, X}[\log p(X, Z|\theta)].$$

Finally we derived the EM algorithm:

- *E-step*: compute $Q(\theta; \theta^t)$, which is the **expectation** of *complete-data* log-likelihood log $p(X, Z|\theta^t)$ and the expectation is wrt $p(Z|\theta^t, X)$.
- *M-step*: maximize $Q(\theta; \theta^t)$ wrt θ to obtain θ^{t+1} .

MIXTURE OF NORMAL DISTRIBUTIONS

We now apply EM to fit a mixture of two normal distributions. Suppose we observe x_1, \ldots, x_n from a mixture of normal distributions

$$p(x) = \lambda N(\mu_1, \sigma_1^2) + (1 - \lambda) N(\mu_2, \sigma_2^2).$$

So in our case the observed data is $\{x_1, \ldots, x_n\}$ and the $\theta = \{\lambda, \mu_1, \sigma_1^2, \mu_2, \sigma_2^2\}$. We introduce hidden variables Z_1, \ldots, Z_n where $Z_i = 0$ if x_i comes from the first mixture component and 1 otherwise. The complete-data log-likelihood can be written down easily as (due to our introduction of hidden variables):

$$\log p(x_i, z_i | \theta) = \log \left\{ \left[\lambda \frac{1}{\sqrt{2\pi\sigma_1}} \exp\left(-\frac{(x_i - \mu_1)^2}{2\sigma_1^2}\right) \right]^{z_i} \left[(1 - \lambda) \frac{1}{\sqrt{2\pi\sigma_2}} \exp\left(-\frac{(x_i - \mu_2)^2}{2\sigma_2^2}\right) \right]^{1 - z_i} \right\}$$

= $z_i \log \left[\lambda \frac{1}{\sqrt{2\pi\sigma_1}} \exp\left(-\frac{(x_i - \mu_1)^2}{2\sigma_1^2}\right) \right] + (1 - z_i) \log \left[(1 - \lambda) \frac{1}{\sqrt{2\pi\sigma_2}} \exp\left(-\frac{(x_i - \mu_2)^2}{2\sigma_2^2}\right) \right]$

and $Q(\theta; \theta^t)$ can be written as (for simplicity we discard constants and group parameters together):

$$\begin{aligned} Q(\theta; \theta^{t}) &= \mathbb{E}\left[\sum_{i=1}^{n} \left(z_{i} \log \lambda + (1-z_{i}) \log(1-\lambda)\right)\right] + \mathbb{E}\left[\sum_{i=1}^{n} \left(-z_{i} \log \sigma_{1} - (1-z_{i}) \log \sigma_{2}\right)\right] \\ &+ \mathbb{E}\left[\sum_{i=1}^{n} \left(-z_{i} \frac{(x_{i}-\mu_{1})^{2}}{2\sigma_{1}^{2}} - (1-z_{i}) \frac{(x_{i}-\mu_{2})^{2}}{2\sigma_{2}^{2}}\right)\right] \\ &= \sum_{i=1}^{n} \left(\mathbb{E}[z_{i}] \log \lambda - (1-\mathbb{E}[z_{i}]) \log(1-\lambda)\right) + \sum_{i=1}^{n} \left(-\mathbb{E}[z_{i}] \log \sigma_{1} - (1-\mathbb{E}[z_{i}]) \log \sigma_{2}\right) \\ &+ \sum_{i=1}^{n} \left(-\mathbb{E}[z_{i}] \frac{(x_{i}-\mu_{1})^{2}}{2\sigma_{1}^{2}} - (1-\mathbb{E}[z_{i}]) \frac{(x_{i}-\mu_{2})^{2}}{2\sigma_{2}^{2}}\right). \end{aligned}$$

Define $m_i^1 = \mathbb{E}[z_i]$ and $m_i^2 = 1 - \mathbb{E}[z_i]$ and we first work out the M-step assuming that we already know m_i^1, m_i^2 's (which depend on the value of θ^t). By maximizing $Q(\theta; \theta^t)$ wrt θ we have

$$\lambda^{t+1} = \frac{1}{n} \sum_{i=1}^{n} m_i^1$$

$$\mu_j^{t+1} = \frac{\sum_{i=1}^{n} m_i^j x_i}{\sum_{i=1}^{n} m_i^j}, \quad (j = 1, 2)$$

$$\sigma_j^{t+1} = \frac{\sum_{i=1}^{n} m_i^j (x_i - \mu_j^{t+1})^2}{\sum_{i=1}^{n} m_i^j}, \quad (j = 1, 2)$$

Note that the M-step makes perfect sense if we split each x_i into two particles, the first comes from mixture component one with weight m_i^1 , etc. The quantity $m_i^1 = \mathbb{E}[z_i]$ which is needed in the E-step can be computed as

$$\mathbb{E}[z_i] = 1 \cdot p(z_i = 1 | \theta^t, x_1, \dots, x_n) + 0 \cdot p(z_i = 0 | \theta^t, x_1, \dots, x_n)$$

=
$$\frac{p(x_i, z_i = 1 | \theta^t)}{p(x_i, z_i = 0 | \theta^t) + p(x_i, z_i = 1 | \theta^t)}$$

=
$$\frac{\lambda^t N(x_i | \mu_1^t, (\sigma_1^t)^2)}{\lambda^t N(x_i | \mu_1^t, (\sigma_1^t)^2) + (1 - \lambda^t) N(x_i | \mu_2^t, (\sigma_2^t)^2)}.$$

To extend the idea to a mixture of m distributions we can introduce hidden variables $z_{i,j}$ with i = 1, ..., nand j = 1, ..., m. Define $z_{ij} = 1$ if x_i is generated from the *j*-th mixture component and 0 otherwise. The rest follows straightforwardly.

EM in the Exponential Family

Let X be the observed data and Z be the hidden variable [2]. Suppose the augmented data Y = (X, Z) are distributed as

$$p(Y|\theta) = \frac{b(Y)}{a(\theta)} \exp(\theta^T s(Y))$$

i.e. the regular exponential family, where $\theta \in \mathbb{R}^d$ is the parameter vector and $s(Y) \in \mathbb{R}^d$ is the vector of sufficient statistics.

The $Q(\theta; \theta^t)$ can be written as

$$Q(\theta; \theta^t) = \int p(Z|\theta^t, X) \log p(X, Z|\theta) dZ$$

=
$$\int p(Z|\theta^t, X) \log b(Y) dZ + \theta^T \int p(Z|\theta^t, X) s(Y) dZ - \log a(\theta).$$

Notice that the first term does not depend on θ and thus can be thrown away. So the E-step reduces to just compute the *expected sufficient statistics*

$$\mathbb{E}_{Z|\theta^t, X}[S(Y)] \stackrel{\triangle}{=} \mathbf{s}$$

In the M-step we maximize $\theta^T \mathbf{s} - \log a(\theta)$, where $a(\theta) = \int b(Y) \exp(\theta^T s(Y)) dY$. Compute the derivative wrt θ and set it to zero we have

$$\mathbb{E}_{Y|\theta}[S(Y)] = \int p(X, Z|\theta) S(Y) dY = \mathbf{s}.$$

In other words, the M-step is reduced to find the root θ^{t+1} of the above equation.

EM GENERALIZATIONS

There are many ways to generalize the standard EM algorithm, and here we just mention a few.

Generalized M-step.

Sometimes it may be difficult or expensive to find $\theta^{t+1} = \arg \max Q(\theta; \theta^t)$. Since all we need is to find θ^{t+1} such that $Q(\theta; \theta^t) \ge Q(\theta^t, \theta^t) = 0$, we may use an easy or cheap method to just maximize $Q(\theta; \theta^t)$ approximately. Note that this change usually results in more iterations to converge and may not slow down your algorithm especially when E-step is expensive to compute.

Generalized E-step.

In practice the E-step is often more complicated than the M-step, and sometimes the exact E-step is difficult to obtain. Recall that in the derivation of EM we have

$$L(\theta) - L(\theta^t) = \log \frac{\int p(X, Z|\theta) dZ}{p(X|\theta^t)} = \log \left[\int \frac{p(Z|\theta^t, X)}{p(Z|\theta^t, X)} \frac{p(X, Z|\theta)}{p(X|\theta^t)} dZ \right] \ge \int \left[p(Z|\theta^t, X) \log \frac{p(X, Z|\theta)}{p(Z|\theta^t, X)p(X|\theta^t)} \right] dZ$$

In fact in order for the Jensen's inequality to hold we can replace $p(Z|\theta^t, X)$ with any valid distribution $q(Z|\gamma)$ in the above derivation. Thus we have

$$L(\theta) - L(\theta^t) = \log\left[\int \frac{q(Z|\gamma)}{q(Z|\gamma)} \frac{p(X,Z|\theta)}{p(X|\theta^t)} dZ\right] \ge \int \left[q(Z|\gamma)\log\frac{p(X,Z|\theta)}{q(Z|\gamma)p(X|\theta^t)}\right] dZ \stackrel{\triangle}{=} \underline{\Delta}L_{q(.|\gamma)}(\theta,\theta^t)$$

Note also that when $q(Z|\gamma)$ is the true posterior $p(Z|\theta, X)$ the above bound is exact. So the generalized EM works as follows:

- E-step: compute the expectation of complete-data log-likelihood log $p(X, Z|\theta)$ where the expectation is wrt $q(Z|\gamma)$. You want to use a distribution $q(Z|\gamma)$ which is a good approximation¹ to $p(Z|\theta^t, X)$.
- M-step: maximize $Q_{q(\cdot|\gamma)}(\theta; \theta^t) = \mathbb{E}_{q(Z|\gamma)}[\log p(X, Z|\theta)]$ to obtain θ^{t+1} .

¹This can be done, for example, by choosing its parameter γ in some parametric family $q(.|\gamma) \in \mathcal{F}$.

Monte Carlo E-step.

Instead of computing $Q(\theta; \theta^t) = \mathbb{E}_{Z|\theta^t, X}[\log p(X, Z|\theta)]$, one may apply the method of Monte Carlo [2] to approximate the Q function. In particular, the Monte Carlo E-step can be computed as:

- (1) Draw $z_1, \ldots, z_m \stackrel{iid}{\sim} p(Z|\theta^t, X).$ (2) Let $\hat{Q}(\theta; \theta^t) = \frac{1}{m} \sum_{j=1}^m \log p(X, z_j|\theta).$

References

- [1] Dempster, A., Laird, N. and Rubin, D. Maximum likelihood from incomplete data via the EM algorithm. Journal of the Royal Statistical Society, 39 (Series B), 1-38, 1977.
- [2] Martin A. Tanner. Tools for Statistical Inference, 3rd edition. Springer, 1996.