# COMPUTATION OF THE EMPIRICAL LIKELIHOOD RATIO FROM CENSORED DATA 

Kun Chen and Mai Zhou ${ }^{1}$<br>Bayer Pharmaceuticals and University of Kentucky

SUMMARY

The empirical likelihood ratio method is a general nonparametric inference procedure that has many desirable properties. Recently, the procedure has been generalized to several settings including testing of weighted means with right censored data. However, the computation of the empirical likelihood ratio with censored data and other complex settings is often non-trivial. We propose to use a sequential quadratic programming (SQP) method to solve the computational problem. We introduce several auxiliary variables so that the computation of SQP is greatly simplified. Examples of the computation with null hypothesis concerning the weighted mean are presented for right and interval censored data.

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## 1. Introduction

The empirical likelihood ratio method was first proposed by Thomas and Grunkemeier (1975). Owen $(1988,1990,1991)$ and many others developed this into a general methodology. It has many desirable statistical properties, see Owen's recent book (2001). A crucial step in computing the empirical likelihood ratio, i.e. the Wilks statistic, is to find the maximum of the log empirical likelihood (LEL) function under some constraints. The Wilks statistic is just two times the difference of two such LEL functions maximized under different constraints. In all the papers mentioned above, this is achieved by using the Lagrange multiplier method. It reduces the maximization of empirical likelihood over $n-1$ variables to solving a set of $r$ equations, $f(\lambda)=0$, for the $r$-dimensional multiplier $\lambda$. The number $r$ is fixed as the sample size $n$ grows. Furthermore, the functions $f$ are monotone in each of the $r$ coordinates. These equations can easily be solved numerically and thus the empirical likelihood ratio can be obtained.

Recently, the empirical likelihood ratio method has been generalized to several more complicated settings. For example, Pan and Zhou (1999) showed that for right censored data, the

[^0]empirical likelihood ratio can also be used to test hypotheses about a weighted mean. Murphy and Van der Vaart (1997) demonstrated, among other things, that Wilks' theorem for the empirical likelihood ratio also holds for doubly censored data.

However, computation of the censored data empirical likelihood ratio in these settings remains difficult, as the Lagrange multiplier simplification is not available (see example 1). Unlike the Owen (1988) paper, the proofs of Wilks' theorem for the censored empirical likelihood ratio contained in Pan and Zhou (1999) and Murphy and van der Vaart (1997) do not offer a viable computational method. They provide existence proofs rather than constructive proofs. Therefore, a study of computational methods that can find the relevant empirical likelihood ratios numerically when analyzing censored data is needed.

Example 1 Suppose i.i.d. observations $X_{1}, \cdots, X_{n}$ with an unknown CDF $F_{X}(t)$ are subject to right censoring so that we only observe

$$
\begin{equation*}
Z_{i}=\min \left(X_{i}, C_{i}\right) ; \quad \delta_{i}=I_{\left[X_{i} \leq C_{i}\right]}, \quad i=1,2, \ldots, n \tag{1}
\end{equation*}
$$

where $C_{1}, \cdots, C_{n}$ are censoring times, assumed independent of $X_{1}, \cdots, X_{n}$.
The log empirical likelihood (LEL) function based on the censored observations $\left(Z_{i}, \delta_{i}\right)$ is

$$
\begin{equation*}
L E L(\mathbf{w})=\sum_{i=1}^{n}\left[\delta_{i} \log w_{i}+\left(1-\delta_{i}\right) \log \left(\sum_{Z_{j}>Z_{i}} w_{j}\right)\right] \tag{2}
\end{equation*}
$$

where $w_{i}=F_{X}\left(Z_{i}\right)-F_{X}\left(Z_{i}-\right)$.
The empirical likelihood ratio test is based on Wilks' statistic

$$
\begin{aligned}
-2 \log R\left(H_{0}\right) & =-2 \log \frac{\max _{H_{0}} E L(\mathbf{w})}{\max _{H_{0}+H_{1}} E L(\mathbf{w})} \\
& =2\left[\log \left(\max _{H_{0}+H_{1}} E L(\mathbf{w})\right)-\log \left(\max _{H_{0}} E L(\mathbf{w})\right)\right] \\
& =2[\log (L(\tilde{\mathbf{w}}))-\log (L(\hat{\mathbf{w}}))]=2[L E L(\tilde{\mathbf{w}})-L E L(\hat{\mathbf{w}})]
\end{aligned}
$$

Here, $\tilde{\mathbf{w}}$ is the nonparametric maximum likelihood estimate (NPMLE) of probabilities without any constraint, $\hat{\mathbf{w}}$ is the NPMLE of probabilities under the $H_{0}$ constraint.

To compute Wilks' statistic for testing a hypothesis about a weighted mean of $X$, we need to find the maximum of the above LEL under the constraints

$$
\sum_{i=1}^{n} w_{i} Z_{i} \delta_{i}=\mu, \quad \sum_{i=1}^{n} w_{i} \delta_{i}=1, \quad w_{i} \geq 0
$$

where $\mu$ is a given constant, specified by the null hypothesis. While the asymptotic null distribution of the test statistic can be shown to be a chi- squared with 1 degree of freedom; a straight application of the Lagrange multiplier method does not lead to a simple solution. The same difficulty arises also with doubly censored data and other censoring cases. Thus a viable computation algorithm for the maximization of the empirical likelihood ratio is needed.

We propose to use the sequential quadratic programming (SQP) method to find the constrained maximum. In particular, we show how one can introduce several auxiliary variables so that the computation of SQP for censored empirical likelihood is greatly simplified. In fact, this trick can be used to compute empirical likelihood ratios in many other cases (for example, doubly or interval censored data) where a simple Lagrange multiplier computation is not available.

We briefly review the SQP method in section 2. We show how to use the SQP method to compute the maximum of the LEL function in section 3. Examples and simulations are given in section 4.

## 2. The Sequential Quadratic Programming Method

There is a large amount of literature on nonlinear programming methods, see for example Nocedal and Wright (1999) and references there. The general strictly convex (positive definite) quadratic programming problem is to minimize

$$
\begin{equation*}
f(\mathbf{x})=-\mathbf{a}^{T} \mathbf{x}+\frac{1}{2} \mathbf{x}^{T} \mathbf{G} \mathbf{x} \tag{3}
\end{equation*}
$$

subject to

$$
\begin{equation*}
s(\mathbf{x})=\mathbf{C}^{T} \mathbf{x}-\mathbf{b} \geq \mathbf{0}, \tag{4}
\end{equation*}
$$

where $\mathbf{x}$ and $\mathbf{a}$ are $n$-vectors, $\mathbf{G}$ is an $n \times n$ symmetric positive definite matrix, $\mathbf{C}$ is an $n \times m(m<$ $n$ ) matrix, $\mathbf{b}$ is an $m$-vector, and a superscript $T$ denotes the transpose. In this paper, the vector $\mathbf{x}$ is only subject to equality constraints $\mathbf{C}^{T} \mathbf{x}-\mathbf{b}=\mathbf{0}$. This makes the QP problem easier. In the next section we shall show how to introduce a few new variables in the maximization of the censored LEL (2) so that the matrix $\mathbf{G}$ is always diagonal, which further simplifies the computation. Therefore, instead of using a general QP algorithm, we have implemented our own version in R which takes advantage of the mentioned simplifications. The specific QP problem can be solved by performing one matrix QR decomposition, one backward solve, and one forward solve of equations.

Since all our constraints are equality constraints, one way to solve the minimization problem (3) is to use (yet again) the Lagrange multiplier:

$$
\min _{x, \eta}-\mathbf{a}^{T} \mathbf{x}+\frac{1}{2} \mathbf{x}^{T} \mathbf{G} \mathbf{x}-\eta^{T}\left[\mathbf{C}^{T} \mathbf{x}-\mathbf{b}\right]
$$

where $\eta$ is a column vector of length $m$. Taking the derivative with respect to $\mathbf{x}$ and setting it equal to zero, we get $\mathbf{G x}-\mathbf{a}-\mathbf{C} \eta=\mathbf{0}$. We can solve $\mathbf{x}$ in terms of $\eta$ to get

$$
\begin{equation*}
\mathbf{x}=\mathbf{G}^{-1}[\mathbf{a}+\mathbf{C} \eta] . \tag{5}
\end{equation*}
$$

Since the matrix $\mathbf{G}$ is diagonal, the inverse $\mathbf{G}^{-1}$ is easy to obtain. Finally, we need to solve for $\eta$. Substituting (5) into $\mathbf{C}^{T} \mathbf{x}=\mathbf{b}$, we get $\mathbf{C}^{T}\left(\mathbf{G}^{-1}[\mathbf{a}+\mathbf{C} \eta]\right)=\mathbf{b}$, which is, upon rewriting,

$$
\begin{equation*}
\mathbf{C}^{T} \mathbf{G}^{-1} \mathbf{C} \eta=\mathbf{b}-\mathbf{C}^{T} \mathbf{G}^{-1} \mathbf{a} . \tag{6}
\end{equation*}
$$

Once we get the solution $\eta$ from (6) we can substitute it back into (5) above to calculate $\mathbf{x}$.
One way to solve (6) is to use QR decomposition. If $\mathbf{C}^{T} \mathbf{G}^{-1 / 2}=\mathbf{R Q}$ then (6) can be rewritten as

$$
\begin{gather*}
\left(\mathbf{R Q Q}^{T} \mathbf{R}^{T}\right) \eta=\mathbf{b}-\mathbf{R Q G}^{-1 / 2} \mathbf{a} \\
\left(\mathbf{R R}^{T}\right) \eta=\mathbf{b}-\mathbf{R Q G}^{-1 / 2} \mathbf{a} \\
\mathbf{R}^{T} \eta=\mathbf{R}^{-1} \mathbf{b}-\mathbf{Q G}^{-1 / 2} \mathbf{a} \tag{7}
\end{gather*}
$$

Equation (7) can be solved by using back-substitution (twice) and one matrix-vector multiplication, which are numerically low cost operations.

We are interested in maximizing LEL, or minimizing the negative LEL over all possible probabilities. This is a nonlinear programming problem. Since it is hard to find a minimum of the negative LEL directly in many cases, and the negative LEL is often convex at least near the minimum, we use a quadratic function to approximate it. Starting from an initial probability $\mathbf{w}^{0}$, we replace the nonlinear target function (negative LEL) with a quadratic function that has the same first and second derivatives at $\mathbf{w}^{0}$. The QP method is used to find the minimum of the quadratic function subject to the same constraints. Denote the location of the minimum by $\mathbf{w}^{1}$. Then, we update the quadratic approximation which now has the same first and second derivatives as the negative LEL at $\mathbf{w}^{1}$. The QP method is used again to find the minimum of the new quadratic function under the same constraints. Iteration ends when a predefined convergence criterion is satisfied. The convergence criterion can be based on the values of the
negative LEL, which should decrease at each iteration. When the value of the negative LEL no longer decreases, we stop the iteration.

One way to improve convergence and guarantee that the negative LEL decreases at each iteration is the technique of damping: write the updated value of the solution as $\mathbf{x}^{(s)}=\mathbf{x}^{(s-1)}+\mathbf{x}$, we shall only accept $\mathbf{x}^{(s)}$ if it decreases the negative LEL, otherwise we shall search along the line $\mathbf{x}_{\xi}^{(s)}=\mathbf{x}^{(s-1)}+\xi \mathbf{x}$ for $0 \leq \xi<1$ until it decreases the negative LEL value.

When the information matrix (of the LEL) is positive, the quadratic approximation is good at least in a neighborhood of the true MLE. Thus, in case of convergence, the solution gives the correct MLE under the given constraints.

## 3. Empirical Likelihood Maximization with Right Censored Data

We now describe the SQP method that solves the problem in Example 1. The implementations for doubly censored data and interval censored data are similar. We only give the details for right censored data here.

For right-censored data as in (1), the LEL is given in (2). It is well known that the maximizer of the LEL has the following property: $w_{i}>0$ only when the corresponding $\delta_{i}=1$. We shall restrict the search of a maximizer for the LEL under the mean constraint to those $w_{i}$ 's. See Owen (1988) p. 238 for a discussion on this type of restriction.

We describe below two ways to implement the SQP method for finding the constrained MLE.
The first implementation of QP would simply take the $\mathbf{w}$ in (2) as $\mathbf{x}$. The knowledge of $w_{i}=0$ when $\delta_{i}=0$ helps to reduce the number of variables to $k$ (number of uncensored data). The length of the vector $\mathbf{a}$ is $k$ and the matrix $\mathbf{G}$ is $k \times k$. The second derivative matrix $\mathbf{G}$ in the quadratic approximation is dense and the computation of the inverse/QR decomposition is very expensive numerically.

A second and better way to use the SQP with censored data will introduce some auxiliary variables $R_{l}=P\left(Z \geq Z_{l}\right)$, one for each censored observation, this enlarges the dimension of the vectors ( $\mathbf{a}, \mathbf{x}, \mathbf{b}$ ) and the matrices $(\mathbf{G}, \mathbf{C})$ in (3) and (4), but simplifies the matrix $\mathbf{G}$. In fact, $\mathbf{G}$ will be diagonal, so that we can directly plug in the inverse of the decomposition matrix of G. This speeds up the computation tremendously.

We illustrate the two methods for the problem described in Example 1. In method one, since $w_{i}>0$ only when the corresponding $\delta_{i}=1$, we would separate the observations into two
groups: $Z_{1}<\cdots<Z_{k}$ for those with $\delta=1$ and $Z_{1}^{*}<\cdots<Z_{n-k}^{*}$ for those with $\delta=0$. The first derivative of the $\log$ empirical likelihood function is:

$$
\frac{\partial L E L(\mathbf{w})}{\partial w_{i}}=\frac{1}{w_{i}}+\sum_{l=1}^{n-k} \frac{I_{\left[Z_{i}>Z_{l}^{*}\right]}}{\sum_{Z_{j}>Z_{l}^{*}, \delta_{j}=1,1 \leq j \leq k} w_{j}},
$$

Let us denote $M_{l}=\sum_{Z_{j}>Z_{l}^{*}, \delta_{j}=1,1 \leq j \leq k} w_{j}$, then the a vector in the QP problem (3) will be

$$
\mathbf{a}=\left(\frac{1}{w_{1}}+\sum_{l=1}^{n-k} \frac{I_{\left[Z_{1}>Z_{l}^{*}\right]}}{M_{l}}, \frac{1}{w_{2}}+\sum_{l=1}^{n-k} \frac{I_{\left[Z_{2}>Z_{l}^{*}\right]}}{M_{l}}, \cdots, \frac{1}{w_{k}}+\sum_{l=1}^{n-k} \frac{I_{\left[Z_{k}>Z_{l}^{*}\right]}}{M_{l}}\right)^{T}
$$

Taking the second derivative with respect to $w_{i}, i=1,2, \ldots, k$, we have

$$
\frac{\partial^{2} L E L(\mathbf{w})}{\left(\partial w_{i}\right)^{2}}=-\frac{1}{w_{i}^{2}}-\sum_{l=1}^{n-k} \frac{I_{\left[Z_{i}>Z_{l}^{*}\right]}}{M_{l}^{2}},
$$

and for $i \neq q$ :

$$
\frac{\partial^{2} L E L(\mathbf{w})}{\partial w_{i} \partial w_{q}}=-\sum_{l=1}^{n-k} \frac{I_{\left[Z_{i}>Z_{l}^{*}\right]} I_{\left[Z_{q}>Z_{l}^{*}\right]}}{M_{l}^{2}}=\frac{\partial^{2} L E L(\mathbf{w})}{\partial w_{q} \partial w_{i}},
$$

and therefore the matrix $\mathbf{G}$ is given by the negative of those second derivatives.
Finally

$$
\mathbf{x}=\left(\begin{array}{c}
w_{1}-w_{1}^{\star} \\
w_{2}-w_{2}^{\star} \\
\vdots \\
w_{k}-w_{k}^{\star}
\end{array}\right) \quad, \quad \mathbf{C}=\left(\begin{array}{cc}
1 & Z_{1} \\
1 & Z_{2} \\
\vdots & \vdots \\
1 & Z_{k}
\end{array}\right)
$$

We always use an initial value $\mathbf{w}_{0}$ that is a probability, but it may not satisfy the mean constraint. Therefore $\mathbf{b}_{\mathbf{0}}=(0, \mu-\bar{Z})$, where $\bar{Z}=\sum w_{0 i} Z_{i}$. For subsequent iterations we have $\mathbf{b}=(0,0)$ since the current value of $\mathbf{w}$ already satisfies both constraints.

In the second and better SQP implementation, we introduce new variables

$$
R_{l}=R\left(Z_{l}\right)=\sum_{Z_{j}>Z_{l}, \delta_{j}=1,1 \leq j \leq k} w_{j},
$$

one for each right censored observation $Z_{l}$. If we identify $\mathbf{x}$ in (3) as the vector $(\mathbf{w}, \mathbf{R})$, then the log empirical likelihood function (2) becomes

$$
L(\mathbf{x})=L E L(\mathbf{w}, \mathbf{R})=\sum_{i=1, \delta_{i}=1}^{k} \log w_{i}+\sum_{l=1, \delta_{l}=0}^{n-k} \log R_{l}
$$

To find the quadratic approximation of $L(\mathbf{x})$, we need to compute two derivatives. The first derivatives with respect to $(\mathbf{w}, \mathbf{R})$ are

$$
\begin{gathered}
\frac{\partial L E L(w, R)}{\partial w_{i}}=\frac{1}{w_{i}}, \quad i=1,2, \ldots, k \\
\frac{\partial L E L(w, R)}{\partial R_{l}}=\frac{1}{R_{l}}, \quad l=1,2, \ldots, n-k
\end{gathered}
$$

So the vector $\mathbf{a}(n \times 1)$ in the quadratic programming problem (3) becomes much simpler with entries either equal to $\frac{1}{w_{i}}$ or $\frac{1}{R_{l}}$, depending on the censoring status of the observation. The second derivatives of $L$ with respect to $(\mathbf{w}, \mathbf{R})$ are

$$
\begin{aligned}
\frac{\partial^{2} L E L(w, R)}{\left(\partial w_{i}\right)^{2}}=-\frac{1}{w_{i}^{2}}, \quad \frac{\partial^{2} L E L(w, R)}{\left(\partial R_{l}\right)^{2}} & =-\frac{1}{R_{l}^{2}}, \quad \frac{\partial^{2} L E L(w, R)}{\partial w_{i} \partial R_{l}}=0 \\
i=1,2, \ldots, k, \quad l & =1,2, \ldots, n-k
\end{aligned}
$$

Therefore the matrix $\mathbf{G}(n \times n)$ in the quadratic approximation (3) is diagonal. The $i^{\text {th }}$ diagonal element of $\mathbf{G}$ is either $\frac{1}{w_{i}^{2}}$ or $\frac{1}{R_{l}^{2}}$ depending on whether this observation is censored or not. Since $\mathbf{G}$ is a diagonal matrix, it is trivial to find the inverse of the decomposition matrix of $\mathbf{G}$, say $\mathbf{H}^{-1}$, such that $\mathbf{H}^{T} \mathbf{H}=\mathbf{G} . \mathbf{H}^{-1}$ is also a diagonal matrix with $i^{t h}$ entries equal to $w_{i}$ or $R_{l}$ depending on the censoring status. Many QP solvers, including the one in $R$ package quadprog, can directly use $\mathbf{H}^{-1}$ to calculate the solution much faster. Now, because we introduced new variables $R_{l}$, they bring $(n-k)$ additional constraints, that is,

$$
\begin{gathered}
(1): \quad R_{1}=\sum_{Z_{j}>Z_{1}^{*}, \delta_{j}=1,1 \leq j \leq k} w_{j} \\
\vdots \\
(n-k): \quad R_{n-k}=\sum_{Z_{j}>Z_{n-k}^{*}, \delta_{j}=1,1 \leq j \leq k} w_{j} .
\end{gathered}
$$

These, plus the two original constraints (using the original $Z_{1}<\cdots<Z_{n}$ )

$$
\sum_{i=1}^{n} w_{i} \delta_{i}=1, \quad \sum_{i=1}^{n} w_{i} Z_{i} \delta_{i}=\mu
$$

would make the constraint matrix $\mathbf{C}$ to be of size $n \times(n-k+2)$. The first two columns of $\mathbf{C}$ for the above two original constraints will be

$$
\left(\begin{array}{cc}
\delta_{1} & \delta_{1} Z_{1} \\
\delta_{2} & \delta_{2} Z_{2} \\
\vdots & \vdots \\
\delta_{n} & \delta_{n} Z_{n}
\end{array}\right)
$$

The rest of the columns depend on the positions of censored observations. If the observation is censored, the entry is 1 . All entries before this observation are 0 . The entries after this observation are -1 if uncensored, 0 if censored.

Example 2: For a concrete example of second QP implementation, suppose there are five ordered observations $\mathbf{Z}=(1,2,3,4,5)$ and censoring indicators $\delta=(1,0,1,0,1)$. The weight vector will be $w=\left(w_{1}, 0, w_{2}, 0, w_{3}\right)$ and the probability constraint is that $\sum w_{i} \delta_{i}=w_{1}+w_{2}+w_{3}=$ 1. Suppose that we want to test a null hypothesis $\sum w_{i} Z_{i} \delta_{i}=w_{1}+3 w_{2}+5 w_{3}=\mu$. We have the log empirical likelihood function

$$
L E L(w, R)=\log w_{1}+\log w_{2}+\log w_{3}+\log R_{1}+\log R_{2}
$$

where $R_{1}=w_{2}+w_{3}$ and $R_{2}=w_{3}$. In this case, the relevant vectors and matrices are:

$$
\begin{gathered}
\mathbf{a}=\left(\begin{array}{c}
1 / w_{1}^{\star} \\
1 / R_{1}^{\star} \\
1 / w_{2}^{\star} \\
1 / R_{2}^{\star} \\
1 / w_{3}^{\star}
\end{array}\right), \quad \mathbf{G}=\left(\begin{array}{ccccc}
\frac{1}{\left(w_{1}^{\star}\right)^{2}} & 0 & 0 & 0 & 0 \\
0 & \frac{1}{\left(R_{1}^{\star}\right)^{2}} & 0 & 0 & 0 \\
0 & 0 & \frac{1}{\left(w_{2}^{\star}\right)^{2}} & 0 & 0 \\
0 & 0 & 0 & \frac{1}{\left(R_{2}^{\star}\right)^{2}} & 0 \\
0 & 0 & 0 & 0 & \frac{1}{\left(w_{3}^{\star}\right)^{2}}
\end{array}\right), \\
\mathbf{C}=\left(\begin{array}{cccc}
1 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
1 & 3 & -1 & 0 \\
0 & 0 & 0 & 1 \\
1 & 5 & -1 & -1
\end{array}\right), \quad \mathbf{x}=\left(\begin{array}{c}
w_{1}-w_{1}^{\star} \\
R_{1}-R_{1}^{\star} \\
w_{2}-w_{2}^{\star} \\
R_{2}-R_{2}^{\star} \\
w_{3}-w_{3}^{\star}
\end{array}\right)
\end{gathered}
$$

where $w^{\star}$ and $R^{\star}$ are the current values, and $w$ and $R$ will be the updated values after one QP.
The vector $\mathbf{b}_{0}$ will depend on the starting value $\mathbf{w}_{0}$. We always use a starting value $\mathbf{w}_{0}$ that is a probability, but it may not satisfy the weighted mean constraint. After one QP iteration, the new $\mathbf{w}$ will satisfy $\sum w_{i} Z_{i} \delta_{i}=\mu$ and thus for subsequent QP the vector $\mathbf{b}$ should be zero. Suppose we take $\mathbf{w}_{0}$ to be the discrete uniform probability, then

$$
\mathbf{b}_{\mathbf{0}}=\left(\begin{array}{lll}
0, & \mu-\bar{Z}, & 0, \\
0
\end{array}\right), \mathbf{b}=\left(\begin{array}{llll}
0, & 0, & 0
\end{array}\right)
$$

The decomposition of the matrix $\mathbf{G}$ is $\mathbf{H}$, and we have:

$$
\mathbf{H}^{-1}=\left(\begin{array}{ccccc}
w_{1}^{\star} & 0 & 0 & 0 & 0 \\
0 & R_{1}^{\star} & 0 & 0 & 0 \\
0 & 0 & w_{2}^{\star} & 0 & 0 \\
0 & 0 & 0 & R_{2}^{\star} & 0 \\
0 & 0 & 0 & 0 & w_{3}^{\star}
\end{array}\right) .
$$

Remark 2. To compare the two methods, we generated a random sample of size $n=100$, where $X$ from $N(1,1), C$ from $N(1.5,2)$. On the same computer, the first method took about $25-30$ minutes to find the maximum of the likelihood, however, the second method only took $1-2$ seconds. The difference is remarkable. The computation took about 5 iterations of QP. Of course this comparison is very much hardware dependent, but it at least is an indication of what could happen.

Remark 3. The same trick also works for other types of censoring. The key is to introduce some new variables so that the $\log$ likelihood function is just $\sum \log x_{i}$. This, for example, works for interval censored data where for an interval censored observation the log likelihood term is $\log x_{i}$, and $x_{i}$ now equals the sum of the probabilities located inside the interval of observation $i$.

## 4. Empirical Likelihood Ratio Computation

The SQP method is a very powerful way to find the maximizer of a log empirical likelihood function under constraints which in turn allows us to compute the empirical likelihood ratio statistic. After we obtain $\tilde{w}$ and $\hat{w}$, Wilks' theorem can then be used to compute the P-value of the observed statistic. Thus, we can use the empirical likelihood ratio to test hypotheses and construct confidence intervals.

We have implemented this SQP in the R software (Gentleman and Ihaka 1996). The R function el.cen.test that computes the empirical likelihood ratio for right censored observations with one mean constraint has been packaged as part of the emplik package and posted on CRAN (http://cran.us.r-project.org). Our implementation of QP in R uses the R functions backsolve(), qr() which in turn call the corresponding LINPACK routines.

To illustrate the application, we will show the simulation results for right censored data and give one example for interval censored data.

### 4.1 Confidence Interval, real data, right censored

Veteran's Administration Lung cancer study data (for example available from the R package survival). We took the subset of survival data for treatment 1 and the smallcell group. There are two right censored observations. The survival times are:
$30,384,4,54,13,123+, 97+, 153,59,117,16,151,22,56,21,18,139,20,31,52,287,18$, 51, 122, 27, 54, 7, 63, 392, 10.

We used the empirical likelihood ratio to test the null hypothesis that the mean is equal to $\mu$ (for various values of $\mu$ ). The $95 \%$ confidence interval for the mean survival time is seen to be [61.708, 144.915] since the empirical likelihood ratio test statistic -2 LogLikRatio $=3.841$ both when $\mu=61.708$ and $\mu=144.915$.

The MLE of the mean is 94.7926 which is the integrated Kaplan-Meier estimator. We see that the confidence interval is not symmetric around the MLE, this is typical for confidence intervals based on likelihood ratio tests.

### 4.2 Simulation: right censored data

We randomly generated 5000 right-censored samples, each of size $n=300$, as in equation (1), where $X$ is taken from $N(1,1), C$ from $N(1.5,1)$. Censoring percentage is around $10 \%-20 \%$. The software R is used in the implementation. We tested the null hypothesis $H_{0}: \sum_{i=1}^{n} w_{i} Z_{i} \delta_{i}=$ $\mu=1$, which is true for our generated data.

We computed 5000 empirical likelihood ratios, using the Kaplan Meier estimator's jumps as $(\tilde{w})$ which maximizes the denominator in (9) and we used the SQP method to find ( $\hat{w}$ ) that maximizes the numerator under the $H_{0}$ constraint. The Q-Q plot based on 5000 empirical


Figure 1: $\quad Q-Q$ Plot of -2log-likelihood Ratios vs. $\chi_{(1)}^{2}$ Percentiles for Sample Size $=300$
likelihood ratios and $\chi_{1}^{2}$ percentiles is shown in Figure 1. At the point 3.84 (or 2.71) which is the critical value of $\chi_{1}^{2}$ with nominal level $5 \%$ (or $10 \%$ ), if the $-2 \log$-likelihood ratio line is above the dashed line ( $45^{\circ}$ line), the probability of rejecting $H_{0}$ is greater than $5 \%$ (or $10 \%$ ).

Otherwise, the rejection probability is less than $5 \%$ (or $10 \%$ ). From the Q-Q plot, we can see that the $\chi_{1}^{2}$ approximation is pretty good. Only at the tail of the plot, the differences between the percentiles of $-2 \log$-likelihood ratios and $\chi_{1}^{2}$ are getting bigger.

### 4.3 Example - Interval Censored Case

As we mentioned before, the SQP method can also be used to compute the (constrained) nonparametric MLE with interval censored data. We use the breast cosmetic deterioration data from Gentleman and Geyer (1994) as an example. The data consist of 46 early breast cancer patients who were treated with radiotherapy, but there are only 8 intervals with positive probabilities. We use SQP to compute the probabilities for these 8 intervals under the constraint $\sum_{i=1}^{8} X_{i} p_{i}=\mu$, where $\mu$ is the population mean which we want to test, $X_{i}$ is the midpoint of each interval, $p_{i}$ is the probability of the corresponding interval. Table 3.1 lists the probabilities for two different constraints. The mean of the unconstrained NPMLE is 33.5809, therefore the hypothesis $H_{0}$ : $\mu=33.5809$ is equivalent to imposing no constraint, and the P -value is 1 .

| left | right | $H_{0}: \mu=33.5809$ | $H_{0}: \mu=40$ |
| :---: | :---: | :---: | :---: |
| 4 | 5 | 0.04634407 | 0.01954125 |
| 6 | 7 | 0.03336178 | 0.01543886 |
| 7 | 8 | 0.08866270 | 0.03917190 |
| 11 | 12 | 0.07075012 | 0.03524150 |
| 24 | 25 | 0.09264346 | 0.05263571 |
| 33 | 34 | 0.08178547 | 0.06119782 |
| 38 | 40 | 0.12087966 | 0.09192321 |
| 46 | 48 | 0.46557274 | 0.68484974 |
| $-2 L L R\left(H_{0}\right)$ |  | 0 | 7.782341 |

Table 3.1: Restricted set of intervals and the associated probabilities

Discussion: One drawback of the SQP method is that it becomes more memory/computationally intensive for larger sample sizes. The cost increases at the rate of $n^{2}$. This is in contrast to the Lagrange multiplier method mentioned above where (when available) $r$ remains fixed as the sample size $n$ increases. However, we argue that this is not a major drawback for SQP because (1) the advantages of the empirical likelihood ratio method are most pronounced for small to medium sample sizes. Often for large samples, there are alternative, equally effective and easily computable statistical methods available, as for example the Wald method. (2) by our implementation of the SQP method in R, we can easily handle sample sizes of up to 2000
on today's average PC ( 20 seconds on a $3 \mathrm{GHz}, 512 \mathrm{MB}$ PC). With computer hardware getting cheaper, this drawback should diminish and not pose a major handicap for the SQP method for most applications.

Of course, not all constrained maximization problems have a solution. If the $H_{0}$ constraint is too far away from the sample mean, this may well happen. See Owen (1988 p.238) for further discussion. When this happens, we should define the likelihood ratio to be zero, implying that this is an impossible $H_{0}$.

There may be simpler methods available to compute $\tilde{w}$, the NPMLE without constraint. In the case of Example 1, this is the well known Kaplan-Meier estimator.

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Department of Statistics
University of Kentucky
Lexington, KY 40506-0027


[^0]:    ${ }^{1}$ Corresponding author: Mai Zhou (Email: mai@ms.uky.edu)

