

3/6/30

MA 322 : Written Homework 1

+101. Suppose we know the system

$$3x_1 + 5x_2 = h$$

$$cx_1 + dx_2 = k$$

is consistent for all possible values of h and k .
What can you say about c and d ?

$$\left[\begin{array}{cc|c} 3 & 5 & h \\ c & d & k \end{array} \right]$$

$$\left[\begin{array}{cc|c} 3 & 5 & h \\ 0 & d - \frac{5}{3}c & k - \frac{h}{3}c \end{array} \right] R_2 \leftarrow R_2 - \frac{c}{3}R_1$$

The system would be consistent when $d - \frac{5}{3}c \neq 0$ since we can always find an h and k so $k - \frac{h}{3}c \neq 0$. Great!

+102. Find three different augmented matrices which represent linear systems with solution s
 $x_1 = 6$, $x_2 = 2$, and $x_3 = 4$.

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 6 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 4 \end{array} \right] \begin{array}{l} x_1 = 6 \\ x_2 = 2 \\ x_3 = 4 \end{array} \checkmark$$

$$\left[\begin{array}{ccc|c} 2 & 0 & 0 & 12 \\ 0 & 2 & 0 & 4 \\ 0 & 0 & 2 & 8 \end{array} \right] \begin{array}{l} \checkmark \text{ IF you divide each row} \\ \text{by 2 then the solution is} \\ x_1 = 6, x_2 = 2, \text{ and } x_3 = 4. \end{array}$$

$$\left[\begin{array}{ccc|c} 5 & 0 & 0 & 30 \\ 0 & 5 & 0 & 10 \\ 0 & 0 & 5 & 20 \end{array} \right] \begin{array}{l} \checkmark \text{ IF you divide each row} \\ \text{by 5 then the solution is} \\ x_1 = 6, x_2 = 2, \text{ and } x_3 = 4. \end{array}$$

+103. In the following matrices, \blacksquare represent a nonzero entry, and $*$ represents an entry that may or may not be zero. For each of these augmented matrices determine if the associated linear system is inconsistent, consistent with a unique solution, or consistent with infinitely many solutions.

✓ a) $\left[\begin{array}{cc|c} x_1 & x_2 & b \\ \blacksquare & * & * \\ 0 & \blacksquare & * \end{array} \right]$ Consistent with a unique solution because x_1 and x_2 are both basic variables

✓ b) $\left[\begin{array}{c|c} x_1 & b \\ \blacksquare & * \\ 0 & \blacksquare \end{array} \right]$ Inconsistent with no solutions because Row 2 is $[0 \mid b]$ $b \neq 0$

✓ c) $\left[\begin{array}{c|c} x_1 & b \\ \blacksquare & 0 \\ 0 & 0 \end{array} \right]$ Consistent with a unique solution because x_1 is a basic variable.

✓ d) $\left[\begin{array}{ccc|c} x_1 & x_2 & x_3 & b \\ 0 & \blacksquare & * & * \\ 0 & 0 & \blacksquare & * \end{array} \right]$ Consistent with infinitely many solutions because x_1 is a free variable. x_2 and x_3 are basic variables.

✓ e) $\left[\begin{array}{ccc|c} x_1 & x_2 & x_3 & b \\ \blacksquare & * & * & * \\ 0 & 0 & \blacksquare & * \\ 0 & 0 & 0 & \blacksquare \end{array} \right]$ Inconsistent with no solutions because Row 3 is $[0 \ 0 \ 0 \mid b]$ and $b \neq 0$.
great explanations!

+104. A system with fewer equations than unknowns is called an underdetermined system. A system with more equations than unknowns is called an overdetermined system.

a) Give an example of an inconsistent underdetermined linear system.

$$\begin{aligned}
 X_1 + X_2 + X_3 &= 1 \quad \checkmark \\
 X_1 + X_2 + X_3 &= 3
 \end{aligned}$$

This is an example of an inconsistent underdetermined linear system because there are 2 equations and 3 unknowns (fewer equations than unknowns and when I solved the matrix (shown below) I got $[0 \ 0 \ 1 \ b]$ where $b \neq 0$ in Row 2.

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 3 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 2 \end{array} \right] R_2 \leftarrow R_2 - R_1$$

fantastic explanations!

b) Give an example of a consistent overdetermined linear system.

$2X_1 + X_2 = 2$
 $-4X_1 - 4X_2 = -24$
 $X_1 + X_2 = 6$

This is an example of a consistent overdetermined matrix because there are more equations (there are 3) than variables (there are 2) and there's a solution (as shown below).

$$\left[\begin{array}{cc|c} 2 & 1 & 2 \\ -4 & -4 & -24 \\ 1 & 1 & 6 \end{array} \right]$$

$$\rightarrow \left[\begin{array}{cc|c} 1 & 0 & -4 \\ -4 & -4 & -24 \\ 0 & 0 & 0 \end{array} \right] R_3 \leftarrow R_3 + R_2$$

$$\left[\begin{array}{cc|c} 1 & 0 & -4 \\ -4 & -4 & -24 \\ 1 & 1 & 6 \end{array} \right] R_1 \leftarrow R_1 - R_3$$

$$\left[\begin{array}{cc|c} 1 & 0 & -4 \\ 1 & 1 & 6 \\ 0 & 0 & 0 \end{array} \right] -\frac{1}{4}R_2$$

$$\left[\begin{array}{cc|c} 1 & 0 & -4 \\ -4 & -4 & -24 \\ 4 & 4 & 24 \end{array} \right] 4R_3$$

$$\left[\begin{array}{cc|c} 1 & 0 & -4 \\ 0 & 1 & 10 \\ 0 & 0 & 0 \end{array} \right] R_2 \leftarrow R_2 - R_1$$

$$\boxed{X_1 = -4, X_2 = 10}$$

165. True or False. Decide if each statement is true (always true) or false (can ever be false). If true explain clearly. If false, explain or give a counterexample where appropriate.

a) Points in the plane corresponding to the vectors $\begin{bmatrix} 3 \\ 2 \end{bmatrix}$ and $\begin{bmatrix} -2 \\ -3 \end{bmatrix}$ lie on a line through the origin.

False because we have a setup like $\vec{u} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} -2 \\ -3 \end{bmatrix}$ and we'd need

\vec{v} to be a multiple of \vec{u} , which it's not.

$$c\vec{v} = \vec{u}$$

$$c(-2) = 3$$

$$c(-3) = 2$$

} there is not a c to satisfy both of these equations.

b) An example of a linear combination of the vectors \vec{u} and \vec{v} is $\frac{2}{3}\vec{v}$.

True, if both \vec{u} and \vec{v} are in \mathbb{R}^n .

For example, $0\vec{u} + \frac{2}{3}\vec{v} = \frac{2}{3}\vec{v}$, showing if you multiply \vec{u} by a constant, zero, and \vec{v} by a constant $\frac{2}{3}\vec{v}$, then when you add them you get $\frac{2}{3}\vec{v}$.

c) The set $\text{span}\{\vec{u}, \vec{v}\}$ is always visualized as a plane through the origin.

False. $\text{Span}\{\vec{u}, \vec{v}\}$ is a plane through the origin unless \vec{u} is a multiple of \vec{v} or $\vec{u}, \vec{v} = \vec{0}$. ($\vec{0}$ = zero vector).