

Please write up complete, clear solutions on your own paper. We will be looking for your reasoning and explanations, not just a correct answer. Please copy each question and write neatly.

**For the construction, you should justify that your construction meets the required criteria.**

This assignment covers material in sections 5.3, 5.4, and 5.5.

1. Suppose  $A$  is a  $5 \times 5$  matrix with exactly three eigenvalues, and we know one of the eigenspaces is three-dimensional (we aren't told about the others). Can we determine whether or not  $A$  is diagonalizable? Explain why or why not.
2. Now suppose  $A$  is a  $6 \times 6$  matrix with exactly three eigenvalues, and one of the eigenspaces is three-dimensional (we aren't told about the others). Can we determine whether or not  $A$  is diagonalizable? Explain why or why not.
3. Construct an example of a matrix that is diagonalizable, is not diagonal, and is not invertible.
4. Let  $A = \begin{bmatrix} 1 & 1 \\ -1 & 3 \end{bmatrix}$ , and  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2\}$  where  $\mathbf{b}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $\mathbf{b}_2 = \begin{bmatrix} 5 \\ 4 \end{bmatrix}$ . Define  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by  $T(\mathbf{x}) = A\mathbf{x}$ . Find  $[T]_{\mathcal{B}}$ .
5. Let  $A = \begin{bmatrix} \sqrt{3} & 3 \\ -3 & \sqrt{3} \end{bmatrix}$ . The transformation  $\mathbf{x} \mapsto A\mathbf{x}$  is a composition of a rotation and a scaling.
  - a. Give the angle of rotation and the scale factor.
  - b. Find the eigenvalues and a basis for each eigenspace.