# Preliminary Examination in Numerical Analysis 

June 2, 2006

## Instructions:

1. The examination is for 3 hours.
2. The examination consists of two parts:

Part I: Matrix Theory and Numerical Linear Algebra
Part II: Introductory Numerical Analysis
3. There are three problem sets in each part. Work two out of the three problem sets for each part.
4. All problem sets carry equal weights.

## PART I - Matrix Theory and Numerical Linear Algebra <br> (Work two of the three problem sets in this part)

## Problem 1.

1. Assume that $A$ and $A+\delta A$ are $n \times n$ invertible matrices and $\eta:=\kappa(A) \frac{\|\delta A\|}{\|A\|}<1$. Prove that

$$
\frac{\left\|(A+\delta A)^{-1}-A^{-1}\right\|}{\left\|A^{-1}\right\|} \leq \frac{\kappa(A) \frac{\|\delta A\|}{\|A\|}}{1-\eta}
$$

where $\|\cdot\|$ is any matrix operator norm and $\kappa(A)$ is the condition number of $A$.
2. Let $A \in R^{n \times n}$ be symmetric positive definite. Prove by induction on $n$ that $A$ has a Cholesky factorization, namely there exists a lower triangular matrix $G$ such that $A=G G^{T}$.
3. Write down the algorithm for computing the Cholesky factorization. Use the error analysis of the $L U$ factorization to explain briefly why the Cholesky algorithm is stable without pivoting.

Problem 2. Let $A$ be an $m \times n$ matrix and $m>n$.

1. Describe the Gram-Schmidt process to orthogonalize the columns of $A$. Prove that the process produces an orthonormal basis if the columns of $A$ are linearly independent. Formulate the process into the matrix factorization $A=Q R$, and what is $Q$ and what is $R$ ?
2. Describe an algorithm for computing the $Q R$ factorization of $A$ by the Householder transformations. How does this algorithm compare with the one based on the Gram-Schmidt process?

## Problem 3.

1. State the power method for computing the largest eigenvalue (in absolute value) of a matrix $A \in R^{n \times n}$. State and prove the convergence result for the case that $A$ is symmetric. Describe the shift-and-invert method to compute the eigenvalue closest to a given number $\mu$.
2. Let $\beta$ be an approximate eigenvalue and $x \in R^{n}$ with $\|x\|_{2}=1$ a corresponding approximate eigenvector of an $n \times n$ real symmetric matrix $A$. Prove

$$
\min _{i}\left|\lambda_{i}-\beta\right| \leq\|A x-\beta x\|_{2} .
$$

where $\lambda_{1}, \lambda_{2}, \cdots, \lambda_{n}$ are eigenvalues of $A$.

## Part II - Numerical Analysis <br> (Work two of the three problem sets in this part)

Problem 4. Polynomial interpolation.

1. Prove that if $g$ interpolates the function $f$ at $x_{0}, x_{1}, \ldots, x_{n-1}$ and if $h$ interpolates $f$ at $x_{1}, x_{2}, \ldots, x_{n}$, then the function

$$
g(x)+\frac{x_{0}-x}{x_{n}-x_{0}}[g(x)-h(x)]
$$

interpolates $f$ at $x_{0}, x_{1}, \ldots, x_{n-1}, x_{n}$.
2. Complete the following divided-difference table

| $x$ | $f(x)$ | $f[$, ] | $f[$, , ] | $f[, ~, ~, ~] ~$ |
| :---: | :---: | :---: | :---: | :---: |
| 4 | 63 |  |  |  |
| 2 | 11 |  |  |  |
| 0 | 7 |  |  |  |
| 3 | 28 |  |  |  |

3. Obtain polynomials of degree 3 that interpolates the function values given in (2), using Newton's formula.
4. Obtain polynomials of degree 3 that interpolates the function values given in (2), using Lagrange's formula. (You may just write down the formula without simplifying it.)

Problem 5. Quadrature rules.

1. Given $(n+1)$ nodes $x_{0}, x_{1}, \ldots, x_{n}$ in $[a, b]$. Derive the Newton-Cotes formula for approximating $\int_{a}^{b} f(x) d x$. Write down the trapezoid rule (for which $n=1, x_{0}=a$, and $x_{1}=b$ ).
2. Prove that the Newton-Cotes formula you just derived is exact for all polynomials of degree no higher than $n$.
3. Find the Gaussian quadrature rule

$$
\int_{-1}^{1} f(x) d x \approx A_{0} f\left(x_{0}\right)+A_{1} f\left(x_{1}\right)+A_{2} f\left(x_{2}\right) .
$$

What is the highest degree of polynomials for which this formula is exact?
4. Use the Gaussian quadrature rule you just found to find the Gaussian quadrature rule

$$
\int_{a}^{b} g(t) d t \approx A_{0} f\left(t_{0}\right)+A_{1} f\left(t_{1}\right)+A_{2} f\left(t_{2}\right) .
$$

Use it to approximate $\int_{0}^{2} \frac{\sin t}{t} d t$.

Problem 6. Zeros of functions and splines.

1. What are the conditions that guarantee the bisection to work, i.e., to find a zero? Justify your answer.
2. What are the conditions that guarantee the Newton method to converge quadratically at the end? Justify your answer.
3. Given $(n+1)$ knots $t_{0}<t_{1}<\cdots<t_{n}$, what are the conditions to make a function $S(x)$ on $\left[t_{0}, t_{n}\right]$ a natural cubic spline.
4. Find the natural cubic spline that interpolates the table

$$
\begin{array}{l||r|r|r}
x & -1 & 0 & 1 \\
\hline y & 1 & 2 & -3
\end{array}
$$

