

Solutions to PS 6.

2.2.17

$$[M_i, M_j] = iM_k$$

Take the trace of both sides

$$\begin{aligned} \text{Tr}(M_i, M_j) &= \text{Tr}(M_i M_j - M_j M_i) \\ &= \text{Tr} M_i M_j - \text{Tr} M_j M_i \\ &= \text{Tr} M_i M_j - \text{Tr} M_i M_j = 0 \end{aligned}$$

using the fact that $\text{Tr} AB = \text{Tr} BA$
 So $\text{Tr} M_k = 0$, for any k .

2.2.38

If U is unitary then $U^{-1} = U^*$. To show U^{-1} is unitary we must show $(U^{-1})^{-1} = (U^{-1})^*$.

We know $(U^{-1})^{-1} = U$. The key is the procedure of taking the adjoint commutes with taking the inverse. $(A^*)^{-1} = (A^{-1})^*$.

Applying this: $(U^{-1})^* = (U^*)^{-1}$ but U is unitary
 $= (U^{-1})^{-1} = U$

Hence the statement $(U^{-1})^{-1} = (U^{-1})^*$ is true and U^{-1} is unitary.

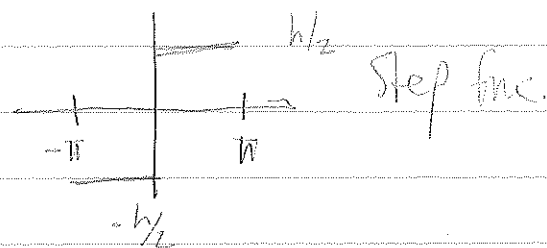
Another way to show this:

$$U^{-1} = U^*$$

$$(U^{-1})^* = (U^*)^* = U = (U^{-1})^{-1}$$

5.1.5

$$f(x) = \begin{cases} h/2 & 0 < x < \pi \\ -h/2 & -\pi < x < 0 \end{cases}$$



$$= \frac{2h}{\pi} \sum_{n=0}^{\infty} \frac{\sin(2n+1)x}{2n+1}$$

$$(a) \int_{-\pi}^{\pi} |f(x)|^2 dx = (f, f) = \left(\frac{2h}{\pi} \right)^2 \sum_{n=0}^{\infty} \frac{1}{(2n+1)^2}$$

The left side is $\|f\|^2 = (f, f)$
A direct calculation

$$(f, f) = \sum_{n,m=0}^{\infty} \left(\frac{2h}{\pi} \right)^2 \frac{1}{(2n+1)(2m+1)} \int_{-\pi}^{\pi} dx \sin(2n+1)x \sin(2m+1)x$$

Basic integral

$$\sin A \sin B = \frac{1}{2} [\cos(A-B) - \cos(A+B)]$$

so

$$J_{nm} = \int_{-\pi}^{\pi} dx \sin(2n+1)x \sin(2m+1)x = \frac{1}{2} \int_{-\pi}^{\pi} [\cos 2(n-m)x - \cos 2[(n+m)+1]x] dx$$

$$n \neq m \quad = \quad \frac{1}{2} \frac{1}{2(n-m)} \sin 2(n-m)x \Big|_{-\pi}^{\pi} - \frac{1}{2} \frac{1}{2(n+m+1)} \sin 2(n+m+1)x \Big|_{-\pi}^{\pi}$$

$$\underline{n \neq m} \quad J_{nm} = 0, \quad \underline{n = m} \quad J_{nn} = \pi, \quad \text{so } J_{nm} = \pi \delta_{nm}$$

$$\begin{aligned} \text{so } (f, f) &= \sum_{n,m=0}^{\infty} \left(\frac{2h}{\pi} \right)^2 \frac{1}{(2n+1)(2m+1)} (\pi \delta_{nm}) \\ &= \sum_{n=0}^{\infty} \left(\frac{2h}{\pi} \right)^2 \frac{\pi}{(2n+1)^2} = \sum_{n=0}^{\infty} \frac{4h^2}{\pi} \frac{1}{(2n+1)^2} \end{aligned}$$

PS 6-3

$$(b) \sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6} = \zeta(2) \quad \text{Riemann Zeta func. at } \zeta=2.$$

$$\sum_{n=0}^{\infty} \frac{1}{(2n+1)^2} = \sum_{k=1}^{\infty} \frac{1}{k^2} - \sum_{k=1}^{\infty} \frac{1}{(2k)^2} = \frac{\pi^2}{6} - \frac{1}{4} \frac{\pi^2}{6} = \frac{3}{4} \frac{\pi^2}{6}$$

$2n+1$ odd integer

So

$$\|f\|^2 = \left(\frac{4h^2}{\pi}\right) \left(\frac{3}{4}\right) \left(\frac{\pi^2}{6}\right) = \frac{h^2 \pi}{2}$$

This is exactly $\int_{-\pi}^{\pi} f(x)^2 dx = 2 \int_0^{\pi} \left(\frac{h}{2}\right)^2 dx$

$$= \frac{h^2 \pi}{2}$$

(PS6-4)

5.1.12

$\underline{a} = a_1 \hat{e}_1 + a_2 \hat{e}_2$ and $\underline{b} = b_1 \hat{e}_1 + b_2 \hat{e}_2$ Real LVS

Define $\langle \underline{a} | \underline{b} \rangle_k = a_1 b_1 - a_1 b_2 - a_2 b_1 + k a_2 b_2$
 $= (a_1 - a_2)(b_1 - b_2) + (k-1) a_2 b_2$

To be an inner product, we need

(1) $\langle \underline{a} | \underline{b} \rangle = \langle \underline{b} | \underline{a} \rangle$

If

This is easily verified so it is symmetric

(2) $\langle \underline{a} + \lambda \underline{c} | \underline{b} \rangle = ((a_1 + \lambda c_1 - a_2 + \lambda c_2)$

$$\begin{aligned} & \lambda (b_1 - b_2) + (k-1)(a_2 + \lambda c_2) b_2 \\ &= (a_1 - a_2)(b_1 - b_2) + \lambda (c_1 - c_2)(b_1 - b_2) \\ & \quad + (k-1) a_2 b_2 + \lambda (k-1) c_2 b_2 \\ &= \langle \underline{a} | \underline{b} \rangle + \lambda \langle \underline{c} | \underline{b} \rangle \end{aligned}$$

so it is linear

(3) $\langle \underline{a} | \underline{a} \rangle = (a_1 - a_2)^2 + (k-1) a_2^2$

Clearly $(k-1) \geq 0$ for $\langle \underline{a} | \underline{a} \rangle \geq 0$.

Further, if $a_1 = a_2 \neq 0$ then $(a_1 - a_2)^2 = 0$

so we need $(k-1) > 0$.

Conclude $\langle \cdot | \cdot \rangle$ is an IP if $k \geq 1$.

PS6-5

5.3.1 Show $(A^*)^* = A$:

Defining property of A^* . For all $u, v \in V$:

$$\langle u, Av \rangle = \langle A^* u, v \rangle$$

So now compute

$$\langle u, A^* v \rangle = \langle (A^*)^* u, v \rangle$$

$$\text{but } \langle u, A^* v \rangle = \overline{\langle A^* v, u \rangle} = \overline{\langle v, Au \rangle}$$

by the defining property,

$$\text{Since } \overline{\langle v, Au \rangle} = \langle Au, v \rangle$$

we get:

$$\langle (A^*)^* u, v \rangle = \langle Au, v \rangle$$

for all u, v . This shows $(A^*)^* = A$.

This calculation holds for any IP space and does not use the matrix rep.

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PS6-C

5.3.3.

$$\varphi_1(x) = x_1 \quad \varphi_2(x) = x_2 \quad \varphi_3(x) = x_3$$

$$\langle x_\mu | x_\nu \rangle = \delta_{\mu\nu} \quad \{\varphi_i\} \text{ ONB}$$

$$A_m: [A_m]_{ij} = \langle \varphi_i | A_m | \varphi_j \rangle$$

$$[A_1]_{ij} = \langle \varphi_i | A_1 | \varphi_j \rangle = \langle \varphi_i | \sum x_e \partial_e | \varphi_j \rangle$$

$$\begin{aligned} \partial_e \varphi_j &= \delta_{ej} \\ &= \langle \varphi_i | \varphi_j \rangle = \delta_{ij} \end{aligned} \quad [A_1] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\begin{aligned} [A_2]_{ij} &= \langle \varphi_i | (x_1 \partial_2 - x_2 \partial_1) | \varphi_j \rangle \\ &= \langle \varphi_i | x_1 \delta_{2j} - x_2 \delta_{1j} \rangle \\ &= \delta_{i1} \delta_{2j} - \delta_{i2} \delta_{1j} \end{aligned}$$

$$\begin{aligned} [A_2] &= \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \end{aligned}$$

$$(b) \psi = x_1 - 2x_2 + 3x_3 \quad \text{so} \quad \psi = \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix}$$

$$\begin{aligned} \text{Compute } X &\equiv (A_1 - A_2)\psi = \sum_{i=1}^3 x_i \partial_{x_i} \psi - (x_1 \partial_2 - x_2 \partial_1) \psi \\ &= (x_1 - 2x_2 + 3x_3) + 2x_1 + x_2 = 3x_1 - x_2 + 3x_3 \end{aligned}$$

PS6.7

$$[A_1 | A_2] = \left(\begin{array}{cc|c} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right)$$

$$[A_1 | A_2] = \left(\begin{array}{c|c} 1 \\ -2 \\ 3 \end{array} \right) = \left(\begin{array}{c} 3 \\ -1 \\ 3 \end{array} \right) \text{ which is } X.$$