# MA 138 – Calculus 2 with Life Science Applications Matrices (Section 9.2)

#### **Alberto Corso**

(alberto.corso@uky.edu)

Department of Mathematics University of Kentucky

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# Identity Matrix and Inverse of a Matrix

For any  $n \ge 1$ , the identity matrix is an  $n \times n$  matrix, denoted by  $l_n$ , with 1's on its diagonal line and 0's elsewhere; that is,

$$I_n = \left[ egin{array}{cccc} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ dots & dots & \ddots & dots \\ 0 & 0 & \cdots & 1 \end{array} 
ight]$$

#### **Property of the Identity Matrix**

Suppose that A is an  $m \times n$  matrix. Then  $I_m A = A = AI_n$ .

#### Inverse of a Matrix

Suppose that A is an  $n \times n$  square matrix. If there exists an  $n \times n$  square matrix B such that  $AB = I_n = BA$  then B is called the inverse matrix of A and is denoted by  $A^{-1}$ .

**Example 1** (Part I)...Checking

Verify that:

$$A_1 = \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix}$$
 and  $B_1 = \frac{1}{2} \begin{bmatrix} 4 & -5 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} 2 & -5/2 \\ -1 & 3/2 \end{bmatrix}$ 

are inverses of each other. That is  $A_1B_1 = I_2 = B_1A_1$ .

$$A_2 = \begin{bmatrix} 3 & 5 & -1 \\ 2 & -1 & 3 \\ 4 & 2 & -3 \end{bmatrix} \quad \text{and} \quad B_2 = \frac{1}{73} \begin{bmatrix} -3 & 13 & 14 \\ 18 & -5 & -11 \\ 8 & 14 & -13 \end{bmatrix}$$

are inverses of each other. That is  $A_2B_2 = I_3 = B_2A_2$ .

$$\begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 2 & -\frac{5}{2} \\ -1 & \frac{3}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & -\frac{5}{2} \\ -1 & \frac{3}{2} \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix}$$

$$A_{1} \qquad B_{1} \qquad A_{1}$$

easy bout Addious ....

$$\begin{bmatrix} 3 & 5 & -1 \\ 2 & -1 & 3 \\ 4 & 2 & -3 \end{bmatrix} \begin{bmatrix} -\frac{3}{73} & \frac{13}{73} & \frac{14}{73} \\ \frac{18}{73} & -\frac{5}{73} & -\frac{11}{73} \\ \frac{14}{73} & \frac{14}{73} & -\frac{13}{73} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A2$$

$$B_{2}$$

and 
$$B_2 \cdot A_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 ... very tedious!

# Matrix Representation of Linear Systems

We observe that the system of linear equations

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{cases}$$

can be written in matrix form as AX = B, where

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

# The ... Guiding Light

- A simple key observation: To solve 5x = 10 for x, we just divide both sides by  $5 \equiv 0$  multiply both sides by  $1/5 = 5^{-1}$ . That is,  $5x = 10 \iff 5^{-1} \cdot 5x = 5^{-1} \cdot 10 \iff x = 2$  as  $5^{-1} \cdot 5 = 1$  and  $5^{-1} \cdot 10 = 2$ .
- We have learnt how to write a system of n linear equations in n variables in the matrix form AX = B.
- To solve AX = B, we therefore need an operation that is analogous to multiplication by the 'reciprocal' of A. We have defined, whenever possible, a matrix  $A^{-1}$  that serves this function (i.e.,  $A^{-1} \cdot A = \text{Identity Matrix}$ ).
- Then, whenever possible, we can write the solution of AX = B as  $AX = B \iff A^{-1} \cdot AX = A^{-1} \cdot B \iff X = A^{-1} \cdot B$ .

# Example 1 (Part II)

Using the results verified in Example 1 (Part I) and our *Guiding Light* ( $\equiv$  Principle), solve the following systems of linear equations by transforming them into matrix form

$$\begin{cases} 3x + 5y = 7 \\ 2x + 4y = 6 \end{cases}$$

$$\begin{cases} 3x + 5y - z = 10 \\ 2x - y + 3z = 9 \\ 4x + 2y - 3z = -1 \end{cases}$$

$$\begin{cases} 3 \times + 5 \text{ y} = 7 \\ 2 \times + 4 \text{ y} = 6 \end{cases} \longrightarrow \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$$

$$\begin{cases} A_1 \\ \text{from (Part 1)} \end{cases}$$

$$\begin{cases} B_1 = \begin{bmatrix} 2 & -5/2 \\ -1 & 3/2 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 & -5/2 \end{bmatrix} \begin{bmatrix} 7 \\ 7 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -5/2 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 & -5/2 \end{bmatrix} \begin{bmatrix} 7 \\ -1 & 3/2 \end{bmatrix} \begin{bmatrix} 6 \\ 9 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix}$$

$$\begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 2 & -\frac{5}{2} \\ -1 & \frac{3}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & -\frac{5}{2} \\ -1 & \frac{3}{2} \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix}$$

$$B_{1} \qquad B_{1} \qquad A_{1}$$

easy bout Hedious ....

$$\begin{bmatrix} 3 & 5 & -1 \\ 2 & -1 & 3 \\ 4 & 2 & -3 \end{bmatrix} \begin{bmatrix} -\frac{3}{73} & \frac{13}{73} & \frac{14}{73} \\ \frac{14}{73} & -\frac{5}{73} & -\frac{11}{73} \\ \frac{14}{73} & \frac{14}{73} & -\frac{13}{73} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$A2$$

$$B2$$

and 
$$B_2 \cdot A_2 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 ... very tedious!

$$\begin{cases} 3 \times + 5 y = 7 \\ 2 \times + 4 y = 6 \end{cases} \longrightarrow \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$$

$$\begin{cases} A_1 \\ A_2 \\ A_3 \\ A_4 \\ A_4 \\ A_4 \\ A_4 \\ A_5 \\ A_4 \\ A_4 \\ A_4 \\ A_4 \\ A_4 \\ A_5 \\ A_6 \\ A_1 \\ A_1 \\ A_2 \\ A_2 \\ A_3 \\ A_4 \\ A_4 \\ A_4 \\ A_4 \\ A_4 \\ A_5 \\ A_6 \\ A_1 \\ A_1 \\ A_1 \\ A_2 \\ A_1 \\ A_2 \\ A_3 \\ A_4 \\ A_4 \\ A_4 \\ A_4 \\ A_5 \\ A_6 \\ A_1 \\ A_1 \\ A_2 \\ A_1 \\ A_2 \\ A_3 \\ A_4 \\ A_4 \\ A_4 \\ A_5 \\ A_6 \\ A_1 \\ A_1 \\ A_2 \\ A_1 \\ A_2 \\ A_3 \\ A_4 \\ A_4 \\ A_4 \\ A_5 \\ A_1 \\ A_2 \\ A_2 \\ A_3 \\ A_4 \\ A_4 \\ A_4 \\ A_5 \\ A_1 \\ A_2 \\ A_3 \\ A_4 \\ A_4 \\ A_5 \\ A_5 \\ A_5 \\ A_2 \\ A_4 \\ A_5 \\ A_2 \\ A_4 \\ A_5 \\ A_$$

## **Properties of Matrix Inverses**

The following properties of matrix inverses are often useful.

#### **Properties of Matrix Inverses**

Suppose A and B are both invertible  $n \times n$  matrices then

- $\blacksquare$   $A^{-1}$  is unique;
- $(A^{-1})^{-1} = A;$
- $\blacksquare$   $(AB)^{-1} = B^{-1}A^{-1}$ ;
- $(A^T)^{-1} = (A^{-1})^T$ .

# How do we find the inverse (if possible) of a matrix?

- First of all the matrix has to be a square matrix!
- Suppose n = 2. For example,  $A = \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix}$ .
- We need to find a matrix  $B = \begin{bmatrix} x & y \\ z & w \end{bmatrix}$  such that  $AB = I_2 = BA$ .

$$AB = I_2 \qquad \Longleftrightarrow \qquad \begin{bmatrix} 3x + 5z & 3y + 5w \\ 2x + 4z & 2y + 4w \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{cases} 3x + 5z = 1 \\ 2x + 4z = 0 \end{cases} \text{ and } \begin{cases} 3y + 5w = 0 \\ 2y + 4w = 1 \end{cases}$$

$$\begin{bmatrix} 3 & 5 & 1 & 0 \\ 2 & 4 & 0 & 1 \end{bmatrix} \rightsquigarrow \dots \text{row reduce...} \rightsquigarrow \begin{bmatrix} 1 & 0 & 2 & -5/2 \\ 0 & 1 & -1 & 3/2 \end{bmatrix}$$

# Warning (using the other condition)

- Consider again the matrix  $A = \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix}$ .
- We need to find a matrix  $B = \begin{bmatrix} x & y \\ z & w \end{bmatrix}$  such that  $AB = I_2 = BA$ .
- Suppose we impose instead the condition  $BA = I_2$ .

$$BA = I_2 \qquad \Longleftrightarrow \qquad \begin{bmatrix} 3x + 2y & 5x + 4y \\ 3z + 2w & 5z + 4w \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

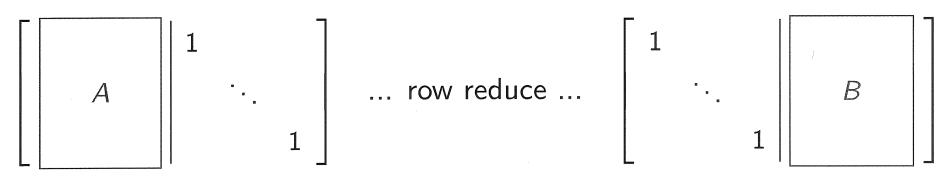
$$\begin{cases} 3x + 2y = 1 \\ 5x + 4y = 0 \end{cases} \text{ and } \begin{cases} 3z + 2w = 0 \\ 5z + 4w = 1 \end{cases}$$

$$\begin{bmatrix} 3 & 2 & 1 & 0 \\ 5 & 4 & 0 & 1 \end{bmatrix}$$
 ...row reduce...  $\sim \begin{bmatrix} 1 & 0 & 2 & -1 \\ 0 & 1 & -5/2 & 3/2 \end{bmatrix}$ 

**Morale:** We work with the transpose of A and of  $A^{-1}$ .

# General Method for finding (if possible) the inverse

- Let A be an  $n \times n$  matrix. Finding a matrix B with  $AB = I_n$  results in n linear systems, each consisting of n equations in n unknowns.
- The corresponding augmented matrices have the same matrix A on their left side and a column of 0's and a single 1 on their right side.
- By solving these *n* systems simultaneously, we can speed up the process of finding the inverse matrix.
- To do so, we construct the augmented matrix  $[A \mid I_n]$ . We row reduce to obtain, if possible, the augmented matrix  $[I_n \mid B]$ .



The matrix B, if it exists, is the inverse  $A^{-1}$  of A.

# Example 2

Find the inverse of the 3 
$$\times$$
 3 matrix  $A = \begin{bmatrix} -1 & 3 & -1 \\ 2 & -2 & 3 \\ -1 & 1 & 2 \end{bmatrix}$ 

To find the inverse of 
$$A = \begin{bmatrix} -1 & 3 & -1 \\ 2 & -2 & 3 \\ -1 & 1 & 2 \end{bmatrix}$$

We built the metrix

$$\begin{bmatrix} -1 & 3 & -1 & | & 1 & 0 & 0 \\ 2 & -2 & 3 & | & 0 & 1 & 0 \\ -1 & 1 & 2 & | & 0 & 0 & | \end{bmatrix}$$
and we row reduce to obtain

$$\begin{bmatrix} 1 & 0 & 0 & | & 1/2 & 1/2 \\ 0 & 1 & 0 & | & 1/2 & 1/4 \\ 0 & 0 & 1 & | & 0 & | & 1/4 \\ 0 & 0 & 1 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 1/4 \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | & 0 & | & 0 & | \\ 0 & 1/4 & 1/4 & | & 0 & | & 0 & | & 0 & | & 0 & | &$$

### General Formula for a 2x2 Matrix

For simplicity we write 
$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
 instead of  $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ .

- Construct the augmented matrix  $\begin{bmatrix} a & b & 1 & 0 \\ c & d & 0 & 1 \end{bmatrix}$ .
- Perform the Gaussian Elimination Algorithm. Set  $\Delta = ad bc$ .

#### The Inverse of a $2 \times 2$ Matrix

Let 
$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
 be a  $2 \times 2$  matrix.

- We define det(A) = ad bc.
- A is invertible ( $\equiv$  nonsingular) if and only if  $\det(A) \neq 0$ .

In particular, 
$$A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Looking back at the formula for  $A^{-1}$ , where A is a  $2 \times 2$  matrix whose determinant is nonzero, we see that, to find the inverse of A

- $\blacksquare$  we divide by the determinant of A,
- $\blacksquare$  switch the diagonal elements of A,
- change the sign of the off-diagonal elements.

If the determinant is equal to 0, then the inverse of A does not exist.

# Example 3

Find the inverse of the matrix

$$A = \begin{bmatrix} 1 & 5 \\ 2 & 7 \end{bmatrix}$$

$$B = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 5 \\ 2 & 7 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 5 \\ 2 & 7 \end{bmatrix}$$
  $det(A) = 1.7 - 2.5$ 

$$\Delta = -\frac{1}{3} \cdot \begin{bmatrix} 7 & -5 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} -\frac{7}{3} & \frac{5}{3} \\ \frac{2}{3} & -\frac{1}{3} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{7}{3} & \frac{5}{3} \\ \frac{2}{3} & -\frac{1}{3} \end{bmatrix}$$

$$B = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$$
  $det(B) = 0 \cdot 1 - 1 \cdot 1 = -1$ 

$$B' = \frac{1}{-1} \begin{bmatrix} 1 & -1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix}$$

The determinant can be defined for any  $n \times n$  matrix. The general formula is computationally complicated for  $n \geq 3$ .

We mention the following important result. Part (2) below will be of particular interest to us in the near future.

#### Theorem

Suppose that A is an  $n \times n$  matrix, and X and X and X are X matrices. Then

- A is invertible ( $\equiv$  nonsingular) if and only if  $det(A) \neq 0$ .
- The matrix equation ( $\equiv$  system of linear equations)  $AX = \mathbf{0}$  has a **nontrivial solution**  $\iff$  A is **singular**  $\iff$   $\det(A) = 0$ .

# Example 4

Find the solution of the following matrix equations ( $\equiv$  systems of linear equations)

$$\begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & -1 \\ 8 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

(\*) 
$$\begin{bmatrix} 1 & 2 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} 7 \\ 7 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
Notice that 
$$A^{-1} = \frac{1}{1.5 - 2.3} \cdot \begin{bmatrix} .5 & -2 \\ -3 & 1 \end{bmatrix} = \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix}$$
thus; if we multiply both sides by  $A^{-1}$  we obtain 
$$\begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ 1 \end{bmatrix} = \begin{bmatrix} -5 & 2 \\ 1 \end{bmatrix} \begin{bmatrix} 0 \end{bmatrix}$$

thus; if we multiply both sides by 
$$A^{-1}$$
 we obtain 
$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -5 & 2 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$A^{-1} A$$

Thus 
$$X = 0$$
 $y = 0$ 

\* 
$$\begin{bmatrix} 4 & -1 \end{bmatrix} \begin{bmatrix} x \\ 8 & -2 \end{bmatrix} \begin{bmatrix} y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Notice that  $\det(A) = 4(-2) - (-1)8 = 0$ 

Thus  $A^{-1}$  does not exist. In other words  $A$  is not invertible  $(= A \text{ is singular})$ 

If we now reduce
$$\begin{bmatrix} 4 & -1 & 0 \\ 8 & -2 & 0 \end{bmatrix}$$
we obtain 
$$\begin{bmatrix} 1 & -1/4 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

I.e.  $x - \frac{1}{4}y = 0$   $\Rightarrow$   $x = \frac{1}{4}y$ 

if we set  $y = t$  then  $x = \frac{1}{4}t$ .

Thus
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4 & -1 \\
8 & -2
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