## MA 138 - Calculus 2 with Life Science Applications Linear Systems: Theory (Section 11.1) Alberto Corso

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## (c) Which direction field corresponds to the system of DEs in (b)?

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 Sketch the lines in the direction of the eigenvectors. Indicate on each line the direction in which the solution would move if the initial condition is on that line.

From your analysis, the point (0,0) is a:

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Let  $A = \begin{bmatrix} -1 & 3 \\ 3 & 1 \end{bmatrix}$ .

Example 3 (Problem # 8, Exam 4, Spring 2014) (Metapopulations). Many biological populations are subdivided into

Example 2 (Problem #9, Exam 3, Spring 2013)

What are the corresponding eigenvalues?

(a) Show that  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  and  $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  are eigenvectors of A.

 $\frac{d}{dt} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -1 & 3 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}.$ 

(b) Find the general solution of the system of differential equations

smaller subpopulations with limited movement between them. The entire collection of such subpopulations is called a metapopulation. Consider the following model of two subpopulations, where  $x_1$  and  $x_2$  are the number of individuals in each:

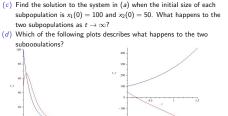
 $\frac{dx_1}{dt} = r_1 x_1 - m_1 x_1 + m_2 x_2 \qquad \frac{dx_2}{dt} = r_2 x_2 - m_2 x_2 + m_1 x_1.$ Here  $r_i$  is the intrinsic growth rate of subpopulation i and  $m_i$  is the per capita movement rate from patch i into the other patch. (a) Suppose  $r_1 = 1$ ,  $r_2 = -2$ ,  $m_1 = 2$ , and  $m_2 = 0$ .

Write the system of differential equations corresponding to these ☐ saddle point (unstable equilibrium) choices. □ source (unstable equilibrium) (b) Find the general solution to the system in (a).

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□ sink (stable equilibrium)

(choose one)



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Example 3 (cont'd)

Example 4 (cont'd)

(b) Describe the long term behavior of your solution. In particular what happens to the temperature of the room and to the block of ice? (c) Which of the pictures below describes the behavior of the two temperatures?

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Fahrenheit (°F).)

Consider the matrix  $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ . It is easy to verify that A has

Example 5 (Problem # 6, Exam 4, Spring 2012)

 $\frac{d}{dt} \begin{vmatrix} I \\ R \end{vmatrix} = \begin{vmatrix} -0.5 & 0.5 \\ 0.25 & -0.25 \end{vmatrix} \begin{vmatrix} I \\ R \end{vmatrix} \qquad \begin{vmatrix} I(0) \\ R(0) \end{vmatrix} = \begin{vmatrix} 32 \\ 74 \end{vmatrix}$ 

Example 4 (Problem # 9, Exam 4, Spring 2013) If a large block of ice is placed in a room we can describe how the temperature of

the block of ice and room are changing using the system of differential equations

 $\frac{dI}{dt} = \alpha(R - I)$   $\frac{dR}{dt} = \beta(I - R),$ 

where I is the temperature of the block of ice. R is the temperature of the room

and  $\alpha$  and  $\beta$  are positive constants that determine the relationship between the rates of change of the temperatures of the block of ice and room and the difference between these temperatures. (All temperatures are measured in degrees

case that  $\alpha = 0.5$ ,  $\beta = 0.25$ , I(0) = 32, and R(0) = 74. That is

(a) Find the solution of the given system of linear differential equations in the

repeated eigenvalues  $\lambda_1 = \lambda_2 = 1$  and that every eigenvector of A is of the form  $c \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ , where c is a real number different from 0.

 $\begin{cases} \frac{dx_1}{dt} = x_1 + 2x_2 \\ \frac{dx_2}{t} = x_2 \end{cases}$ 

Consider, now, the corresponding system of linear differential equations given by the above matrix:

(or, more concisely,  $\frac{d\mathbf{x}}{dt} = A \cdot \mathbf{x}(t)$ .)

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(a) Show that $\mathbf{x}(t) = e^{\mathbf{t}} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is a solution of the given system of
differential equations.
(b) Show that $\mathbf{x}(t) = te^t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + e^t \begin{bmatrix} 0 \\ 0.5 \end{bmatrix}$ is a (second
independent) solution of the given system of differential equations.

w are real-valued vectors.  $e^{x+iy} = e^x(\cos y + i \sin y),$ Using Fuler's formula it can be shown that the typical solutions of the DEs can be written as  $e^{(a\pm ib)t}(\mathbf{u}\pm i\mathbf{w})=\mathbf{g}(t)\pm i\mathbf{h}(t)$ 

where both h(t) and g(t) form the family of real solutions of the given

 $\mathbf{g}(t) = e^{at}(\mathbf{u}\cos(bt) - \mathbf{w}\sin(bt))$   $\mathbf{h}(t) = e^{at}(\mathbf{w}\cos(bt) + \mathbf{u}\sin(bt)).$ 

The case of complex eigenvalues and eigenvectors Suppose that the linear system of DEs dx/dt = Ax, where A is a 2 × 2 matrix with real coefficients, has two complex (conjugate) eigenvalues

 $\lambda_{1,2} = a \pm ib$  with corresponding eigenvectors  $\mathbf{v}_{1,2} = \mathbf{u} \pm i\mathbf{w}$ , where  $\mathbf{u}$  and

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system of DEs. More precisely

Example 6 (Online Homework #9)

Example 5 (cont'd)

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Consider the linear system 
$$\mbox{\bf y}' = \left[ \begin{array}{cc} 3 & 2 \\ -5 & -3 \end{array} \right] \mbox{\bf y}.$$

(a) Find the eigenvalues and eigenvectors for the coefficient matrix.

Write the system of differential equations corresponding to these choices. (b) Find the real valued solution to the initial value problem

 $\begin{cases} y_1' = 3y_1 + 2y_2 & y_1(0) = -9, \\ y_2' = -5y_1 - 3y_2 & y_2(0) = 10. \end{cases}$ 

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Use t as the independent variable in your answer.