

**Spectral Geometry of Eigenvalues and  
Resonances: A Retrospective on the  
Work of Robert Brooks**

*Dedicated To The Memory of Robert Brooks  
1952–2002*

Peter A. Perry  
Department of Mathematics  
University of Kentucky  
Lexington, Kentucky 40506-0027

## Outline

1. Introduction: Inverse Spectral Geometry
2. Part I: The Sunada Construction and Counterexamples
3. Part II: Cheeger's Constant, Cheeger Finiteness, and Isospectral Sets of Metrics
4. Conclusion

## Inverse Spectral Geometry: Compact Manifolds

- $X$  is a compact Riemannian manifold
- $\Delta_X$  is the Laplace-Beltrami operator on functions (with boundary conditions if  $\partial X \neq \emptyset$ )
- $\text{Spec}(X, g) = \{\lambda_j\}_{j=1}^{\infty}$  is the spectrum of  $\Delta_X$

Two manifolds  $X_1$  and  $X_2$  are *isospectral* if  $\text{Spec}(X_1) = \text{Spec}(X_2)$

The *isospectral set* of  $X$  is the set of all Riemannian manifolds isospectral to  $X$

**Conjecture:** If  $X$  has dimension two or three, the isospectral set of  $X$  is finite.

## Inverse Spectral Geometry: Non-Compact Manifolds

- $X$  is a complete, non-compact manifold with “simple geometry at infinity”
- $\Delta_X$  is the Laplacian on  $X$
- $R(z) = (\Delta_X - z)^{-1}$  is meromorphic on a cut plane  $\mathbb{C} \setminus [c, \infty)$  for some  $c \geq 0$
- $R(z)$  admits meromorphic continuation to a covering of  $\mathbb{C}$

Poles of the meromorphic continuation of  $R(z)$  are called *scattering poles*

Examples:

- Exterior domains in  $\mathbf{R}^n$
- Compactly supported metric perturbations of  $\mathbf{R}^n$
- Geometrically finite hyperbolic manifolds

The *isopolar set* of  $X$  is the set of all manifolds with the same scattering poles

**Conjecture:** In “low dimension” the isopolar set of a given manifold  $X$  is finite.

## **Part I: The Sunada Construction and Counterexamples**

It is rather remarkable that all of the examples of isospectral surfaces, as well as all of the examples of Theorem 0.1, can be constructed from a single Sunada triple.

Robert Brooks and Orit Davidovich,  
“Isoscattering on Surfaces” (2002)

## Sunada's Method

Sunada (1985) gave a group-theoretic condition for producing pairs of isospectral manifolds. For a finite group  $G$  and an element  $g \in G$ , denote by  $[g]$  the  $G$ -conjugacy class of  $g$ .

**Definition** A finite group  $G$  and subgroups  $H_1$  and  $H_2$  are a *Sunada triple* if

$$\# ([g] \cap H_1) = \# ([g] \cap H_2)$$

**Theorem** *Suppose  $(G, H_1, H_2)$  are a Sunada triple. Suppose that  $X_0$  is a compact Riemannian manifold and  $\phi : \pi_1(X_0) \rightarrow G$  is an onto homomorphism. If  $X_1$  and  $X_2$  are finite covers of  $X_0$  with respective fundamental groups  $\phi^{-1}(H_1)$  and  $\phi^{-1}(H_2)$ , then  $X_1$  and  $X_2$  are isospectral.*

**Example** Let  $G = PSL(3, \mathbb{Z}/2)$ , and let

$$H_1 = \left\{ \begin{pmatrix} * & * & * \\ 0 & * & * \\ 0 & * & * \end{pmatrix} \right\}, \quad H_2 = \left\{ \begin{pmatrix} * & 0 & 0 \\ * & * & * \\ * & * & * \end{pmatrix} \right\}$$

Then  $(G, H_1, H_2)$  is a Sunada triple.

- The outer automorphism  $A \mapsto (A^{-1})^t$  takes elements in  $H_1$  to  $G$ -conjugate elements in  $H_2$
- There are generators  $A$  and  $B$  of  $G$  so that  $A$ ,  $B$ , and  $AB$  have order 7
- There are generators  $A'$  and  $B'$  of  $G$  so that  $[A', B']$  has order 7

Using this Sunada triple, Brooks and Tse proved:

**Theorem** (*Brooks-Tse 1987*) *There are isospectral Riemann surfaces of genus 4 and 6 having constant curvature, and isospectral surfaces of genus 3 having variable curvature.*

In this case,  $X_0$  is the sphere with three singular points, each singular point having order 7.

The homomorphism  $\phi : \pi_1(X) \rightarrow G$  is given by:

$$\begin{aligned}\phi(\gamma_1) &= A \\ \phi(\gamma_2) &= B \\ \phi(\gamma_3) &= AB\end{aligned}$$

where  $\gamma_i$  are loops around the singular points.

Remarkably, this construction can be revised to yield examples of isopolar two-dimensional surfaces.

**Theorem** (*Brooks-Perry 2001*) *There are manifolds  $X_1$  and  $X_2$  so that:*

- (1)  $X_1$  and  $X_2$  are isometric to  $\mathbb{R}^2$  outside a compact set
- (2)  $X_1$  and  $X_2$  have the same scattering phase and scattering poles

The Sunada technique also yields congruence surfaces with the same eigenvalues and scattering phase.

Recall that a subgroup of  $PSL(2, R)$  is a *congruence group* if it contains a subgroup of the form

$$\left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} : \begin{pmatrix} a & b \\ c & d \end{pmatrix} \simeq \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \pmod{k} \right\}$$

A *congruence surface* is a hyperbolic manifold  $\Gamma \backslash \mathbb{H}_2$  where  $\Gamma$  is a congruence subgroup of  $PSL(2, R)$ .

- Congruence surfaces have infinite discrete spectrum
- Congruence subgroups have a rigid algebraic structure

**Theorem** (*Brooks-Davidovich 2002*) *There exist isoscattering congruence surfaces  $X_1$  and  $X_2$ .*

## **Part II: Cheeger's Constant, Cheeger Finiteness, and Isospectral Sets**

War is the continuation of diplomacy  
by other means.

*Carl von Clausewitz*

Analysis is the continuation of geom-  
etry by other means.

*Robert Brooks*

## Cheeger's Constant

- $X$  is a closed Riemannian manifold
- $S$  is a hypersurface dividing  $X$  into two parts,  $A$  and  $B$
- Cheeger's constant for  $X$  is

$$h(X) = \inf_S \left( \frac{\text{area}(S)}{\min(\text{vol}(A), \text{vol}(B))} \right)$$

**Theorem** (Cheeger 1969) Let  $\lambda_1(X)$  be the first nontrivial eigenvalue of  $X$ . Then

$$\lambda_1 \geq \frac{1}{4}h(X)^2.$$

**Theorem** (Buser 1982) *Let  $X$  be a closed Riemannian manifold with*

$$\text{Ricc}(X) \geq -c.$$

*There are constants  $c_1$  and  $c_2$  depending on  $c$  with*

$$\lambda_1(X) \leq c_1 h + c_2 h^2.$$

Brooks realized that there was a broader relationship between isoperimetric constants and the spectrum which could be exploited to study isospectral sets.

## Background

**Theorem** (*Osgood, Phillips, Sarnak 1988*)  
*Let  $\{X_k\}$  be a sequence of closed Riemannian surfaces with the same spectrum. The  $X_k$  are diffeomorphic, and there a subsequence of the metrics on  $X_k$  which converge in the  $C^\infty$  topology to a nondegenerate limiting metric.*

The proof exploits the heat invariants and the determinant of the Laplacian.

## Heat Invariants

If  $\dim(X) = n$  and  $\partial X$  is empty, then as  $t \downarrow 0$ :

$$\begin{aligned}\mathrm{Tr} \exp(-t\Delta_X) &= \sum_{j=0}^{\infty} \exp(-t\lambda_j) \\ &\sim (4\pi t)^{-n/2} \sum_{j=0}^{\infty} a_j t^j\end{aligned}$$

Here

$$a_0 = \mathrm{vol}(X)$$

$$a_1 = \frac{1}{6} \int_X \mathrm{Scal}(X) dg$$

$$a_2 = \frac{1}{360} \int_X \left[ 5 |\mathrm{Scal}(X)|^2 - 2 |\mathrm{Ricc}(X)|^2 + 2 |\mathrm{Riem}(X)|^2 \right] dg$$

The heat invariants:

- Fix the diffeomorphism class of an oriented surface
- Are an infinite sequence of 'nonlinear Sobolev norms' of the curvature
- Are trivial for constant curvature metrics

The determinant of the Laplacian is defined by zeta-function regularization. In two dimensions:

- Its conformal variation can be explicitly calculated
- It is extremal on constant curvature metrics
- It is a proper function on the moduli space of a compact surface

These properties play a crucial role in the analysis of isospectral sets. What about three dimensions?

## First Steps

**Theorem** (Brooks, Perry, Yang 1989) *Suppose  $(X, g)$  is a closed three-dimensional manifold and  $g$  is conformally equivalent to a metric of constant negative scalar curvature. Then the set of conformal factors  $\varphi$  with*

$$\text{Spec}(X, g) = \text{Spec}(X, e^\varphi g)$$

*is compact in  $C^\infty(X)$ .*

**Theorem** (Chang, Yang 1990) *The same holds true if  $g$  is conformally equivalent to a metric of zero or positive scalar curvature.*

Note that the case treated by Chang and Yang requires a *much* more subtle analysis. In each case, the conformal deformation equation is used to link integral bounds on curvature to bounds on the conformal factor. A key role is played by estimates for  $\lambda_1$  in terms of the conformal factor.

## Leaving Conformal Classes: Cheeger Finiteness

Let  $\mathcal{M}$  be the space of all Riemannian metrics on a fixed smooth manifold  $X$ .

**Theorem** (*Cheeger 1970, Gromov 1981*) *The set of all  $n$ -dimensional manifolds  $(X, g)$  with*

- $|\nabla^j \text{Riem}(X)|_{C^0(X)} \leq \Lambda, 0 \leq j \leq k$
- $\text{vol}(X) \geq v > 0$ , and
- $\text{diam}(X) \leq D$

*contains only finitely many diffeomorphism types, and is precompact in the  $C^{k+1, \alpha}$ -topology on  $\mathcal{M}$  for any  $\alpha < 1$ .*

Key issues:

- Bounding analytic Sobolev constants from above
- Bounding the diameter from below

**Theorem** (Anderson 1991; Brooks, Perry, and Petersen 1992) *The space of isospectral compact isospectral 3-manifolds  $X$  for which the length of the shortest closed geodesic is bounded below:*

$$l_X \geq \ell > 0 \tag{1}$$

*is compact in the  $C^\infty$  topology. In particular, there are only finitely many diffeomorphism types of isospectral manifolds satisfying (1).*

Cheeger's and Buser's results suggest that isoperimetric constants can be controlled directly from the spectrum. Gallot (1988) showed how to estimate volumes of tubes in terms of isoperimetric constants and  $L^p$  estimates on the curvature. Brooks realized that these estimates could be used to construct test functions for the low-lying eigenvalues of the Laplacian and so obtain spectral bounds on the isoperimetric constants.

## Sobolev Constants

- The ‘analytic Sobolev constant’:

$$C^S = \inf \left\{ \inf_{a \in \mathbf{R}} \left( \frac{\|df\|_{L^2}}{\|f + a\|_{2n/(n-2)}} \right) : f \in C^\infty(X) \right\}$$

- The ‘isoperimetric Sobolev constant’:

$$C_S = \inf \left( \frac{\text{area}(S)}{(\inf(\text{vol}(A), \text{vol}(B)))^{1-1/n}} \right)$$

## Compactness for ‘Nearly’ Constant Scalar Curvature Metrics

$g$ -orthogonal decomposition of Ricci curvature:

$$\text{Ricc}(X) = \text{Scal}(X) \oplus \text{Ricc}_t(X)$$

Here  $\text{Ricc}_t(X)$  is the traceless Ricci tensor.

Define the *reduced scalar curvature*

$$\text{Scal}_r(X) = \text{Scal}(X) - \frac{1}{\text{vol}(X)} \int_X \text{Scal}(X) dg$$

Define the *reduced Riemann tensor*  $\text{Riem}_r$  (if  $\dim(X) = 3$ ) by

$$\text{Riem}_r(X) = \text{Scal}_r(X) \oplus \text{Ricc}_t(X)$$

Note that  $\text{Riem}_r(X) = 0$  if  $X$  has constant scalar curvature.

**Theorem** (Brooks, Perry, Petersen 1994) For  $n = 2$  and  $n = 3$  there are constants  $Q(n)$  and  $K(n, k)$  so that if

$$\lambda_k > Q(n) \int_X \text{Scal}(X) dg$$

and

$$\lambda_k > K(k) \frac{\left( \int_X |\text{Riem}_r(X)|^2 dg \right)^{1/2}}{\sqrt{\text{vol}(X)}}$$

then the set of all manifolds isospectral to  $(X, g)$  is compact in the  $C^\infty$  topology on metrics.

- The Sobolev constant is controlled by building test-functions for low-lying eigenvalues in ‘slices’ about the minimizing hypersurface  $S$  for  $C_S$
- One has  $K(k) \sim k^2$  as  $k \rightarrow \infty$  but by Weyl’s law  $\lambda_k \sim k^2/3$

## Conclusion

Finally, I would like to take this opportunity to thank my colleagues, including those present at the conference and those who could not attend, for making spectral geometry a truly pleasant and exciting area in which to work. While it is my hope that the picture presented here will induce some to join this area of research, I think that a far greater inducement would be the opportunity to get to know, and to be a part of, the community which occupies itself with these questions.

*Robert Brooks, "Inverse Spectral Geometry" (Review paper, 1997)*

Perhaps Brooks' most enduring mathematical legacy is his influence upon his students and colleagues. He had a vision of mathematics as a cooperative, collaborative endeavor, and his generosity in sharing his ideas and in collaborating widely has had a profound impact upon an entire generation of spectral geometers.

*Carolyn Gordon and David Webb,*  
September 2002