

DEPARTMENT OF MATHEMATICS

Ma 322 Solved First Exam February 17, 2017

With supplements

1. Points: 4+7+4

You are given an augmented matrix of a linear system of equations. Here t is a parameter:

$$\left[\begin{array}{ccc|c} 1 & 1 & -1 & 0 \\ -4 & 1 & -4-t & 0 \\ -3 & 2 & -3+t & 0 \end{array} \right]$$

answer the following questions

(a) Carefully define what is meant by a system of linear equations to be consistent.

A Linear system of equations may be represented as $AX = B$ where A is an $m \times n$ matrix of scalars, X is a column of n variables and B is a column of m scalars.

It is said to be consistent if there is a vector $v \in \mathfrak{R}^n$ such that $Av = B$.

For a scalar field K other than \mathfrak{R} the vector is assumed to be in K^n .

(b) Explain why the above linear system of equations is consistent for all values of t . Be sure to explain how your conclusion is consistent with your definition.

Our current system is of the form $AX = 0$. If we take v to be the zero vector in \mathfrak{R}^n , then $Av = 0$ is true, regardless of the entries of A . Hence it is consistent for all values of t .

(c) Find all values of t for which the above linear system has **infinitely many solutions**. Be sure to justify your answer.

Since a system $AX = 0$ always has one solution $X = 0$ it is called the trivial solution. It can have infinitely many solutions iff it has at least one non trivial (i.e. non zero) solution w . The equation $Aw = 0$ for a non trivial w implies that the columns of A are linearly dependent. Thus, the necessary and sufficient condition for infinitely many solutions is that the rank of A is less than its number of columns ($colnum(A)$).

For our 3×3 matrix A , this means its rank is less than 3. The easiest calculation is to note that

$$\det(A) = 1((-3+2) - 2(-4-t)) - 1(-4(-3+t) - (-3)(-1-t)) + (-1)(-4(2) - (-3)(1)) = 10+10t.$$

Thus, the answer is that $t = -1$ is the only value giving infinitely many solutions.

You may also find the rank from an REF of A :

$$\begin{pmatrix} 1 & 1 & -1 \\ 0 & 5 & -8-t \\ 0 & 0 & 2+2t \end{pmatrix}. \text{ Clearly, this has rank less than 3 iff } 2+2t = 0, \text{ i.e. } t = -1.$$

2. **Points: 3+3+4+5**

(a) Complete the definition:

A set of vectors $S = \{v_1, v_2, \dots, v_r\}$ is said to be **linearly dependent** if :

There are scalars a_1, a_2, \dots, a_r such that $a_1v_1 + a_2v_2 + \dots + a_rv_r = 0$ and at least one of a_1, \dots, a_r is non zero. In other words $AX = 0$ has at least one non trivial solution.

Alternatively, we have an equivalent definition which says: there is an s with $1 \leq s \leq r$ such that v_s is a linear combination of v_1, \dots, v_{s-1} .

(b) Explain why the two columns of the matrix $A = \begin{bmatrix} 3 & 6 \\ -2 & -6 \\ -4 & -4 \end{bmatrix}$ are

linearly independent. Be sure to justify your answer in terms of your definition.

In terms of our first definition, we need to solve $AX = 0$ and determine that we have only the trivial solution. If we take v_1, v_2 as the columns of A in order, then we are solving $a_1v_1 + a_2v_2 = 0$. This gives 3 equations $3a_1 + 6a_2 = 0, -2a_1 - 6a_2 = 0, -4a_1 - 4a_2 = 0$. This gives $a_1 = -2a_2, a_1 = -3a_2, a_1 = -a_2$ respectively. The first two already force $a_1 = 0 = a_2$.

If we use the second definition then our s is 1 or 2. If $s = 1$ then $v_1 = 0$ (since the definition implies v_1 is a linear combination of an empty set of vectors!)

If $s = 2$, then we must have $v_2 = a_1v_1$ for some a_1 . But the three different rows give inconsistent values for a_1 , namely 2, 3, 1 respectively.

This definition can give a quicker result using determinants. If v_2 is a multiple of v_1 , then all 2×2 subdeterminants of A must be zero! So, we simply need to find a non zero subdeterminant, e.g. the one formed by the top two rows gives $-18 + 12 = -6 \neq 0!$

(c) Determine a vector v in \mathbb{R}^3 such that v is **not** in $Col(A)$. You must justify your claim.

The condition is equivalent to the three columns v_1, v_2, v being independent. It is easy to note this by using the second definition since $v \in Col(A)$ means the three vectors are dependent.

So, all we need is a convenient independent vector. Try $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$. You can

show the determinant of the resulting 3×3 matrix to be $(1)(-6) \neq 0$.

Alternatively, you can determine the rank by an easy row reduction.

(d) Determine if the set of three vectors consisting of your v together with the two columns of the matrix A **linearly dependent**.

We already arranged the vectors to be linearly independent!

3. **Points: 4+4+3+4**

You are given a matrix A and a REF M of the augmented matrix $A|I$.

Use these to answer the following questions.

$$A = \begin{bmatrix} -2 & -6 & -8 \\ 2 & 2 & 4 \\ 4 & 8 & 12 \end{bmatrix} \text{ and } M = \left[\begin{array}{ccc|ccc} -2 & -6 & -8 & 1 & 0 & 0 \\ 0 & -4 & -4 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 1 \end{array} \right]$$

(a) Given any column vector $v \in \mathfrak{R}^3$ is it true that the equation $AX = v$ is consistent? Be sure to justify your claim.

Consider the vector $v = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$. The given REF of $(A|I)$ informs us

that the REF of $(A|v)$ will be the matrix formed by dropping the columns numbered 4, 5 from M . This produces an inconsistent third row equation $0 = 1$.

So, the answer is no! An alternate argument would be that $AX = v$ is consistent for all v iff all v are in $Col(A)$, i.e. $Col(A) = \mathfrak{R}^m$ where $rownum(A) = m$. In our situation, $m = 3$.

But this requires that $rank(A) = rownum(A) = 3$ and the left hand part of M shows the rank to be 2.

(b) In case your answer is “no”, determine the consistency matrix G , i.e. a matrix G such that $AX = v$ is consistent if and only if $Gv = 0$.

Hint: You may find the answer in the matrix M . As established in the class notes, the matrix G is simply the matrix on the right hand side of the matrix of zero rows in the REF of $(A|I)$. So $G = \begin{pmatrix} 1 & -1 & 1 \end{pmatrix}$.

(c) Complete the definition:

A set S of vectors in \mathfrak{R}^n is a spanning set for \mathfrak{R}^n if :

every $v \in \mathfrak{R}^n$ is a linear combination of some finite set of vectors from S .

(d) Determine, with proof, if the columns of A give a spanning set for \mathfrak{R}^3 .

Be sure to use your definition.

We have already shown a vector v which is not a combination of the columns of A , since $AX = v$ is inconsistent. So, columns of A do not span \mathfrak{R}^3 .

4. **Points: 3+4+5+3**

You are given a matrix A and its REF M . **Use these to answer the following questions.**

$$A = \begin{bmatrix} -1 & -2 & -3 & -1 \\ -2 & 3 & 1 & -9 \\ 3 & 2 & 5 & 7 \end{bmatrix} \text{ its REF } M = \begin{bmatrix} 1 & 0 & 1 & 3 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

(a) Complete this definition:

Given a matrix H , its null space $Nul(H)$ is defined to be set of all vectors such that

$Hv = 0$, if the vector be named as v . Alternatively, $Nul(H) = \{v \mid Hv = 0.\}$

(b) **Using the given information**, determine $Nul(A)$ completely.

Suppose that $v = \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$. The system $Av = 0$ gives the following three

equations by using the REF. $a + c + 3d = 0, b + c - d = 0, 0 = 0$.

This gives the two pivot variables a, b in terms of the free variables c, d . Hence we have

$$\begin{pmatrix} 1 \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} -c - 3d \\ -c + d \\ c \\ d \end{pmatrix} = c \begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix} + d \begin{pmatrix} -3 \\ 1 \\ 0 \\ 1 \end{pmatrix}.$$

Let v, w be the vectors multiplied by c, d above. This shows that $Nul(A) = Span\{v, w\}$.

(c) Determine a matrix P **with four rows and two linearly independent columns** such that $AP = 0$. You should justify why your answer is correct by using the above calculations.

The two columns v, w will form the matrix P , giving $AP = 0$. The vectors v, w are seen to be independent since the resulting matrix has rank 2. This can be proved by noting the non zero 2 determinant formed by the bottom two rows.

(d) Suppose that a matrix H is invertible. Determine if $Nul(H)$ has a nonzero vector. Justify your answer.

Let $G = H^{-1}$ so that $GH = HG = I$. If $v \in Nul(H)$, then $Hv = 0$. Multiplying by G on the left, we have $GHv = G0$ which simplifies to $Iv = 0$ i.e. $v = 0$. So, for an invertible H , its Null space has only the zero vector.

First Supplement Quiz

1. Define what is meant by “the set of vectors $\{v_1, v_2, v_3\}$ are dependent.”

Answer: $\{v_1, v_2, v_3\}$ are said to be dependent if there are scalars a_1, a_2, a_3 such that $a_1v_1 + a_2v_2 + a_3v_3 = 0$ and at least one of a_1, a_2, a_3 is non zero.

2. Give examples of three **nonzero** vectors v_1, v_2, v_3 in \mathfrak{R}^4 such that they are linearly dependent, but none of the three vectors is a multiple of another.

Answer: Let $v_1 = e_1, v_2 = e_2$ the two independent vectors of the standard basis of \mathfrak{R}^4 . Let $v_3 = e_1 + e_2 = v_1 + v_2$ which gives the required dependence. By being a part of a basis, we know that v_1, v_2 are non zero and not multiples of each other. We claim that $v_3 \neq ke_1$ for any scalar k since that would give $e_1 + e_2 = ke_1$ or $(1 - k)e_1 + e_2 = 0$, making e_1, e_2 dependent, contrary to the assumption. similarly v_3 is not a multiple of e_2 . Alternatively, write down any two non zero v_1, v_2 which are not multiples of each other and then $v_3 = v_1 + v_2$ can be easily checked to satisfy all conditions by finding non zero 2×2 determinants in every two of the three columns.

3. Give examples of three **nonzero** vectors v_1, v_2, v_3 in \mathfrak{R}^4 which are linearly independent.

Answer: Any three elements of the standard basis, say $\{e_1, e_2, e_3\}$ will be independent.

Second Supplement Quiz

1. Define what is meant by “a linear system $AX = B$ is consistent.”

Answer: A linear system $(A|B)$ is consistent if there is some vector v such that $Av = B$.

2. When is a linear system $AX = B$ said to be homogeneous? Prove that a homogeneous linear system is always consistent.

Answer: A linear system $(A|B)$ is said to be homogeneous if B is a zero vector. Since $A0 = 0$, we can take $v = 0$ in the consistency definition for a homogeneous system.

3. Give an example of “a linear system of three equations in three variables x, y, z which is **inconsistent**.” Be sure to explain why it is inconsistent.

Answer: A simplest example would be $(A|B) = \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{array}$ If $Av = B$ for some v , then the bottom entry of Av is zero, but it is 1 for B . Hence it is inconsistent.

4. Determine all values of t for which the following system has more than one solution. Show your argument.

$$\begin{array}{ccc|c} x & y & z & \text{RHS} \\ \hline 1 & 0 & 1 & 0 \\ -1 & 1 & 2-t & 0 \\ 2 & t & t+2 & 0 \end{array}$$

Answer: A homogeneous system $(A|0)$ for a matrix A has only a trivial solution when $\text{rank}(A) = \text{colnum}(A)$. Thus we need values of t for which $\text{rank}(A) < 3$ or $\det(A) = 0$. The value of the determinant is $(1)(t+2) - t(2-t) + 0 + 1(-t-2) = t^2 - 2t$ if we expand by the first row. Hence $t = 0, t = 2$ are the desired values.

Third Supplement Quiz

You are given the following matrices:

$$A = \begin{bmatrix} 1 & 1 & 2 & -1 \\ 2 & 1 & 3 & -2 \\ -1 & 1 & 0 & 1 \\ 1 & 0 & 1 & -1 \end{bmatrix} \text{ and its REF } M = \begin{bmatrix} 1 & 1 & 2 & -1 \\ 0 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

1. Determine the $Nul(A)$ using the given information. The answer must be in the usual parametric form. Show your work.

Answer: We know that $Nul(A) = Nul(M)$ since A and M are related by row transformations. Explicitly $M = HA$ for some invertible H . Thus $AX = 0$ iff $HAX = 0$ iff $MX = 0$. Now, M gives $-y - z = 0$ and $x + y + 2z - w = 0$ by using x, y, z, w in order as the variables for columns of M . If we set $z = s$ and $w = t$, then we get the parametric solution:

$$\begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} = s \begin{pmatrix} -1 \\ -1 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}. \text{ The multipliers of } s, t \text{ give a basis of two independent vectors for } Nul(A).$$

2. Determine if the linear system $(A|B)$ is consistent for all $B \in \mathbb{R}^4$. Prove your claim.

Answer: The answer is no. Since $rank(A) = 2$ as visible in REF, the space $Col(A)$ has dimension $2 < 4 = \dim \mathbb{R}^4$. So $Col(A) \neq \mathbb{R}^4$.

3. Set L to be the linear transformation from \mathbb{R}^n to \mathbb{R}^m defined by the formula $L(X) = AX$.

From the shape of A , decide the values of n, m .

$$n = m = .$$

Answer: $n = m = 4$.

Further, decide if L is injective. Prove your claim.

Answer: No! The condition for injectivity of T_A is that $Nul(A) = 0$. We showed this to be non zero above.

Also decide if L is surjective. Prove your claim.

Answer: No. The surjectivity of T_A requires that $Image(T_A) = Col(A) = \mathbb{R}^4$, the codomain. Since $Col(A)$ has dimension 2 and \mathbb{R}^4 has dimension 4, T_A is not surjective.