Math 322 - Matrix Algebra **SOLUTIONS** Friday, September 25 Ouiz 4 **

1. (4 points) Suppose that

$$A = \begin{pmatrix} 4 & 1 \\ -2 & 2 \\ 3 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 1 & 2 & 3 \\ -2 & 0 & 5 \end{pmatrix}.$$

Name:

Find the matrix products *AB* and *BA*, if they are defined. If either is not defined, simply write NOT DEFINED.

Both products are defined. Since *A* is 3×2 and *B* is 2×3 , the products *AB* and *BA* will be of shape 3×3 and 2×2 , respectively.

$$AB = \begin{pmatrix} 2 & 8 & 17 \\ -6 & -4 & 4 \\ 1 & 6 & 14 \end{pmatrix} \qquad BA = \begin{pmatrix} 9 & 8 \\ 7 & 3 \end{pmatrix}$$

2. (2 points) True/False. No justification required.

If the matrix product *AB* is defined, then the entry in row 2 and column 3 of AB can be computed by pairing row 2 of A with column 3 of B.

3. (4 points)

(a) Let $T_1 : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ be the linear transformation which rotates a vector counterclockwise by 180°. Find the *standard matrix* A_1 corresponding to this transformation. We discussed a general rotation matrix in class, and this has form

$$A = \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix}.$$
$$A_1 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

Plugging in $\theta = 180^{\circ}$ gives

(b) Let $T_2 : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ be the linear transformation which **first** rotates a vector counterclockwise by 180° and **next** reflects across the (vertical) y-axis. Find the standard *matrix* A_2 corresponding to this transformation.

Composing transformations corresponds to multiplying matrices, so we can just multiply our matrix from (a) by the reflection matrix, which is $B = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$. Since the rotation happens first and the reflection second, we put the matrix A_1 on the *right* (so that it interacts with a vector first) and B on the left (so that it meets the vector second).

$$A_2 = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$