MA322-001 Apr 11 Cliff Notes - Properties of orthogonal projection

Let  $\vec{\mathbf{g}}_1, \vec{\mathbf{g}}_2, \vec{\mathbf{g}}_3$  be vectors in a vector space with  $\vec{\mathbf{g}}_i \cdot \vec{\mathbf{g}}_j = 0$  if  $i \neq j$  and with  $\vec{\mathbf{g}}_i \cdot \vec{\mathbf{g}}_i \neq 0$ . Set  $\vec{\mathbf{v}} = x_1 \vec{\mathbf{g}}_1 + x_2 \vec{\mathbf{g}}_2 + x_3 \vec{\mathbf{g}}_3$  and find an expression for  $\|\vec{\mathbf{v}}\|^2 = \|x_1 \vec{\mathbf{g}}_1 + x_2 \vec{\mathbf{g}}_2 + x_3 \vec{\mathbf{g}}_3\|^2$ 

Find an expression for  $\vec{\mathbf{v}} \cdot \vec{\mathbf{g}}_i$ 

Do you need  $\vec{\mathbf{g}}_i \cdot \vec{\mathbf{g}}_j = 0$  for  $i \neq j$ ?

Let  $\vec{\mathbf{u}}$ ,  $\vec{\mathbf{v}}$  and  $\vec{\mathbf{w}}$  be vectors in a vector space where  $\langle \vec{\mathbf{v}}, \vec{\mathbf{v}} \rangle \neq 0$  and  $\langle \vec{\mathbf{a}}, \vec{\mathbf{b}} \rangle = \langle \vec{\mathbf{b}}, \vec{\mathbf{a}} \rangle$ . Define  $\operatorname{proj}_{\vec{\mathbf{v}}}(\vec{\mathbf{w}}) = \frac{\vec{\mathbf{v}} \cdot \vec{\mathbf{w}}}{\vec{\mathbf{v}} \cdot \vec{\mathbf{v}}} \vec{\mathbf{v}}$ .

We have the following properties:

- $\vec{\mathbf{w}} \mapsto \operatorname{proj}_{\vec{\mathbf{v}}}(\vec{\mathbf{w}})$  is linear
- $\operatorname{proj}_{\vec{\mathbf{v}}}(\vec{\mathbf{w}}) = \operatorname{proj}_{\vec{\mathbf{v}}}(\operatorname{proj}_{\vec{\mathbf{v}}}(\vec{\mathbf{w}}))$
- If  $\vec{\mathbf{a}} \cdot \vec{\mathbf{v}} = 0$ , then  $\vec{\mathbf{a}} \cdot \operatorname{proj}_{\vec{\mathbf{v}}}(\vec{\mathbf{w}}) = 0$
- If  $\vec{\mathbf{v}} \cdot \vec{\mathbf{a}} = 0$ , then  $\operatorname{proj}_{\vec{\mathbf{v}}}(\vec{\mathbf{w}}) \cdot \vec{\mathbf{a}} = 0$
- $\vec{\mathbf{v}} \cdot \operatorname{proj}_{\vec{\mathbf{v}}}(\vec{\mathbf{w}}) = \vec{\mathbf{v}} \cdot \vec{\mathbf{w}}$
- $\vec{\mathbf{v}} \cdot (\vec{\mathbf{w}} \operatorname{proj}_{\vec{\mathbf{v}}}(\vec{\mathbf{w}})) = 0$

**Gram-Schmidt**: Replace a sequence of vectors  $\vec{\mathbf{v}}_1, \vec{\mathbf{v}}_2, \ldots$  with a sequence of orthogonal vectors  $\vec{\mathbf{g}}_1, \vec{\mathbf{g}}_2, \ldots$  with the same span.

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For i = 1, 2, ...

Set \vec{\mathbf{g}}_i = \vec{\mathbf{v}}_i

For j = 1, 2, ..., i - 1

Set r_{ij} = \frac{\vec{\mathbf{g}}_j \cdot \vec{\mathbf{g}}_i}{r_{jj}} if r_{jj} \neq 0

Set \vec{\mathbf{g}}_i = \vec{\mathbf{g}}_i - r_{ij}\vec{\mathbf{g}}_j

End For

Set r_{ii} = \vec{\mathbf{g}}_i \cdot \vec{\mathbf{g}}_i

End For

For i = 1, 2, ...

Set r_{ii} = 1

End For
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At the end of the *i*th iteration,  $\vec{\mathbf{v}}_i = r_{i1}\vec{\mathbf{g}}_1 + \ldots + r_{(i-1),1}\vec{\mathbf{g}}_{i-1} + \vec{\mathbf{g}}_i$  and  $\vec{\mathbf{g}}_j \cdot \vec{\mathbf{g}}_k = 0$  for all  $1 \leq j < k \leq i$ . If  $r_{ii} = 0$ , then  $\vec{\mathbf{v}}_i$  is linearly dependent on the previous  $\vec{\mathbf{v}}_j$ , so  $\vec{\mathbf{g}}_i = \vec{\mathbf{0}}$  could be omitted (or replaced with a random vector orthogonal to the previous vectors).

MA322-001 Apr 11 Example - Gram-Schmidt and Least Squares

Let 
$$\vec{\mathbf{v}}_1 = \begin{bmatrix} 4\\4\\7 \end{bmatrix}$$
,  $\vec{\mathbf{v}}_2 = \begin{bmatrix} 16\\7\\10 \end{bmatrix}$ , and let  $A = \begin{bmatrix} \uparrow & \uparrow\\\vec{\mathbf{v}}_1 & \vec{\mathbf{v}}_2\\\downarrow & \downarrow \end{bmatrix}$ . Set  $\vec{\mathbf{b}} = \begin{bmatrix} 1\\6\\5 \end{bmatrix}$  and  $\vec{\mathbf{x}}_1 = \begin{bmatrix} x_1\\x_2 \end{bmatrix}$ .

We want to find  $x_1$  and  $x_2$  so that  $x_1\vec{\mathbf{v}}_1 + x_2\vec{\mathbf{v}}_2 = \vec{\mathbf{b}}$ , that is, find  $\vec{\mathbf{x}}$  so that  $A\vec{\mathbf{x}} = \vec{\mathbf{b}}$ .

We cannot directly use dot products, because the columns of A are not orthogonal. We will replace A with a matrix G that does have orthogonal columns.

We'll keep the first column  $\vec{\mathbf{g}}_1 = \vec{\mathbf{v}}_1$ , but the second column of A points in the  $\vec{\mathbf{g}}_1$  direction:

$$\vec{\mathbf{v}}_2 \cdot \vec{\mathbf{g}}_1 = 162 \qquad \qquad \vec{\mathbf{g}}_1 \cdot \vec{\mathbf{g}}_1 = 81 \qquad \qquad \operatorname{proj}_{\vec{\mathbf{g}}_1}(\vec{\mathbf{v}}_2) = \frac{162}{81}\vec{\mathbf{g}}_1 = 2\vec{\mathbf{g}}_1 = \begin{bmatrix} 8\\ 8\\ 14 \end{bmatrix}.$$

If we set 
$$\vec{\mathbf{g}}_2 = \vec{\mathbf{v}}_2 - \operatorname{proj}_{\vec{\mathbf{v}}_1}(\vec{\mathbf{v}}_2) = \begin{bmatrix} 8 \\ -1 \\ -4 \end{bmatrix}$$
 then  
 $\vec{\mathbf{g}}_1 \cdot \vec{\mathbf{g}}_2 = 0$   $\vec{\mathbf{g}}_2 \cdot \vec{\mathbf{g}}_2 = 81$   $\vec{\mathbf{v}}_2 = 2\vec{\mathbf{g}}_1 + \vec{\mathbf{g}}_2$ 

How does this relate to  $A\vec{\mathbf{x}} = \vec{\mathbf{b}}$ ? Well we can write  $A\vec{\mathbf{x}}$  in terms of G:

$$A\vec{\mathbf{x}} = x_1\vec{\mathbf{v}}_1 + x_2\vec{\mathbf{v}}_2 = x_1\vec{\mathbf{g}}_1 + x_2(2\vec{\mathbf{g}}_1 + \vec{\mathbf{g}}_2) = (x_1 + 2x_2)\vec{\mathbf{g}}_1 + (x_2)\vec{\mathbf{g}}_2$$

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And we can almost write  $\vec{\mathbf{b}}$  in terms of G:

$$\vec{\mathbf{b}} \cdot \vec{\mathbf{g}}_{1} = 63 \qquad \vec{\mathbf{g}}_{1} \cdot \vec{\mathbf{g}}_{1} = 81 \qquad \operatorname{proj}_{\vec{\mathbf{g}}_{1}}(\vec{\mathbf{b}}) = \frac{63}{81}\vec{\mathbf{g}}_{1} = \frac{7}{9}\vec{\mathbf{g}}_{1} = \frac{1}{9} \begin{bmatrix} 28\\28\\49 \end{bmatrix}.$$
  
$$\vec{\mathbf{b}} \cdot \vec{\mathbf{g}}_{2} = -18 \qquad \vec{\mathbf{g}}_{2} \cdot \vec{\mathbf{g}}_{2} = 81 \qquad \operatorname{proj}_{\vec{\mathbf{g}}_{2}}(\vec{\mathbf{b}}) = \frac{-18}{81}\vec{\mathbf{g}}_{1} = \frac{-2}{9}\vec{\mathbf{g}}_{2} = \frac{1}{9} \begin{bmatrix} -16\\2\\8 \end{bmatrix}.$$
  
Now we get sneaky, and set  $\vec{\mathbf{g}}_{3} = \vec{\mathbf{b}} - \operatorname{proj}_{\vec{\mathbf{g}}_{1}}(\vec{\mathbf{b}}) - \operatorname{proj}_{\vec{\mathbf{g}}_{2}}(\vec{\mathbf{b}}) = \frac{1}{3} \begin{bmatrix} -1\\8\\-4 \end{bmatrix}$   
$$\vec{\mathbf{g}}_{1} \cdot \vec{\mathbf{g}}_{3} = 0 \qquad \vec{\mathbf{g}}_{2} \cdot \vec{\mathbf{g}}_{3} = 0 \qquad \vec{\mathbf{g}}_{3} \cdot \vec{\mathbf{g}}_{3} = 9 \qquad \vec{\mathbf{b}} = \frac{7}{9}\vec{\mathbf{g}}_{1} + \frac{-2}{9}\vec{\mathbf{g}}_{2} + \vec{\mathbf{g}}_{3}$$
  
Calculate  $||A\vec{\mathbf{x}} - \vec{\mathbf{b}}||$  using the  $\vec{\mathbf{g}}$ s:

$$\|A\vec{\mathbf{x}} - \vec{\mathbf{b}}\|^2 = \|\left((x_1 + 2x_2)\vec{\mathbf{g}}_1 + (x_2)\vec{\mathbf{g}}_2\right) - \left(\frac{7}{9}\vec{\mathbf{g}}_1 + \frac{-2}{9}\vec{\mathbf{g}}_2 + \vec{\mathbf{g}}_3\right)\|^2$$
  
=  $\|\left(x_1 + 2x_2 - \frac{7}{9}\right)\vec{\mathbf{g}}_1 + \left(x_2 - \frac{-2}{9}\right)\vec{\mathbf{g}}_2 + \vec{\mathbf{g}}_3\|^2$   
=  $(x_1 + 2x_2 - \frac{7}{9})^2\|\vec{\mathbf{g}}_1\|^2 + (x_2 - \frac{-2}{9})^2\|\vec{\mathbf{g}}_2\|^2 + \|\vec{\mathbf{g}}_3\|^2$ 

This is clearly minimized exactly when  $x_1 + 2x_2 = \frac{7}{9}$  and  $x_2 = \frac{-2}{9}$ , that is, when  $\vec{\mathbf{x}} = \frac{1}{9} \begin{bmatrix} 11 \\ -2 \end{bmatrix}$ , but it can never be smaller than  $\|\vec{\mathbf{g}}_3\|^2 = 9$ .

MA322-001 Apr 11 Quiz  
Let 
$$\vec{\mathbf{v}}_1 = \begin{bmatrix} 3\\4\\0 \end{bmatrix}$$
,  $\vec{\mathbf{v}}_2 = \begin{bmatrix} 1\\3\\0 \end{bmatrix}$ , and  $\vec{\mathbf{b}} = \begin{bmatrix} 7\\11\\13 \end{bmatrix}$ .

1. Find vectors  $\vec{\mathbf{g}}_1$  and  $\vec{\mathbf{g}}_2$  with the same span as  $\vec{\mathbf{v}}_1$  and  $\vec{\mathbf{v}}_2$ , except with  $\vec{\mathbf{g}}_1 \cdot \vec{\mathbf{g}}_2 = 0$ .

Name: \_\_\_\_\_

- 2. What is the projection of  $\vec{\mathbf{b}}$  onto  $\vec{\mathbf{g}}_1$
- 3. What is the projection of  $\vec{\mathbf{b}}$  onto  $\vec{\mathbf{g}}_2$
- 4. Define  $\vec{\mathbf{g}}_3=\vec{\mathbf{b}}-\mathrm{proj}_{\vec{\mathbf{g}}_1}(\vec{\mathbf{b}})-\mathrm{proj}_{\vec{\mathbf{g}}_2}(\vec{\mathbf{b}})$
- 5. If you write  $\vec{\mathbf{b}} = y_1 \vec{\mathbf{g}}_1 + y_2 \vec{\mathbf{g}}_2 + y_3 \vec{\mathbf{g}}_3$ , what are  $y_1, y_2$ , and  $y_3$ ?
- 6. Write each  $\vec{\mathbf{v}}_i$  in terms of the  $\vec{\mathbf{g}}_j$ s
- 7. Find the best  $x_1$ ,  $x_2$  so that  $x_1\vec{\mathbf{v}}_1 + x_2\vec{\mathbf{v}}_2$  is as close to  $\vec{\mathbf{b}}$  as possible.
- 8. How far from  $\vec{\mathbf{b}}$  must it be?