An $R \times C$ matrix A with R rows and C columns is a function whose domain is vectors $\vec{\mathbf{c}}, \vec{\mathbf{x}}$ of size C and whose codomain is vectors $\vec{\mathbf{v}}_1, \ldots, \vec{\mathbf{v}}_C, \vec{\mathbf{b}}$ of size R.

We can take linear combinations of functions as long as (a) their domains overlap, and (b) their codomains consist of vectors. For example, if r, s are numbers and A, B are matrices, then rA + sB is the function that takes $\vec{\mathbf{x}}$ to $r(A(\vec{\mathbf{x}})) + s(B(\vec{\mathbf{x}}))$. We can multiply functions as long as the codomain of one is the domain of the other. For example if A has domain vectors of size n and B has codomain vectors of size n, then AB is the function with the same domain as B and the same codomain as A and it takes $\vec{\mathbf{x}}$ from the domain of B to $A(B(\vec{\mathbf{x}}))$ in the codomain of A.

If A, B are matrices and r, s are numbers, then rA + sB is (either undefined or) a matrix, and AB is (either undefined or) a matrix. This is because they satisfy the two matrix axioms: $T(\vec{\mathbf{x}} + \vec{\mathbf{y}}) = T(\vec{\mathbf{x}}) + T(\vec{\mathbf{y}})$ and $T(r\vec{\mathbf{x}}) = r(T(\vec{\mathbf{x}}))$.

2.1.d: Square matrices have equal domain and codomain. If A and B are $n \times n$ matrices, then so are rA, A^n for non-nonegative n, A + B, and AB. This means we can form polynomials in square matrices. If we are careful we can form power series, and so define things like $\sin(A)$, $\exp(A)$, and $\ln(1 + A)$.

A very nice kind of matrix is a diagonal matrix. It has numbers d_1, d_2, \ldots, d_n so that $D(\vec{\mathbf{e}}_i) = d_i \vec{\mathbf{e}}_i$. In other words, it just multiplies each entry by a number (it can be a different number for each entry).

The diagonal matrix where every number d_i is 1 is called the identity matrix, I_n . It multiplies everything by 1, so $I_n\vec{\mathbf{v}} = \vec{\mathbf{v}}$. The zero matrix 0_n is the diagonal matrix with each $d_i = 0$. It multiplies everything by 0, so $0_n\vec{\mathbf{v}} = \vec{\mathbf{0}}$.

2.2: Inverse matrices We've found linear combinations of matrices, and multiplied matrices. Now we'd like to divide matrices.

 A^{-1} is the matrix with the property that if $A\vec{\mathbf{x}} = \vec{\mathbf{b}}$, then $A^{-1}(\vec{\mathbf{b}}) = \vec{\mathbf{x}}$. By applying A^{-1} to the standard basis vectors we see that $A^{-1}A = I_n$. Such a matrix is called a **left inverse** matrix of A.

Math textbooks (such as ours) usually require that $AA^{-1} = I_n$ as well. Such matrices are called **inverse** matrices. If A is square, then this happens automatically (a left inverse matrix of a square matrix is automatically a right inverse matrix).

Do all 1×1 matrices have an inverse? [Write down the rule.]

If A=[a], then A' (= [Va] dato ONE ga=0

What about $A = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$. Can you find a left inverse of A? Hint: What does $\vec{\mathbf{x}}$ look like? If
you know $A\vec{\mathbf{x}} = \vec{\mathbf{b}}$ and you know the first entry of $\vec{\mathbf{b}}$, how do you find $\vec{\mathbf{x}}$?
$A\hat{x} = \begin{bmatrix} 3 \end{bmatrix} [X] = \begin{bmatrix} 3x \\ 5x \end{bmatrix} = \begin{bmatrix} 3x \\ 6x \end{bmatrix} = \begin{bmatrix} 3x \\ 6$
How many left inverses are there?
Are any of them right inverses? A'A = $\begin{bmatrix} a & b \end{bmatrix}$ where $3a + 5b = 1$ $A'A = \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 3a + 5b \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$
· · · · · · · · · · · · · · · · · · ·
No. AA'= [3](ab] = [3a36] \$\frac{1}{5}a510 \\ 5a50 \\ 5a50 \\ \frac{1}{5}a510 \\ \frac{1}
What about $A = \begin{bmatrix} 3 & 0 \\ 0 & 5 \end{bmatrix}$. Can you find a left inverse of A ? Hint: Same hint, but different
answers. $A\hat{x} = \begin{bmatrix} 3 & 3 & 3 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} 3 & 1 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 3 & 3 \\ 5 & 4 \end{bmatrix} = \begin{bmatrix} 3 &$
How many left inverses are there?
Just one Chard &, tollows from ATA=AA' in this case
Are any of them right inverses?
Yes. All/The only one works
Can you give an example of 2×2 matrix that cannot have either a left or a right inverse?
$\Lambda = \Gamma = 0.07$ $\Lambda = \Gamma = 2.2$

What is the rule for 2×2 matrices?

e rule for
$$2 \times 2$$
 matrices?

See Book 99 $9 = [ab] = [ab] = [ab]$
 $A = [ab] = [ab]$

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HW2.1 #11a If $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 5 \\ 3 & 5 & 6 \end{bmatrix}$ and $D = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix}$, then compute AD and DA (label them clearly).

AD =
$$\begin{bmatrix} A \begin{bmatrix} 67 \\ 63 \end{bmatrix} & A \begin{bmatrix} 6$$

m clearly).
$$AD = \begin{bmatrix} A \begin{bmatrix} 5 \\ 6 \end{bmatrix} & A \begin{bmatrix} 6 \\ 6$$

HW2.1 #11b Describe in words what D does to the column or rows of A when you do AD.

HW2.1 #11c Find a matrix B so that AB = BA, but B is neither the zero matrix nor the

HW2.1 #11c Find a matrix
$$B$$
 so that $AB = BA$, but B is neither the zero matrix nor the identity matrix.

$$B = \begin{bmatrix} a & & & \\$$

Here
$$A = \begin{bmatrix} 3 & -6 \\ -2 & 4 \end{bmatrix}$$
.

$$\begin{array}{c}
A \begin{bmatrix} 3 \\ -2 \end{bmatrix} = \begin{bmatrix} 3 \\ -2 \end{bmatrix} \\
V_1 \\
V_2 \\
V_3 \\
V_4 \\
V_4 \\
V_4 \\
V_5 \\
V_6 \\
V_7 \\
V_8 \\
V_9 \\
V_9$$

Circle one of the next two questions and answer it (first is easier, second was homework):

HW2.1 #20 Suppose the first two columns $\vec{\mathbf{b}}_1$ and $\vec{\mathbf{b}}_2$ of B are equal. What can you conclude about the columns of AB? OR

HW2.1 #21 Suppose the last column of AB is entirely zero, but B has no columns that are

entirely zero. What can you conclude about the columns of A?

2.2.1 For
$$D = \begin{bmatrix} 7 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$
, find D^{-1} .

2.2.2 For
$$D = \begin{bmatrix} 7 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
, find D^{-1} .

where \$ \$ \$ could be anything (because it is wrong) but 000 is the smallest possibility