

6.1a Find a vector that is orthogonal to $\vec{v} = (3, 4)$. Can you find one that is unit length?

Old Way: $\vec{u} = (x, y)$ $\vec{v} \cdot \vec{u} = 3x + 4y$ set it equal to 0
 $[3 \ 4] \begin{bmatrix} x \\ y \end{bmatrix} = [0]$ $\begin{bmatrix} x & y & | & 0 \end{bmatrix} \xrightarrow{R_1/3} \begin{bmatrix} 1 & 4/3 & | & 0 \end{bmatrix}$ $x = -4/3 y$
 y is free

$$\vec{u} = \left(-\frac{4}{3}y, y\right) \text{ Solve } \|\vec{u}\| = \sqrt{\left(-\frac{4}{3}y\right)^2 + y^2} = \sqrt{\left(\frac{16}{9} + 1\right)y^2} = \sqrt{\frac{25}{9}}|y| = \frac{5}{3}|y|$$

$$\text{so } y = \pm \frac{3}{5} \quad \vec{u} = \pm \left(-\frac{4}{5}, \frac{3}{5}\right)$$

New Way: $\vec{u} = (1, 1)$ is correctness is undeniable. By undeniable, I mean completely deniable.

$$\vec{u} \cdot \vec{v} = (1, 1) \cdot (3, 4) = 3 + 4 = 7$$

$$\vec{v} \cdot \vec{v} = (3, 4) \cdot (3, 4) = 9 + 16 = 25$$

Step 1: Remove $\vec{u}$ but take $\vec{w} = \vec{u} - \frac{7}{25}\vec{v}$ and see what happens. (It's twice as good as $\vec{u}$)

$$\vec{w} \cdot \vec{v} = \left(\vec{u} - \frac{7}{25}\vec{v}\right) \cdot \vec{v} = \vec{u} \cdot \vec{v} - \frac{7}{25}\vec{v} \cdot \vec{v} = 7 - \frac{7}{25}25 = 0 \quad \checkmark$$

Step 2: Fix Length but $\vec{w}$ is too big so take $\vec{x} = \frac{\vec{w}}{\|\vec{w}\|}$ then $\|\vec{x}\| = \frac{\|\vec{w}\|}{\|\vec{w}\|} = 1 \quad \checkmark \quad \vec{x} \cdot \vec{v} = \frac{1}{\|\vec{w}\|}\vec{w} \cdot \vec{v} = 0 \quad \checkmark$

6.2a Find a vector that is orthogonal to $\vec{u} = (4, 4, 7)$ and $\vec{w} = (8, -1, -4)$. Can you find one that is unit length?

Old Way $\vec{v} = (x, y, z)$ $\vec{u} \cdot \vec{v} = 4x + 4y + 7z = 0$ $\vec{w} \cdot \vec{v} = 8x - y - 4z = 0$ $\begin{bmatrix} 4 & 4 & 7 \\ 8 & -1 & -4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$$\begin{bmatrix} 4 & 4 & 7 & | & 0 \\ 8 & -1 & -4 & | & 0 \end{bmatrix} \xrightarrow{R_2 - 2R_1} \begin{bmatrix} 4 & 4 & 7 & | & 0 \\ 0 & -9 & -18 & | & 0 \end{bmatrix} \xrightarrow{R_2 \cdot (-1/9)} \begin{bmatrix} 4 & 4 & 7 & | & 0 \\ 0 & 1 & 2 & | & 0 \end{bmatrix} \xrightarrow{R_1/4} \begin{bmatrix} 1 & 1 & 7/4 & | & 0 \\ 0 & 1 & 2 & | & 0 \end{bmatrix} \xrightarrow{R_1 - R_2} \begin{bmatrix} 1 & 0 & -1/4 & | & 0 \\ 0 & 1 & 2 & | & 0 \end{bmatrix}$$

$$x = \frac{1}{4}z$$

$$y = -2z$$

$$z \text{ is free}$$

$$\vec{v} = \left(\frac{1}{4}z, -2z, z\right)$$

$$\|\vec{v}\| = \sqrt{\left(\frac{1}{4}z\right)^2 + (-2z)^2 + z^2} = \sqrt{\left(\frac{1}{16} + 4 + 1\right)z^2} = \sqrt{\frac{65}{16}}|z| = \frac{\sqrt{65}}{4}|z|$$

$$z = \pm \frac{4}{\sqrt{65}}$$

$$\vec{v} = \left(\frac{1}{\sqrt{65}}, -\frac{8}{\sqrt{65}}, \frac{4}{\sqrt{65}}\right)$$

New Way: $\vec{v} = (1, 1, 1)$ $\vec{v} \cdot \vec{u} = 4 + 4 + 7 = 15$ $\vec{v} \cdot \vec{w} = 8 - 1 - 4 = 3$ $\vec{u} \cdot \vec{w} = 32 - 4 - 28 = 0$
 $\vec{u} \cdot \vec{u} = 16 + 16 + 49 = 81$ $\vec{w} \cdot \vec{w} = 64 + 1 + 16 = 81$

$$\vec{x} = \vec{v} - \frac{15}{81}\vec{u} - \frac{3}{81}\vec{w} \quad \text{then} \quad \vec{x} \cdot \vec{u} = \vec{v} \cdot \vec{u} - \frac{15}{81}\vec{u} \cdot \vec{u} - \frac{3}{81}\vec{w} \cdot \vec{u} = 15 - \frac{15}{81}81 - \frac{3}{81}0 = 0 \quad \checkmark$$

$$\vec{x} \cdot \vec{w} = \vec{v} \cdot \vec{w} - \frac{15}{81}\vec{u} \cdot \vec{w} - \frac{3}{81}\vec{w} \cdot \vec{w} = 3 - \frac{15}{81}0 - \frac{3}{81}81 = 0 \quad \checkmark$$

$$\|\vec{x}\| = \sqrt{\vec{x} \cdot \vec{x}} = \frac{1}{3}$$

$$\vec{y} = 3\vec{x} \text{ works}$$

Hint: $\vec{x} = (1, 1, 1)$ is wrong, since it points in both the $\vec{u}$ and the $\vec{w}$ directions. Could remove the wrongness?

The most interesting things happen when we have a bunch of unit length vectors that are all orthogonal to each other. For example, let's look at this basis of $\mathbb{R}^4$:

$$\vec{a} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad \vec{\ell} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \quad \vec{m} = \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix}, \quad \vec{h} = \frac{1}{2} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}$$

$$\text{If } A = \begin{bmatrix} \vec{a} & \vec{\ell} & \vec{m} & \vec{h} \end{bmatrix}$$

$$\text{then } A^T A = I$$

$$\text{so } \|\vec{a}\| = \|\vec{\ell}\| = \|\vec{m}\| = \|\vec{h}\| = 1$$

$$\vec{a} \cdot \vec{\ell} = \vec{a} \cdot \vec{m} = \vec{a} \cdot \vec{h} = \vec{\ell} \cdot \vec{m} = \vec{\ell} \cdot \vec{h} = \vec{m} \cdot \vec{h} = 0$$

Can you write $\vec{v} = \begin{bmatrix} 3 \\ 4 \\ 5 \\ 6 \end{bmatrix}$ as a linear combination of $\vec{a}, \vec{\ell}, \vec{m}, \vec{h}$?

$$\text{If } \vec{v} = x \cdot \vec{a} + y \cdot \vec{\ell} + z \cdot \vec{m} + t \cdot \vec{h}$$

$$\text{then } \vec{v} \cdot \vec{a} = (x\vec{a} + y\vec{\ell} + z\vec{m} + t\vec{h}) \cdot \vec{a} = x(\vec{a} \cdot \vec{a}) + y(\vec{\ell} \cdot \vec{a}) + z(\vec{m} \cdot \vec{a}) + t(\vec{h} \cdot \vec{a})$$

$$= x(1) + y(0) + z(0) + t(0) = x$$

$$\text{so } x = \vec{v} \cdot \vec{a} = \frac{1}{2}(3+4+5+6) = 9$$

$$y = \vec{v} \cdot \vec{\ell} = \frac{1}{2}(3+4-5-6) = -2$$

$$z = \vec{v} \cdot \vec{m} = \frac{1}{2}(3-4-5+6) = 0$$

$$t = \vec{v} \cdot \vec{h} = \frac{1}{2}(3-4+5-6) = -1$$

$$\text{so } \vec{v} = 9\vec{a} - 2\vec{\ell} - \vec{h}$$

What if you weren't allowed to use $\vec{h}$? What is the closest you could get to being a linear combination of $\vec{a}, \vec{\ell}, \vec{m}$?

$$\text{dist}(x\vec{a} + y\vec{\ell} + z\vec{m}, \vec{v}) = \text{dist}(x\vec{a} + y\vec{\ell} + z\vec{m}, 9\vec{a} - 2\vec{\ell} - \vec{h}) = \|(x-9)\vec{a} + (y+2)\vec{\ell} + z\vec{m} + \vec{h}\|$$

$$\text{but } \|b\vec{a} + c\vec{\ell} + d\vec{m} + e\vec{h}\| = \sqrt{(b\vec{a} + c\vec{\ell} + d\vec{m} + e\vec{h}) \cdot (b\vec{a} + c\vec{\ell} + d\vec{m} + e\vec{h})}$$

$$= \sqrt{\begin{matrix} b^2 \vec{a} \cdot \vec{a} + bc \vec{a} \cdot \vec{\ell} + bd \vec{a} \cdot \vec{m} + be \vec{a} \cdot \vec{h} \\ + cb \vec{\ell} \cdot \vec{a} + c^2 \vec{\ell} \cdot \vec{\ell} + cd \vec{\ell} \cdot \vec{m} + ce \vec{\ell} \cdot \vec{h} \\ + db \vec{m} \cdot \vec{a} + dc \vec{m} \cdot \vec{\ell} + d^2 \vec{m} \cdot \vec{m} + de \vec{m} \cdot \vec{h} \\ + eb \vec{h} \cdot \vec{a} + ec \vec{h} \cdot \vec{\ell} + ed \vec{h} \cdot \vec{m} + e^2 \vec{h} \cdot \vec{h} \end{matrix}}$$

$$= \sqrt{\begin{matrix} b^2(1) + 0 + 0 + 0 \\ 0 + c^2 + 0 + 0 \\ 0 + 0 + d^2 + 0 \\ 0 + 0 + 0 + e^2 \end{matrix}} \quad \text{so we want to minimize}$$

$$\sqrt{(x-9)^2 + (y+2)^2 + z^2 + 1}$$

$$\text{so } x=9, y=-2, z=0$$

NO CHANGE!

What if you were only allowed to use $\vec{a}$? What is the closest you could get to being a linear combination of $\vec{a}$?

$$\text{Same deal! } \text{dist}(x\vec{a}, 9\vec{a} - 2\vec{\ell} - \vec{h}) = \sqrt{(x-9)^2 + (-2)^2 + (0)^2 + (-1)^2}$$

$$\text{best choice is } x=9 = \vec{a} \cdot \vec{v} \quad \text{error/dist is } \sqrt{\text{sum of squares of other coeffs}} = \sqrt{(-2)^2 + (0)^2 + (-1)^2} = \sqrt{5}$$

$$\text{Formula version } \frac{\vec{a} \cdot \vec{v}}{\vec{a} \cdot \vec{a}} \vec{a}$$

$$\text{and } \frac{\vec{a} \cdot \vec{v}}{\vec{a} \cdot \vec{a}} \vec{a} + \frac{\vec{\ell} \cdot \vec{v}}{\vec{\ell} \cdot \vec{\ell}} \vec{\ell} + \frac{\vec{m} \cdot \vec{v}}{\vec{m} \cdot \vec{m}} \vec{m} \text{ etc}$$

These are called the **projections** onto the span of the vectors you are allowed to use, and they can be computed as in theorem 5, page 339 in the book.

HW 6.2 # 1,3,5,7,9

$$\text{as long as } \vec{a} \cdot \vec{\ell} = 0 \\ \vec{a} \cdot \vec{m} = 0 \\ \text{and } \vec{\ell} \cdot \vec{m} = 0$$