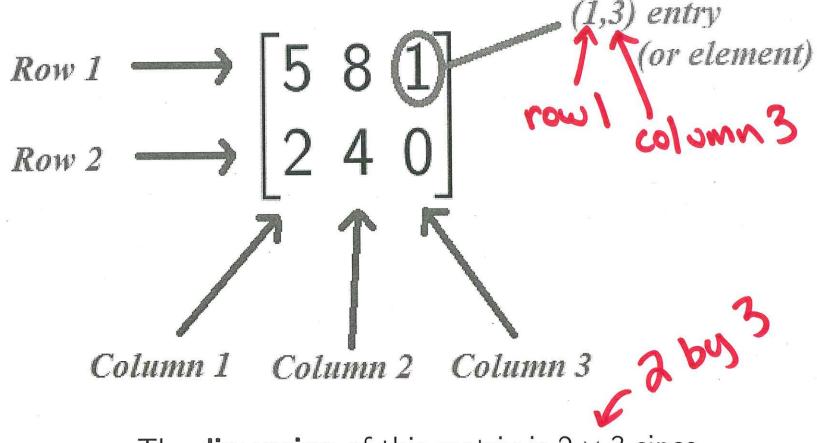
# MA 162 : Finite Mathematics - Chapter 3 Matrix Algebra

University of Kentucky

### 3.2 Introduction to Matrices

A matrix is a rectangular array of numbers. Matrices are useful in organizing and manipulating large amounts of data.



The dimension of this matrix is  $2 \times 3$  since there are 2 rows and 3 columns.

#### 3.2 Introduction to Matrices

A matrix that has the same number of rows as columns is called a square matrix.

A matrix consisting of all zeros is called a zero matrix

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

A square matrix which has 1's along the main diagonal and zeros elsewhere is called an **identity** matrix.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

#### 3.2 Introduction to Matrices

A matrix that has only one row is called a **row matrix** or **row vector** 

$$\begin{bmatrix} 2 & 8 & 1 & 7 \end{bmatrix}$$

A matrix that has only one column is called a **column matrix** or **column vector** 

Two matrices are **equal** if they have the same size and each corresponding entry is equal.

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

#### 3.2 Matrix Addition and Subtraction

If two matrices are the same dimension, they can be added or subtracted.

Example 1: Let 
$$A = \begin{bmatrix} -4 & 1 & 9 \ 3 & -5 & 2 \end{bmatrix}$$
 and  $B = \begin{bmatrix} 7 & 3 & -2 \ 1 & 0 & 6 \end{bmatrix}$ .

• Find  $A + B$ 

=  $\begin{bmatrix} -4+1 & 1+3 & 9-2 \ 3+1 & -5+0 & 2+6 \end{bmatrix} = \begin{bmatrix} 3 & 4 & 7 \ 4 & -5 & 8 \end{bmatrix}$ 

• Find  $B - A$ 

=  $\begin{bmatrix} 7 & 3 & -2 \ 1 & 0 & 6 \end{bmatrix}$ 

• Find  $B - A$ 

=  $\begin{bmatrix} 3 & 4 & 7 \ 4 & -5 & 8 \end{bmatrix}$ 

1 -3 0-(-5) 6-2  $\begin{bmatrix} 11 & 2 & -11 \ -2 & 5 & 4 \end{bmatrix}$ 

# 3.2 Scalar Multiplication

When we multiply a matrix by a scalar, we multiply each entry by that scalar

**Example 2**: Let 
$$A = \begin{bmatrix} -4 & 1 & 9 \\ 3 & -5 & 2 \end{bmatrix}$$
 and  $B = \begin{bmatrix} 7 & 3 & -2 \\ 1 & 0 & 6 \end{bmatrix}$ .

Find 
$$3B - 2A$$

$$\begin{bmatrix}
21 & 9 & -6 \\
3 & 0 & 18
\end{bmatrix} = \begin{bmatrix}
-8 & 2 & 18 \\
6 & -10 & 4
\end{bmatrix} = \begin{bmatrix}
29 & 7 & -24 \\
-3 & 10 & 14
\end{bmatrix}$$

$$3B - 2A$$

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In certain cases, we can multiply two matrices. The process is more difficult than adding/subtracting matrices or multiplying by a scalar.

Because of its wide use in application problems, we need to learn multiplication of matrices well.

If A is a  $n \times m$  matrix and B is an  $m \times r$  matrix, then we can multiply to find the product matrix AB. The resulting matrix will be an  $n \times r$  matrix.

nxr dimension of AB

Example 3: Let 
$$A = \begin{bmatrix} 2 & 1 & -3 \end{bmatrix}$$
 and  $B = \begin{bmatrix} -1 \\ 4 \\ 0 \end{bmatrix}$ .

Find  $AB$  dimension  $\begin{bmatrix} 1 \times 3 \end{bmatrix}$  dimension

AB will have dimension

$$\begin{bmatrix} AB \end{bmatrix} = \begin{bmatrix} 2 & 1 & -3 \end{bmatrix} \begin{bmatrix} -1 \\ 4 \\ 0 \end{bmatrix} = \begin{bmatrix} 2(-1) + 1(4) + (-3)(0) \end{bmatrix}$$

$$= \begin{bmatrix} 2 \end{bmatrix}$$

Example 4: Let 
$$A = \begin{bmatrix} 2 & 1 & -3 \end{bmatrix}$$
 and  $B = \begin{bmatrix} -1 \\ 4 \\ 0 \end{bmatrix}$ .

Find  $BA \rightarrow (3x) \cdot (1x3)$ 

match  $0$ 

Output is a  $3x3$  matrix

 $\begin{bmatrix} -1 \\ 4 \\ 0 \end{bmatrix}$ 
 $\begin{bmatrix} 2 & 1 & -3 \end{bmatrix}$ 
 $\begin{bmatrix} -1(2) & (-1)(1) & (-1)(-3) \\ 4(2) & 4(1) & 4(-3) \\ 0 & 0 & 0 \end{bmatrix}$ 

Example 5: Let 
$$A = \begin{bmatrix} 2 & 1 & -3 \end{bmatrix}$$
 and  $B = \begin{bmatrix} -1 & 2 \\ 4 & 1 \\ 3 & -2 \end{bmatrix}$ .

Find  $AB$ 

Output dimension is [X]

$$2 + 3 = \begin{bmatrix} 2 & 1 & -3 \end{bmatrix} = \begin{bmatrix} 2 & 1 & -3 \\ 2 & 1 & -3 \end{bmatrix} = \begin{bmatrix} 2 & 1 & -3 \\ 2 & 1 & -3 \end{bmatrix} = \begin{bmatrix} 2 & 1 & -3 \\ 2 & 1 & -3 \end{bmatrix} = \begin{bmatrix} -1 & 2 \\ 2 & 1 & -3 \end{bmatrix} = \begin{bmatrix} -1 & 2 \\ 4 & 1 \\ 3 & -2 \end{bmatrix}$$

Example 6: Let 
$$A = \begin{bmatrix} 1 & 2 & -3 \\ 2 & 5 & 3 \end{bmatrix}$$
 and  $B = \begin{bmatrix} -1 & 2 \\ 1 & 4 \\ 3 & -2 \end{bmatrix}$ .

Find  $AB$ 

AB =  $\begin{bmatrix} 1 & 2 & -3 \\ 2 & 5 & 3 \end{bmatrix}$  and  $AB = \begin{bmatrix} -1 & 2 \\ 1 & 4 \\ 3 & -2 \end{bmatrix}$ .

# 3.2 Matrix Multiplication and Systems of Equations

In chapter 1, we discussed solving systems of equations. In this chapter, we will use matrices to solve systems of equations.

We can pass back and forth between the system of equation format we are used to seeing and matrix equations.

# 3.2 Matrix Multiplication and Systems of Equations

**Example 7**: Express the following system of equations as a matrix equation AX = B.

$$\begin{cases} 3x - 4y + 5z = 7 \\ 2x - 8y + 9z = -2 \\ 5x - 6z = 7 \end{cases}$$

$$\begin{bmatrix} 3 & -4 & 5 \\ 2 & -8 & 9 \\ 5 & 0 & -6 \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \end{bmatrix} = \begin{bmatrix} + \\ -2 \\ -3 \end{bmatrix}$$

# 3.3 Solving Systems Using the Gauss-Jordan Method

In this section we will learn about the Gauss-Jordan method for solving systems of equations.

The Gauss-Jordan method is applied to the augmented matrix that represents a system of equations.

First we need to learn how to pass back and forth between the system of equation format we are used to seeing and the corresponding augmented matrix.

# 3.3 Solving Systems Using the Gauss-Jordan Method

Consider the system of equations

$$\begin{cases} 2x - 4y + 7z = 5 \\ 8x - 2y + 2z = -9 \\ 5x + 6y - 6z = 7 \end{cases}$$

The corresponding augmented matrix is

$$\begin{bmatrix} 2 & -4 & 7 & 5 \\ 8 & -2 & 2 & -9 \\ 5 & 6 & -6 & 7 \end{bmatrix}$$

Each row of the matrix represents one of the equations. The first three columns are the coefficients of x, y, and z respectively. The vertical line represents the equal sign and the 4th column contains the constants.

# 3.3 Solving Systems Using the Gauss-Jordan Method

The Gauss-Jordan method is a systematic use of the elimination method. In this next example, we will solve a system of equations using the elimination method while keeping track of the corresponding augmented matrix at each step.

**Example 1**: Solve the system

#### 3.3 The Gauss-Jordan Method

Using the elimination method is repetitive use of three operations. When we apply the operations to the corresponding augmented matrix, we are using what are called **row.operations**.

#### **Row Operations**

- Any two rows in the augmented matrix can be interchanged.
- Any row may be multiplied by a non-zero constant.
- A constant multiple of a row may be added to another row.

Each of these operations make the system "look" different, but create an equivalent system of equations (the solution does not change).

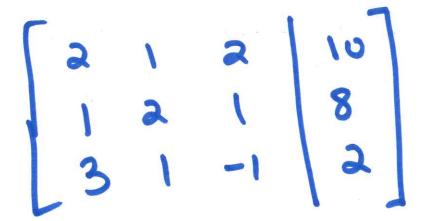
#### 3.3 The Gauss-Jordan Method

**Example 2**: Solve the system of equations by applying row operations to the corresponding augmented matrix.

$$\begin{cases} 2x + y + 2z = 10 \\ x + 2y + z = 8 \end{cases}$$

$$3x + y - z = 2$$

Write the augmented matrix.

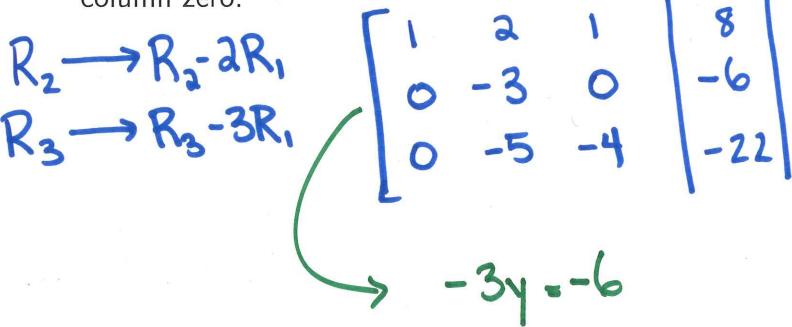


 Interchange rows if necessary to obtain a non-zero entry in the first row, first column.

Already done!

• Use a row operation to make the entry in the first row, first column a 1.

 Use row operations to make all other entries in the first column zero.



 Interchange rows if necessary to obtain a nonzero number in the second row, second column. Not needed

 Use row operations to make the entry in the second row, second column a 1.

$$R_2 \rightarrow -\frac{1}{3}R_2$$

$$\begin{pmatrix} 1 & 2 & 1 & 8 \\ 2 & 1 & 0 & 2 \\ 0 & -5 & -4 & -22 \end{pmatrix}$$

 Use row operations to make all other entries in the second column zero.

 Use row operations to make the entry in the third row, third column a 1 and all other entries in the third column zero.
 Read off the answer from the augmented matrix.

$$R_{3} \rightarrow -4R_{3} \qquad \begin{bmatrix} 1 & 0 & 1 & 4 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

$$R_{1} \rightarrow R_{1} - R_{3} \qquad \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

$$(x_{1}y_{1}z) = (1_{1}z_{1}3)$$

#### 3.3 The Gauss-Jordan Method

Example 2 outlined the Gauss-Jordan method. You can also find the steps on page 54 of the text.

The process of making a certain entry in a matrix 1 and then all other entries in that column zero is called **pivoting**.

The number that is made a 1 is called the **pivot element** and the row that contains the pivot element is called the **pivot row**.

The final form of the augmented matrix after applying the Gauss-Jordan method is called **reduced row echelon form**.

#### 3.3 The Gauss-Jordan Method

**Example 3**: Solve the system of equations using the Gauss-Jordan method.

$$\begin{cases} x - y - z = -1 \\ x - 3y + 2z = 7 \\ 2x - y + z = 3 \end{cases}$$

$$R_{2} \longrightarrow R_{3} - 1 \cdot R_{1}$$

$$R_{3} \longrightarrow R_{3} - 2R_{1}$$

$$R_{4} \longrightarrow R_{3} - 2R_{1}$$

$$R_{5} \longrightarrow R_{5} - 2R_{1}$$

$$R_{7} \longrightarrow R_{7} - 2R_{1}$$

$$R_{8} \longrightarrow R_{7} - 2R_{1}$$

$$R_{8} \longrightarrow R_{7} - 2R_{1}$$

$$R_{9} \longrightarrow R_{1} - 1$$

$$R_{1} \longrightarrow R_{2} - 1 \cdot R_{1}$$

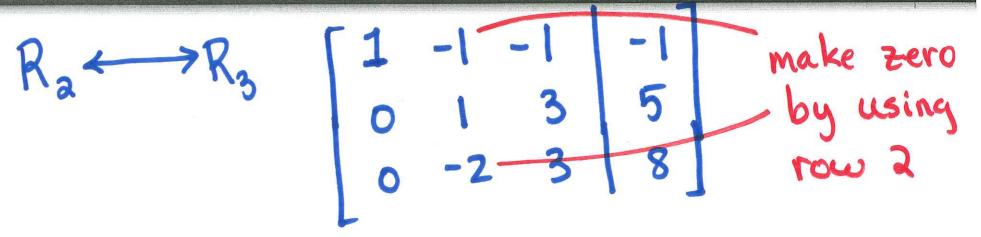
$$R_{2} \longrightarrow R_{3} - 2R_{1}$$

$$R_{3} \longrightarrow R_{3} - 2R_{1}$$

$$R_{4} \longrightarrow R_{5} - 2R_{1}$$

$$R_{5} \longrightarrow R_{5} - 2R_{1}$$

$$R_{7} \longrightarrow R_{7} - 2R_{1}$$



$$R_{3} \rightarrow \frac{1}{9}R_{3} \qquad \begin{bmatrix} 1 & 0 & a & | & 4 \\ 0 & 1 & 3 & | & 5 \\ 0 & 0 & 1 & | & 2 \end{bmatrix}$$

$$R_{1} \rightarrow R_{1} - \lambda R_{3} \qquad \begin{bmatrix} 1 & 0 & 0 & | & 0 \\ 0 & 1 & 0 & | & -1 \\ 0 & 0 & 1 & | & 2 \end{bmatrix}$$

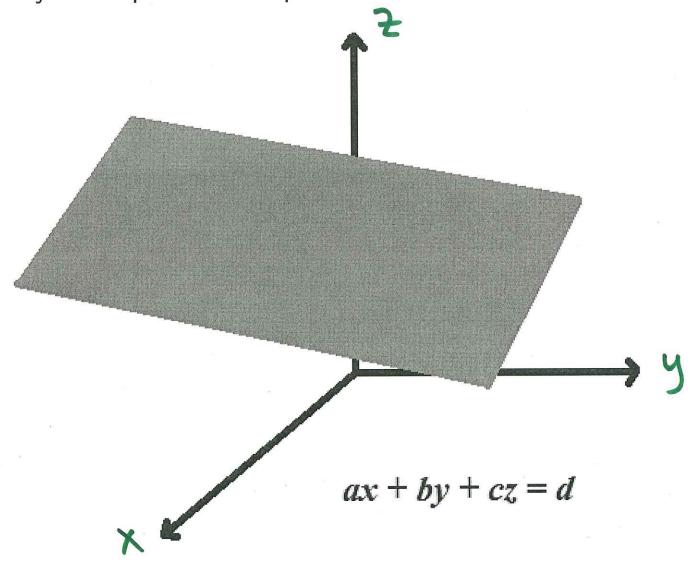
$$\Rightarrow (x_{1}y_{1}z) = (0,-1,a)$$

In Chapter 1, we considered the intersection of two lines in a plane and saw that three things could happen.

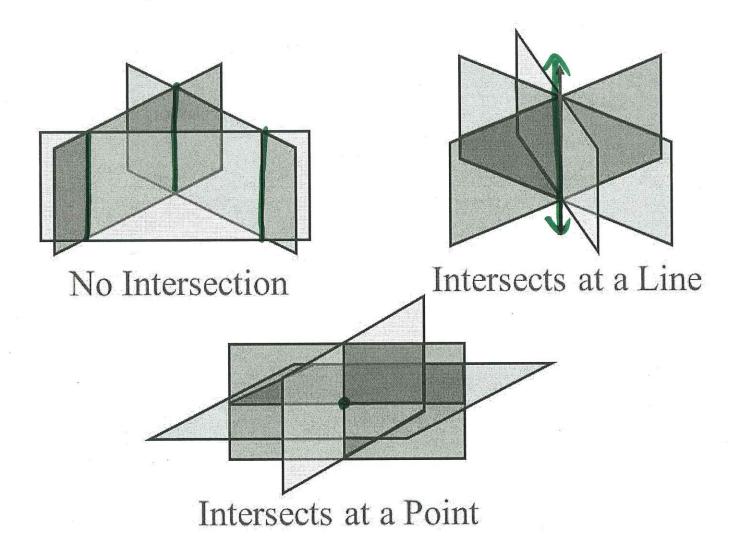
- The lines intersect at exactly one point. This is called an independent system.
- The lines are parallel with different y-intercepts so they do not intersect. This is called an **inconsistent system**.
- The lines coincide and intersect at infinitely many points.
  This is called a dependent system.

If a system has at least one solution, then we called it a **consistent system**. A consistent system is one that is either independent or dependent.

Now we are looking at systems with three or more variables. In the case of a linear equation with three variables, the set of all points that satisfy the equation is a plane in 3-dimensions.



When we want to solve a system of 3 equations with 3 variables, we need to know how the planes intersect. There are a variety of ways that three planes can intersect. Here are a few examples.



We use the same words to describe solutions to systems of equations with three variables as we did with lines.

In the last slide, we saw

No intersection - Inconsistent

No Solution

Intersects at a line - Dependent (consistent)

Infinitely many

Intersects at a point - Independent (consistent)

Exactly one.

In Chapter 3, we are using the Gauss-Jordan method to solve systems of equations by applying the method to the augmented matrix until the matrix is in reduced row echelon form.

Now we need to see what happens when we apply the Gauss-Jordan method to augmented matrices corresponding to inconsistent and dependent systems.

**Example 1**: Determine all solutions (if any exist) for the system of equations

$$\begin{cases} 2x + 3y = 7 \\ -4x - 6y = -13 \end{cases} \times y \text{ constant}$$

$$\begin{cases} 2x + 3y = 7 \\ -4x - 6y = -13 \end{cases} \times y \text{ constant}$$

$$\begin{cases} R_2 \rightarrow R_2 + 2R_1 & 3 & 7 \\ 0 & 0 & 1 \end{cases}$$

$$\begin{cases} 0 \rightarrow 1 & 0 & 1 \\ 0 & 0 & 1 \end{cases}$$

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$$\begin{cases} 0 \rightarrow 1 &$$

**Example 2**: Determine all solutions (if any exist) for the system of equations

**Example 3**: Determine all solutions (if any exist) for the system of equations

$$\begin{cases} x + y + z = 6 \\ 3x + 2y + z = 14 \\ 4x + 3y + 2z = 20 \end{cases}$$

$$\begin{cases} R_2 - 3R_1 \\ R_3 - 4R_1 \end{cases} \qquad \begin{cases} 0 - 1 - 2 - 4 \\ -4 - 4 \end{cases}$$
wake

$$R_{2} \rightarrow -R_{2} \qquad \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & -1 & -2 & -4 \end{bmatrix}$$

$$R_{1} \rightarrow R_{1} - R_{2} \qquad \begin{bmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_{3} \rightarrow R_{3} + R_{2} \qquad \begin{bmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

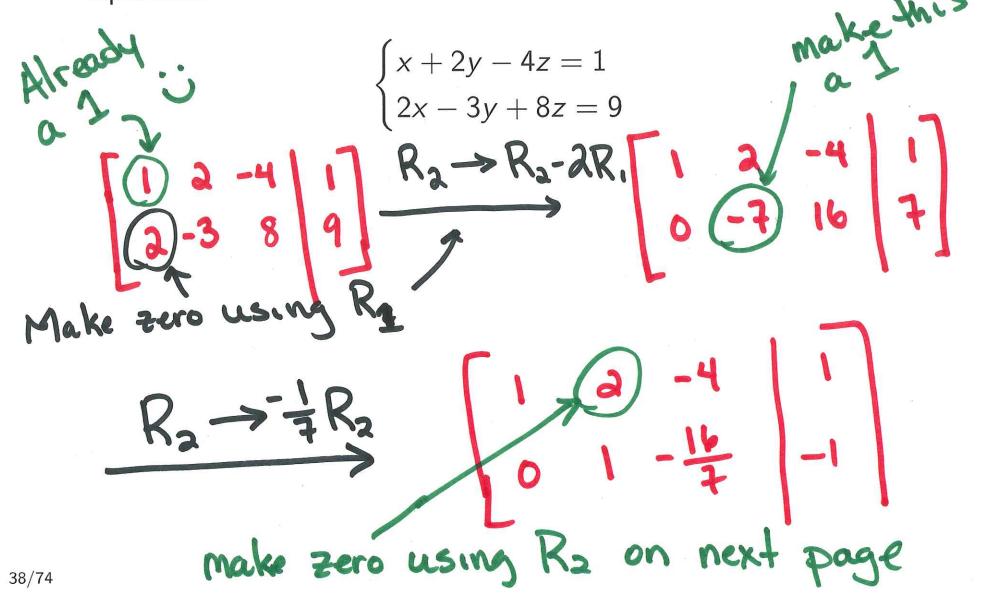
$$X - 2 = \lambda \Rightarrow X = Z + \lambda$$

$$Y + \lambda z = 4 \Rightarrow Y = -\lambda z + 4$$

$$(X_{1} Y_{1} z) = (Z + \lambda_{3} - \lambda_{2} z + 4, z)$$

# 3.4 Systems of Equations - Special Cases

**Example 4**: Determine all solutions (if any exist) for the system of equations



## 3.4 Example 4 continued

$$R_{1} \rightarrow R_{1} - \lambda R_{2}$$

$$R_{1} \rightarrow R_{1} - \lambda R_{2}$$

$$= -4 + 3\frac{2}{7}$$

$$= -2\frac{6}{7} + 3\frac{2}{7}$$

$$= \frac{4}{7}$$

Done reducing.

$$7=0 \Rightarrow (x_1y_1z) = (3_1-1_0)$$

$$7=7 \Rightarrow (x_1y_1z) = (-1_1_{15_1}z)$$

$$7 \Rightarrow (x_1y_1z) = (-1_1_{15_1}z)$$

# 3.4 Systems of Equations - Special Cases

- If any row of the reduced row echelon form of the matrix gives a false statement such as 0 = 1, then the system has no solution.
- If the reduced row echelon form has fewer equations than variables and the system is consistent, then there are infinitely many solutions (rows containing all zeros dropped).
  - If a system has an infinite number of solutions, the solution must be put in **parameterized** form.
  - The number of arbitrary parameters equals the number of variables minus the number of non-zero equations.

$$3 \cdot \frac{1}{2} = 1$$
  $2 \cdot 2^{-1} = 1$ 

**Definition**: A  $n \times n$  matrix A has an inverse if there exists another  $n \times n$  matrix B such that  $AB = BA = I_n$  where  $I_n$  is the  $n \times n$  identity matrix.

The inverse of a matrix A, if it exists, is denoted by  $A^{-1}$ .

**Note**: If is important that you check both  $AB = I_n$  and  $BA = I_n$ . Just checking one is not enough since in general  $AB \neq BA$ .

Example 1: Verify that 
$$A = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$$
 and  $B = \begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix}$  are inverses.

Check ①  $AB = \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$ .  $\begin{bmatrix} 2 & -5 \\ -1 & 3 \end{bmatrix}$   $= \begin{bmatrix} 3(2) - 5(1) & 3(-5) + 5(3) \\ 1(2) - 2(1) & 1(-5) + 2(3) \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ 

②  $BA = \begin{bmatrix} 2 & -5 \\ 1 & 2 \end{bmatrix}$   $= \begin{bmatrix} 3 & 5 \\ 1 & 2 \end{bmatrix}$   $= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ 

## 3.5 Inverse of $2 \times 2$ Matrices

If you look closely at the last example, you will see a relationship between the two matrices. If the determinant

For a  $2 \times 2$  matrix

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

is zero,  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  A is not invertible.

the inverse matrix is

determinant 
$$A^{-1} = \begin{bmatrix} 1 \\ ad - bc \end{bmatrix} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Unfortunately, there is no shortcut for larger matrices.

#### Method for Finding the Inverse of a Matrix

- Write the augmented matrix  $\begin{bmatrix} A & I_n \end{bmatrix}$ .
- Use the Gauss-Jordan method to write the augmented matrix from step 1 in reduced row echelon form.
- If the reduced row echelon form in step 2 is  $\begin{bmatrix} I_n & B \end{bmatrix}$ , then B is the inverse of A.
- If the left side of the reduced matrix from step 2 is not an identity matrix, then A does not have an inverse.

**Example 2**: Find the inverse of the matrix

$$A = \begin{bmatrix} 7 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 0 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 0 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

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$$\begin{bmatrix} 7 & 0 & 0 \\ 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

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$$\begin{bmatrix} 7 & 0 & 0 \\ 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

**Example 3**: Assume  $x, y, z \neq 0$  and find the inverse of the matrix

$$A = \begin{bmatrix} x & 0 & 0 \\ 0 & y & 0 \\ 0 & 0 & z \end{bmatrix}$$

$$\begin{bmatrix} x & 0 & 0 \\ 0 & y & 0 \\ 0 & 0 & z \end{bmatrix}$$

$$R_1 \rightarrow R_1(//x)$$

$$R_2 \rightarrow R_2(//y)$$

$$R_3 \rightarrow R_3(//z)$$

$$R_3 \rightarrow R_3(//z)$$

Example 4: Find the inverse of the matrix

A = 
$$\begin{bmatrix} 1 & 1 & -1 \\ 3 & 1 & -1 \\ 1 & 1 & 2 \end{bmatrix}$$

Make zero using R,

 $R_2 \rightarrow R_2 - 3R_1$ 
 $R_3 \rightarrow R_3 - R_1$ 
 $R_2 \rightarrow -\frac{1}{2}R_2$ 
 $R_3 \rightarrow R_3 - R_1$ 
 $R_4 \rightarrow R_2 - 3R_1$ 
 $R_5 \rightarrow R_5 - R_1$ 
 $R_7 \rightarrow R_7 - R_1$ 
 $R_8 \rightarrow R_8 - R_1$ 
 $R_8 \rightarrow R_8 - R_1$ 
 $R_8 \rightarrow R_8 - R_1$ 
 $R_9 \rightarrow R_9 - R_1$ 
 $R_9 \rightarrow R_$ 

## 3.5 Example 4 continued

$$R_1 \rightarrow R_1 - R_2$$
 [ 0 0 | -1/2 1/2 0]

 $C = \frac{3}{2} - \frac{1}{2} = 0$ 

Make a 1

$$R_3 \rightarrow \frac{1}{3}R_3$$
 $0 \quad 0 \quad -\frac{1}{2} \frac{1}{2} \quad 0$ 
 $\frac{3}{2} -\frac{1}{2} \quad 0$ 
 $0 \quad 0 \quad -\frac{1}{3} \quad 0 \quad \frac{1}{3}$ 

Make zero using  $R_3$ 

# 3.5 Example 4 continued

# 3.5 Using the Inverse to Solve a System of Equations

Suppose we want to solve the system AX = B where A is the coefficient matrix, X is the matrix of variables and B is the matrix of constant terms.

If A is invertible, then we can multiply both sides of the equation AX = B by  $A^{-1}$  to get

$$A^{-1}AX = A^{-1}B \implies X = A^{-1}B$$

Note: This method only works when a unique solution exists.

# 3.5 Using the Inverse to Solve a System of Equations

**Example 5**: Solve the system of equations using the inverse method.

$$A^{-1} = \frac{1}{6-5} \begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 3 & -5 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 & 5 \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 & 3 \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 4 & 5 \\ 1 & 3 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 & 3 \end{bmatrix}$$

## Extra Examples 3.2-3.5

Example 1: Let 
$$X = \begin{bmatrix} 2x & 5y \\ 3 & 5 \end{bmatrix}$$
 and  $Y = \begin{bmatrix} -1 & 4 \\ z & 3w \end{bmatrix}$ .  
Find  $2X - 3Y$ .  $2x$ 

$$= \begin{bmatrix} 4x + 40y \\ 6 & 10 \end{bmatrix} - \begin{bmatrix} -3 & 12 \\ 3z & 9w \end{bmatrix}$$

$$= \begin{bmatrix} 4x + 3 & 10y - 12 \\ 6 - 3z & 10 - 9w \end{bmatrix}$$

## Extra Examples 3.2-3.5

**Example 2**: Let 
$$X = \begin{bmatrix} 2x & 5y \\ 3 & 5 \end{bmatrix}$$
 and  $Y = \begin{bmatrix} -1 & 4 \\ z & 3w \end{bmatrix}$ . Find  $XY$ .

$$\begin{bmatrix} 2x & 5y \\ 3 & 5 \end{bmatrix} \begin{bmatrix} -1 & 4 \\ 2 & 3w \end{bmatrix}$$

$$= \begin{bmatrix} -2x + 5zy & 8x + 15yw \\ -3 + 5z & 12 + 15w \end{bmatrix}$$

## 3.7 Applications - Leontief Models

In the 1930's, Wassily Leontief used matrices to model economic systems.

His models, referred to as input-output models, divide the economy into sectors where each sector produces goods and services for itself and other sectors.

The sectors are dependent on one another and the total input always equal the total output.

In 1973, he won the Nobel Prize in Economics for his work.

#### 3.7 The Closed Model

As an example of the closed model, we look at a very simple economy were there are only three sectors.

**Example 1**: Assume that in a village there is a farmer, carpenter, and tailor who provide the three essential goods: food, shelter, and clothing. Suppose the farmer consumes 30% of the food he produces, and gives 25% to the carpenter, and 45% to the tailor. 40% of the carpenter's production is consumed by the farmer, 35% by himself, and 25% by the tailor. 35% of the tailor's production is consumed by the farmer, 15% by the carpenter, and 50% by himself. Write the matrix that describes the closed model.

# 3.7 Example 1 continued

	Farmer Production	Tarpenter	tailor
Consumption by Farmer	.30	.40	.35
Carpenter	. 25	. 35	.15
Haulor	.45	.25	.50

Internal Consumption

#### 3.7 The Closed Model

# Can also let x = farmers production, y = carpenters

**Example 2**: Using the information from example 1, how much pay should each person get for their effort?

$$.30 \times + .40 + .35 = \times$$

$$.35 \times + .35 + .15 = 4$$

$$.45 \times + .25 + .50 = 2$$

$$A \left[ \frac{x}{y} \right] = \left[ \frac{x}{y} \right] \Rightarrow \left[ \frac{0}{0} \right] = \left[ \frac{x}{y} \right] - A \left[ \frac{y}{z} \right]$$

$$T \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} - A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \implies (T - A) \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} .30 & .40 & .35 \\ .25 & .35 & .15 \\ .45 & .25 & .5 \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

website linked in Canvas announcement

$$X - \frac{115}{142} z = 0$$

this will always you the given to you

T picked

2=142 because

it made the

numbers

work out

nicely

## 3.7 The Open Model

The open model is more realistic, as it deals with an economy where sectors of the economy not only satisfy each others needs, but also satisfy some external demand.

The external demand comes from the consumer. The basic assumption is the same, whatever is produced is consumed.

## 3.7 The Open Model

**Example 3**: Consider the same economy as in example 1, however the production of the farmer, carpenter and tailor is not completely consumed by the three sectors. Instead, the consumption is given by the following table.

Production

NAMES OF THE PARTY	F produces	C produces	T produces
F uses	.15	.20	.15
C uses	.20	.25	.20
T uses	.10	.15	.05

Internal consumption matrix

Also, assume that the consumer uses the other \$50000 worth of food, \$40000 worth of carpenter's production, and \$35000 worth of clothing.

What should be the amount, in thousands of dollars, of required output by each sector to meet the external demand?

# 3.7 Example 3 continued

Exchange Matrix 
$$A = \begin{bmatrix} .15 & .20 & .15 \\ .20 & .25 & .20 \end{bmatrix}$$

$$\begin{bmatrix} .10 & .15 & .05 \end{bmatrix}$$
Want production = consumption demand matrix
$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = X = A \times + \begin{bmatrix} 50 \\ 40 \\ 35 \end{bmatrix}$$

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## Extra Examples 3.2-3.5

**Example 3**: Solve the system of equations using Gauss-Jordan elimination.

## Example 3 continued

## Example 3 continued

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## Extra Examples 3.2-3.5

**Example 4**: Determine the solution(s) to the system of equations using Gauss-Jordan elimination.

$$\begin{cases} x - y + z = 0 \\ 4x + 2y - 6z = 0 \\ 2x + y - 3z = 0 \end{cases}$$

$$\begin{bmatrix} 1 & -1 & 1 & 0 \\ 2 & 1 & -3 & 0 \end{bmatrix} \xrightarrow{R_2 \to R_2 - 4R_1} \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 6 & -10 & 0 \\ \hline R_3 \to R_3 - R_2 & 0 & 3 & -5 & 0 \end{bmatrix}$$

$$\xrightarrow{R_3 \to R_3 - R_2} \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 6 & -10 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

## Example 4 continued

$$x - \frac{2}{3}z = 0$$
  
 $y - \frac{5}{3}z = 0$ 

$$\Rightarrow X = \frac{2}{3}z$$

$$Y = \frac{5}{3}z$$

## Extra Examples 3.2-3.5

Example 5: Find the inverse of 
$$A = \begin{bmatrix} 3 & 4 \\ 1 & x \end{bmatrix}$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \text{ then } A^{-1} = \begin{bmatrix} 1 & d & -b \\ -c & a \end{bmatrix}$$

$$Cannot be zero$$

$$A = \begin{bmatrix} 3 & 4 \\ 1 & x \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & 4 \\ 1 & x \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & 4 \\ 1 & x \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & 4 \\ 1 & x \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & 4 \\ 1 & x \end{bmatrix}$$

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$$A = \begin{bmatrix} 3 & 4 \\ 1 & x \end{bmatrix}$$

$$A = \begin{bmatrix} 3 & 4 \\ 1 & x \end{bmatrix}$$

## Extra Examples

**Example 6**: Tommy has to buy some pens, pencils and notebooks for the upcoming semester. He has \$102 to spend on \$5 pens, \$3 pencils, and \$9 notebooks. He would like to spend the same amount of money on pens as on pencils. He also wants the combined number of pens and pencils to be equal to that of notebooks. Set up a system of equations to find how many of each item he should buy.

## Example 6 continued

$$3\times +5y + 92 = 100 102 \leftarrow total & spent$$
  
 $3\times = 5y (3x-5y=0) \leftarrow # spent on = # spent$   
 $x+y=2 (x+y-2=0)$ 

## Extra Examples

**Example 7**: John inherited \$25,000 and invested part of it in a money market account, part in municipal bonds, and part in a mutual fund. After one year, he received a total of \$1,620 in simple interest from the three investments. The money market paid 6% annually, the bonds paid 7% annually, and the mutually fund paid 8% annually. There was \$6,000 more invested in the bonds than the mutual funds. Set up a system of equations to find the amount John invested in each category.

## Example 7 continued

$$0.00 \times + .07 + .08 = 1620$$
 — interest gained  $\times + 4 + 2 = 25000$  — total money invested  $= 2+6000$  ( $= 2+6000$ ) — total money invested black

# 3.7 The Open Model

**Example 3**: Consider the same economy as in example 1, however the production of the farmer, carpenter and tailor is not completely consumed by the three sectors. Instead, the consumption is given by the following table.

Production

41	F produces	C produces	T produces
F uses	.15	.20	.15
C uses	.20	.25	.20
T uses	.10	.15	.05

- Internal consumption watrix

Also, assume that the consumer uses the other \$50000 worth of food, \$40000 worth of carpenter's production, and \$35000 worth of clothing.

What should be the amount, in thousands of dollars, of required output by each sector to meet the external demand?

# 3.7 Example 3 continued

Exchange Matrix 
$$A = \begin{bmatrix} .15 & .20 & .15 \\ .20 & .25 & .20 \end{bmatrix}$$

$$\begin{array}{c} .10 & .15 & .05 \end{bmatrix}$$

solve

X = output of farmer Y = output of earpenter Z = output of tailor

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# 3.7 Example 3 continued

$$\begin{bmatrix} X \\ Y \end{bmatrix} = X = (I - A) D$$

$$I - A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} .15 & .20 & .15 \\ .20 & .25 & .20 \\ .10 & .15 & .05 \end{bmatrix} = \begin{bmatrix} .85 - .2 & -.15 \\ -.2 & .75 & -.2 \\ -.1 & -.15 & .95 \end{bmatrix}$$

$$\frac{260}{199}$$
  $\frac{1700}{4179}$   $\frac{1220}{4179}$   $\frac{80}{4179}$   $\frac{6340}{4179}$   $\frac{1600}{4179}$   $\frac{4179}{4179}$   $\frac{40}{4179}$   $\frac{1180}{4179}$   $\frac{4780}{4179}$ 

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$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = (I-A) \begin{bmatrix} 50 \\ 40 \\ 35 \end{bmatrix} = \begin{bmatrix} \frac{127900}{1393} \\ \frac{131200}{1393} \\ \frac{85500}{1393} \end{bmatrix}$$

$$= \begin{bmatrix} 91.816 \\ 94.185 \\ 61.378 \end{bmatrix} \Rightarrow Farmers & 91.816 \\ Carpenters & 94.185 \\ Tailors & 61.378 \end{bmatrix}$$

If 
$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$
 then  $A'' = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$ 

① 
$$I - A = \begin{bmatrix} .6 & -.2 \\ -.5 & .5 \end{bmatrix}$$