

# Math 213 - Semester Review - I

Peter A. Perry

University of Kentucky

December 9, 2019



# Reminders

- Homework D5 (16.9, the Divergence Theorem) is due Wednesday night
- There will be a drop-in review session for the final exam on Wednesday, December 18, 3:30-5:30 PM, CB 106.
- Your final exam is Thursday, December 19 at 6:00 PM. Room assignments are the same as for Exams I - III
- On your final exam:
  - The multiple choice questions will be 50% from Units I - III and 50% from unit IV.
  - All free response questions will be from unit IV. Since these questions typically involve integrals, they will also test material from unit III



# Unit IV: Vector Calculus

Fundamental Theorem for Line Integrals

Green's Theorem

Curl and Divergence

Parametric Surfaces and their Areas

Surface Integrals

Stokes' Theorem, I

Stokes' Theorem, II

The Divergence Theorem

Review, I

Review, II

Review, III



# Goals of the Day

Calculus is about functions, derivatives, integrals, and “fundamental theorems” that relate them. Today we will review all of the

- New functions
- New derivatives
- New integrals
- New theorems

that we've learned about in this course.



# New Functions

- **Vector functions**  $\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle$  for space curves, such as

$$\mathbf{r}(t) = \langle \cos t, \sin t, t \rangle$$

- **Vector functions**  $\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$  for surfaces, such as

$$\mathbf{r}(u, v) = \langle u \cos v, u \sin v, v \rangle$$

- **Functions of several variables**  $f(x, y)$  and  $g(x, y, z)$  such as

$$f(x, y) = x^2 + y^2, \quad g(x, y, z) = e^{xyz}$$

- **Transformations**  $(x(u, v), y(u, v))$  and  $(x(u, v, w), y(u, v, w), z(u, v, w))$  such as

$$x(u, v) = u^2 - v^2, \quad y(u, v) = 2uv$$

- **Vector fields**

$$\mathbf{F}(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$$



# New Derivatives - Vector Functions

- The tangent vector to a space curve:

$$\mathbf{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle$$

$$ds = |\mathbf{r}'(t)| dt, \quad d\mathbf{r} = \mathbf{r}'(t) dt$$

- The tangent vectors to a parameterized surface

$$\mathbf{r}_u(u, v) = \frac{\partial x}{\partial u} \mathbf{i} + \frac{\partial y}{\partial u} \mathbf{j} + \frac{\partial z}{\partial u} \mathbf{k}, \quad \mathbf{r}_v(u, v) = \frac{\partial x}{\partial v} \mathbf{i} + \frac{\partial y}{\partial v} \mathbf{j} + \frac{\partial z}{\partial v} \mathbf{k}$$

and the element of area

$$dS = |\mathbf{r}_u \times \mathbf{r}_v| du dv, \quad d\mathbf{S} = (\mathbf{r}_u \times \mathbf{r}_v) du dv$$



# New Derivatives - Functions of Several Variables

- The gradient of a function of a function of two variables

$$\nabla f(x, y) = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j}$$

(greatest change, directional derivatives, critical points)

- The Hessian of a function of two variables

$$\text{Hess}(f) = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$$

(determine whether critical points are local extrema or saddle points)



# New Derivatives - Transformations

- The Jacobian matrix of a transformation  $(x(u, v), y(u, v))$

$$\begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{pmatrix}$$

(Area change from  $uv$  plane to  $xy$  plane)

- The Jacobian of a transformation  $x(u, v, w), y(u, v, w), z(u, v, w)$

$$\begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{pmatrix}$$

(Volume change from  $uvw$  space to  $xyz$  space)



# New Derivatives - Vector Fields

A *vector field* is a function

$$\mathbf{F}(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$$

so there are *nine* derivatives to choose from:

$$\begin{pmatrix} \frac{\partial P}{\partial x} & \frac{\partial P}{\partial y} & \frac{\partial P}{\partial z} \\ \frac{\partial Q}{\partial x} & \frac{\partial Q}{\partial y} & \frac{\partial Q}{\partial z} \\ \frac{\partial R}{\partial x} & \frac{\partial R}{\partial y} & \frac{\partial R}{\partial z} \end{pmatrix}$$

Experience shows that there are two important ones, a scalar (the divergence) and a vector (the curl).



# The Divergence

$$\mathbf{F}(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$$

$$\begin{pmatrix} \frac{\partial P}{\partial x} & \frac{\partial P}{\partial y} & \frac{\partial P}{\partial z} \\ \frac{\partial Q}{\partial x} & \frac{\partial Q}{\partial y} & \frac{\partial Q}{\partial z} \\ \frac{\partial R}{\partial x} & \frac{\partial R}{\partial y} & \frac{\partial R}{\partial z} \end{pmatrix}$$

$$\operatorname{div} \mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

The divergence is a *scalar* which measures net flux of  $\mathbf{F}$  per unit volume



# The Curl

$$\mathbf{F}(x, y, z) = P(x, y, z)\mathbf{i} + Q(x, y, z)\mathbf{j} + R(x, y, z)\mathbf{k}$$

$$\begin{pmatrix} \frac{\partial P}{\partial x} & \frac{\partial P}{\partial y} & \frac{\partial P}{\partial z} \\ \frac{\partial Q}{\partial x} & \frac{\partial Q}{\partial y} & \frac{\partial Q}{\partial z} \\ \frac{\partial R}{\partial x} & \frac{\partial R}{\partial y} & \frac{\partial R}{\partial z} \end{pmatrix}$$

$$\operatorname{curl} \mathbf{F} = \nabla \times \mathbf{F} = \left( \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) \mathbf{i} + \left( \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) \mathbf{j} + \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \mathbf{k}$$

The curl is a *vector*. The circulation of  $\mathbf{F}$  around the boundary of an oriented area  $d\mathbf{S}$  is  $\operatorname{curl} \mathbf{F} \cdot d\mathbf{S}$



# New Integrals - Double Integrals

If  $f(x, y)$  is a function of two variables defined on a region  $D$  in the  $xy$  plane, the double integral of  $f$  over  $D$  is  $\iint_D f(x, y) dA$ . It can be computed in the following ways:

- If  $D = [a, b] \times [c, d]$

$$\iint_D f(x, y) dA = \int_a^b \int_c^d f(x, y) dy dx$$

- If  $D = \{(x, y) : a \leq x \leq b, g_1(x) \leq y \leq g_2(x)\}$  then

$$\iint_D f(x, y) dA = \int_a^b \int_{g_1(x)}^{g_2(x)} f(x, y) dy dx$$

- If  $D = \{(r, \theta) : \alpha \leq \theta \leq \beta, c \leq r \leq d\}$  then

$$\iint_D f(x, y) dA = \int_\alpha^\beta \int_c^d f(r \cos \theta, r \sin \theta) r dr d\theta$$



# New Integrals - Triple Integrals

If  $f(x, y, z)$  is a function of three variables defined on a region  $E$  of  $xyz$  space, the triple integral of  $f$  over  $E$  is  $\iiint_E f(x, y, z) dV$ . It can be computed in the following ways (among others!):

- If  $E = \{(x, y, z) : a \leq x \leq b, c \leq y \leq d, r \leq z \leq s\}$  then

$$\iiint_E f(x, y, z) dV = \int_a^b \int_c^d \int_r^s f(x, y, z) dz dy dx$$

- If  $E = \{(x, y, z) : (x, y) \in D \text{ and } g_1(x, y) \leq z \leq g_2(x, y)\}$  then

$$\iiint_E f(x, y, z) dV = \iint_D \left( \int_{g_1(x, y)}^{g_2(x, y)} f(x, y, z) dz \right) dA$$

- If  $E = \{(\rho, \theta, \phi) : \alpha \leq \theta \leq \beta, \phi_1 \leq \phi \leq \phi_2, a \leq \rho \leq b\}$  then

$$\begin{aligned} \iiint_E f(x, y, z) dV = \\ \int_\alpha^\beta \int_{\phi_1}^{\phi_2} \int_a^b f(\rho \sin \phi \cos \theta, \rho \sin \phi \sin \theta, \rho \cos \phi) \rho^2 \sin \phi d\rho d\phi d\theta \end{aligned}$$



# New Integrals - Line Integrals

If the space curve  $C$  is parameterized by  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$ ,  $a \leq t \leq b$ , then:

- The line integral of a scalar function  $f(x, y, z)$  over  $C$ , denoted  $\int_C f ds$ , is given by

$$\int_a^b f(x(t), y(t), z(t)) |\mathbf{r}'(t)| dt$$

- The line integral of a vector function  $\mathbf{F}(x, y, z)$  over  $C$ , denoted  $\int_C \mathbf{F} \cdot d\mathbf{r}$ , is given by

$$\int_a^b \mathbf{F}(x(t), y(t), z(t)) \cdot \mathbf{r}'(t) dt$$

- We also have

$$\int_C f(x, y, z) dx = \int_a^b f(x(t), y(t), z(t)) x'(t) dt$$

$$\int_C f(x, y, z) dy = \int_a^b f(x(t), y(t), z(t)) y'(t) dt$$

$$\int_C f(x, y, z) dz = \int_a^b f(x(t), y(t), z(t)) z'(t) dt$$



# New Integrals - Surface Integrals

If  $S$  is a surface parameterized by the vector function

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$$

where  $u, v$  run over a domain  $D$  in the  $uv$  plane:

- The surface integral of a scalar function  $f(x, y, z)$ , denoted  $\iint_S f \, dS$ , is given by

$$\iint_D f(x(u, v), y(u, v), z(u, v)) |\mathbf{r}_u \times \mathbf{r}_v| \, du \, dv$$

- The surface integral of a vector function  $\mathbf{F}(x, y, z)$ , denoted  $\iint_S \mathbf{F} \cdot d\mathbf{S}$ , is given by

$$\iint_D \mathbf{F}(x(u, v), y(u, v), z(u, v)) \cdot (\mathbf{r}_u \times \mathbf{r}_v) \, du \, dv$$

You can remember both of these formulas with the shorthand

$$dS = |\mathbf{r}_u \times \mathbf{r}_v| \, du \, dv$$

$$d\mathbf{S} = (\mathbf{r}_u \times \mathbf{r}_v) \, du \, dv$$



# Lots of “Fundamental Theorems”

In Calculus I you learned two versions of the Fundamental Theorem:

**Fundamental Theorem of Calculus, Part I** Suppose that  $f(x)$  is continuous on  $[a, b]$  and let  $F(x) = \int_a^x f(t) dt$ . Then  $F$  is differentiable on  $(a, b)$  and

$$F'(x) = f(x)$$

**Fundamental Theorem of Calculus, Part II** Suppose that  $F$  is any antiderivative of  $f$ . Then

$$\int_a^b f(x) dx = F(b) - F(a)$$



In this course we've seen *four* theorems which reduce integrals “by one dimension”: the Fundamental Theorem for Line Integrals, Green's Theorem, Stokes' Theorem, and the Divergence Theorem

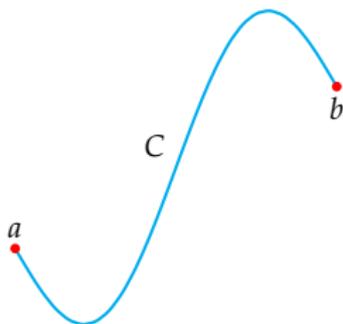


# The Fundamental Theorem for Line Integrals

Recall that a vector field  $\mathbf{F}$  is called *conservative* if there is a scalar function  $\varphi$  so that  $\mathbf{F} = \nabla\varphi$ .

**Theorem** If  $\mathbf{F}$  is a conservative vector field, and  $C$  is a curve parameterized by  $\mathbf{r}(t)$ ,  $a \leq t \leq b$ , then

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \varphi(\mathbf{r}(b)) - \varphi(\mathbf{r}(a))$$



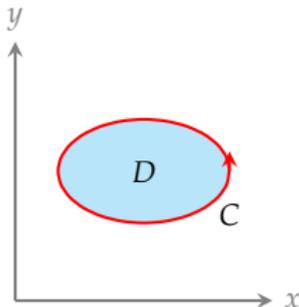


# Green's Theorem

Recall that a domain  $D$  is simply connected if it is connected (any two points of  $D$  can be joined by a curve in  $D$ ) and every simple closed curve in  $D$  surrounds only points of  $D$ .

**Theorem** Suppose that  $D$  is a simply connected domain and its boundary  $C$  is a simple closed curve. Suppose that  $\mathbf{F}(x, y) = P(x, y)\mathbf{i} + Q(x, y)\mathbf{j}$  is a vector field and that  $P$  and  $Q$  have continuous partial derivatives in a neighborhood of  $D$ . Then

$$\iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \oint_C P dx + Q dy$$



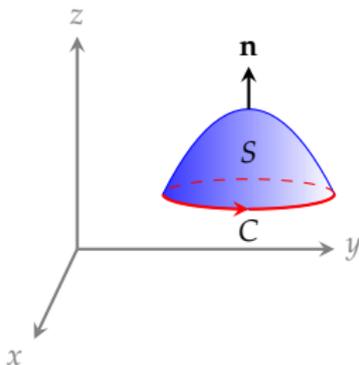


# Stokes' Theorem

Recall that a surface  $S$  is *oriented* if there is a continuous choice of unit normal  $\mathbf{n}$  at every point of  $S$ . The bounding curve  $C$  has positive orientation if its direction is consistent with the direction of  $\mathbf{n}$  via the right-hand rule.

**Theorem** Let  $S$  be an oriented, piecewise smooth surface that is bounded by a simple closed curve  $C$  with positive orientation. Let  $\mathbf{F}$  be a vector field whose components have continuous partial derivatives in an open region on  $\mathbb{R}^3$  that contains  $S$ . Then

$$\iint_S \operatorname{curl} \mathbf{F} \cdot d\mathbf{S} = \int_C \mathbf{F} \cdot d\mathbf{r}$$



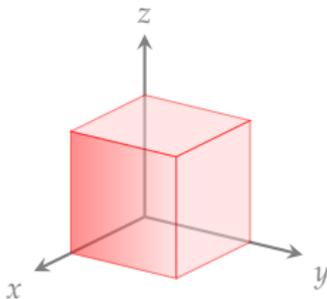


# Divergence Theorem

Recall that  $E$  is a *simple volume* if its boundary separates  $\mathbb{R}^3$  into an “inside” and an “outside.”

**Theorem** Let  $E$  be a simple solid region and let  $S$  be the boundary surface of  $E$ , given with positive (outward) orientation. Let  $\mathbf{F}$  be a vector field whose component functions have continuous partial derivatives on an open region that contains  $E$ . Then

$$\iiint_E \operatorname{div} \mathbf{F} dV = \iint_S \mathbf{F} \cdot d\mathbf{S}$$





# The Unity of (Almost) All Mathematics

| Theorem        | Statement  | Region      | Boundary    |
|----------------|--|-------------|-------------|
| <b>FTC</b>     | $\int_a^b F'(x) dx = F(b) - F(a)$  | $[a, b]$    | $\{a, b\}$  |
| <b>Green</b>   | $\iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \oint_C \mathbf{F} \cdot d\mathbf{r}$ | Domain $D$  | Curve $C$   |
| <b>Stokes</b>  | $\iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} = \oint_C \mathbf{F} \cdot d\mathbf{r}$                                       | Surface $S$ | Curve $C$   |
| <b>Gauss</b>   | $\iiint_E \text{div } \mathbf{F} dV = \iint_S \mathbf{F} \cdot d\mathbf{S}$  | Volume $E$  | Surface $S$ |
| <b>Pattern</b> | $\int_{\text{region}} DF = \int_{\text{boundary}} F$   | Region      | Boundary    |